

# Ao Xi

## List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Balance control of a biped robot on a rotating platform based on efficient reinforcement learning. IEEE/CAA Journal of Automatica Sinica, 2019, 6, 938-951.	13.1	25
2	Walking Control of a Biped Robot on Static and Rotating Platforms Based on Hybrid Reinforcement Learning. IEEE Access, 2020, 8, 148411-148424.	4.2	9
3	Stability Control of a Biped Robot on a Dynamic Platform Based on Hybrid Reinforcement Learning. Sensors, 2020, 20, 4468.	3.8	5