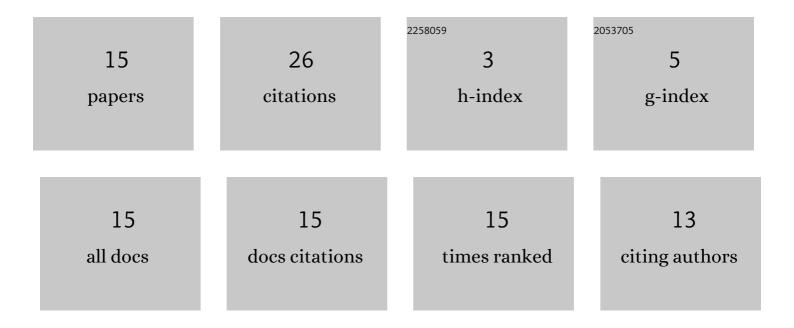
RÃ³bert RÃ;kay

List of Publications by Year in descending order

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PÃ3REDT PÃ:KAV

#	Article	IF	CITATIONS
1	A Non-Anthropomorphic Bipedal Walking Robot with a Vertically Stabilized Base. Applied Sciences (Switzerland), 2022, 12, 4108.	2.5	4
2	Testing of Selected Accuracy Parameters for the Single Axis Positioner at the Automated Workplace. Measurement Science Review, 2021, 21, 47-54.	1.0	0
3	LONG RANGE IOT COMMUNICATION. MM Science Journal, 2021, 2021, 4781-4785.	0.4	3
4	PROPOSAL OF AUTOMATED SYSTEM FOR PRESENTATION PURPOSES. Technical Sciences and Technologies, 2021, , 196-205.	0.0	0
5	MONITORING OF ENVIRONMENT PARAMETERS BASED ON WIRELESS SENSOR NETWORK. Technical Sciences and Technologies, 2021, , 193-201.	0.0	0
6	Comparing of Transfer Process Data in PLC and MCU Based on IoT. Lecture Notes in Electrical Engineering, 2020, , 390-399.	0.4	3
7	CONCEPT FOR PHYSIOLOGICAL FUNCTION MONITORING WITH WEARABLE SENSORS. Technical Sciences and Technologies, 2020, , 190-197.	0.0	0
8	TESTING PROPERTIES OF SMART CONDITON MONITORING SYSTEM. Technical Sciences and Technologies, 2020, , 266-273.	0.0	0
9	ON LOCAL WIRELESS REMOTE CONTROL. MM Science Journal, 2020, 2020, 4093-4096.	0.4	0
10	COMPARISON OF COMMUNICATION PROTOCOLS FOR SMART DEVICES. Technical Sciences and Technