Tong Wang

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49 2,609 20 51 g-index

66 3,104 5.8 6.05 ext. papers ext. citations avg, IF L-index

#	Paper	IF	Citations
49	A Combined Adaptive Neural Network and Nonlinear Model Predictive Control for Multirate Networked Industrial Process Control. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2016 , 27, 416-25	10.3	419
48	Observer-Based Fuzzy Adaptive Event-Triggered Control for Pure-Feedback Nonlinear Systems With Prescribed Performance. <i>IEEE Transactions on Fuzzy Systems</i> , 2019 , 27, 2152-2162	8.3	309
47	Fuzzy Adaptive Actuator Failure Compensation Control of Uncertain Stochastic Nonlinear Systems With Unmodeled Dynamics. <i>IEEE Transactions on Fuzzy Systems</i> , 2014 , 22, 563-574	8.3	267
46	Adaptive Fuzzy Control for Nontriangular Structural Stochastic Switched Nonlinear Systems With Full State Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , 2019 , 27, 1587-1601	8.3	232
45	Adaptive Fuzzy Backstepping Control for A Class of Nonlinear Systems With Sampled and Delayed Measurements. <i>IEEE Transactions on Fuzzy Systems</i> , 2015 , 23, 302-312	8.3	197
44	A Combined Backstepping and Stochastic Small-Gain Approach to Robust Adaptive Fuzzy Output Feedback Control. <i>IEEE Transactions on Fuzzy Systems</i> , 2013 , 21, 314-327	8.3	186
43	Adaptive neural network output feedback control for stochastic nonlinear systems with unknown dead-zone and unmodeled dynamics. <i>IEEE Transactions on Cybernetics</i> , 2014 , 44, 910-21	10.2	145
42	Performance-Based Adaptive Fuzzy Tracking Control for Networked Industrial Processes. <i>IEEE Transactions on Cybernetics</i> , 2016 , 46, 1760-70	10.2	102
41	Adaptive Neural Control of Stochastic Nonlinear Time-Delay Systems With Multiple Constraints. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> 2017 , 47, 1875-1883	7.3	93
40	Network-Based Fuzzy Control for Nonlinear Industrial Processes With Predictive Compensation Strategy. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> 2017 , 47, 2137-2147	7.3	88
39	Distributed Fuzzy \$H_{infty}\$ Filtering for Nonlinear Multirate Networked Double-Layer Industrial Processes. <i>IEEE Transactions on Industrial Electronics</i> , 2017 , 64, 5203-5211	8.9	68
38	Filtering for Switched T-S Fuzzy Systems With Persistent Dwell Time. <i>IEEE Transactions on Cybernetics</i> , 2019 , 49, 1923-1931	10.2	61
37	Adaptive Fuzzy Tracking Control for a Class of Strict-Feedback Nonlinear Systems With Time-Varying Input Delay and Full State Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , 2020 , 28, 3432	-3 4 41	51
36	A Combined Fault-Tolerant and Predictive Control for Network-Based Industrial Processes. <i>IEEE Transactions on Industrial Electronics</i> , 2016 , 1-1	8.9	50
35	Data-Based Optimal Control for Networked Double-Layer Industrial Processes. <i>IEEE Transactions on Industrial Electronics</i> , 2017 , 64, 4179-4186	8.9	50
34	Improved Stability Criteria for Discrete-Time Switched TB Fuzzy Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 51, 712-720	7.3	30
33	Barrier Lyapunov Function-Based Adaptive Fault-Tolerant Control for a Class of Strict-Feedback Stochastic Nonlinear Systems. <i>IEEE Transactions on Cybernetics</i> , 2021 , 51, 938-946	10.2	24

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32	Robust adaptive fuzzy output feedback control for stochastic nonlinear systems with unknown control direction. <i>Neurocomputing</i> , 2013 , 106, 31-41	5.4	23	
31	Adaptive Fuzzy Decentralized Tracking Control for Large-Scale Interconnected Nonlinear Networked Control Systems. <i>IEEE Transactions on Fuzzy Systems</i> , 2020 , 1-1	8.3	20	
30	Event-Triggered Adaptive Fuzzy Tracking Control for Pure-Feedback Stochastic Nonlinear Systems With Multiple Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , 2021 , 29, 1496-1506	8.3	20	
29	Adaptive neural network output feedback control of stochastic nonlinear systems with dynamical uncertainties. <i>Neural Computing and Applications</i> , 2013 , 23, 1481-1494	4.8	19	
28	Robust adaptive fuzzy control for a class of stochastic nonlinear systems with dynamical uncertainties. <i>Journal of the Franklin Institute</i> , 2012 , 349, 3121-3141	4	18	
27	Robust adaptive decentralized fuzzy control for stochastic large-scale nonlinear systems with dynamical uncertainties. <i>Neurocomputing</i> , 2012 , 97, 33-43	5.4	15	
26	Dynamic event-triggered actuator fault estimation and accommodation for dynamical systems. <i>Information Sciences</i> , 2020 , 525, 119-133	7.7	13	
25	Adaptive neural fault-tolerant control for a class of strict-feedback nonlinear systems with actuator and sensor faults. <i>Neurocomputing</i> , 2020 , 380, 87-94	5.4	12	
24	Disturbance Observer-Based Adaptive Fuzzy Control for Strict-Feedback Nonlinear Systems with Finite-Time Prescribed Performance. <i>IEEE Transactions on Fuzzy Systems</i> , 2021 , 1-1	8.3	12	
23	Adaptive tracking control for quantized nonlinear systems via backstepping design technique. <i>Journal of the Franklin Institute</i> , 2018 , 355, 2631-2644	4	11	
22	Event-Triggered Adaptive Fuzzy Fault-Tolerant Control for Stochastic Nonlinear Systems via Command Filtering. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 1-11	7.3	10	
21	Simultaneous fault detection and control for uncertain discrete-time stochastic systems with limited communication. <i>Journal of the Franklin Institute</i> , 2017 , 354, 7794-7811	4	9	
20	Adaptive Fuzzy Finite-Time Tracking Control of Stochastic High-Order Nonlinear Systems With A Class of Prescribed Performance. <i>IEEE Transactions on Fuzzy Systems</i> , 2020 , 1-1	8.3	9	
19	Fault detection of nonlinear stochastic systems via a dynamic event-triggered strategy. <i>Signal Processing</i> , 2020 , 167, 107283	4.4	9	
18	Adaptive Fuzzy Decentralized Control for Nonstrict Feedback Nonlinear Systems With Unmodeled Dynamics. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> 2020 , 1-12	7.3	5	
17	H_/HIFault detection filter design for discrete-time stochastic systems with limited communication. <i>Transactions of the Institute of Measurement and Control</i> , 2019 , 41, 3808-3817	1.8	4	
16	Barrier Lyapunov-based Adaptive Fuzzy Finite-Time Tracking of Pure-feedback Nonlinear Systems With Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , 2021 , 1-1	8.3	4	
15	Fuzzy Adaptive Decentralized Control for Nonstrict-Feedback Large-Scale Switched Fractional-Order Nonlinear Systems. <i>IEEE Transactions on Cybernetics</i> , 2021 , PP,	10.2	4	

14	Event-triggered fault detection filter design for uncertain stochastic systems with package dropouts. <i>Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering</i> , 2019 , 233, 1351-1360	1	3
13	Fault-tolerant Control Based on Fixed-time Observer for a 3-DOF Helicopter System. <i>International Journal of Control, Automation and Systems</i> , 2020 , 18, 2993-3000	2.9	3
12	Gradient Descent-Based Adaptive Learning Control for Autonomous Underwater Vehicles With Unknown Uncertainties. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , 32, 5266-527	'3 ^{10.3}	3
11	Adaptive Fuzzy Risk-Sensitive Control for Stochastic Strict-Feedback Nonlinear Systems with Unknown Uncertainties. <i>IEEE Transactions on Fuzzy Systems</i> , 2020 , 1-1	8.3	2
10	A simplified adaptive tracking control for nonlinear pure-feedback systems with input delay and full-state constraints. <i>International Journal of Adaptive Control and Signal Processing</i> ,	2.8	2
9	Multirate output feedback control for complex industrial processes in double-layer network environment with RBF performance index 2014 ,		1
8	Robustness of It[stochastic nonlinear networked control systems 2017,		1
7	Setpoints compensation for nonlinear industrial processes with disturbances based on fuzzy logic control 2014 ,		1
7			1
	Control 2014 , Optimal Tracking Control For A Two-link Robotic Manipulator Via Adaptive Dynamic Programming	2.8	
6	Control 2014, Optimal Tracking Control For A Two-link Robotic Manipulator Via Adaptive Dynamic Programming 2020, Decentralized optimal tracking control for large-scale nonlinear systems with tracking error	2.8	1
5	Control 2014, Optimal Tracking Control For A Two-link Robotic Manipulator Via Adaptive Dynamic Programming 2020, Decentralized optimal tracking control for large-scale nonlinear systems with tracking error constraints. International Journal of Adaptive Control and Signal Processing, 2021, 35, 1388-1403 PDE-Based Leader-Following Consensus of Multi-Agent Systems with Input Delay under Spatial		1
6 5 4	Optimal Tracking Control For A Two-link Robotic Manipulator Via Adaptive Dynamic Programming 2020, Decentralized optimal tracking control for large-scale nonlinear systems with tracking error constraints. International Journal of Adaptive Control and Signal Processing, 2021, 35, 1388-1403 PDE-Based Leader-Following Consensus of Multi-Agent Systems with Input Delay under Spatial Boundary Communication. IFAC-PapersOnLine, 2021, 54, 181-185 Neural-network-based fault-tolerant control for nonlinear systems subjected to faults and	0.7	1 1 0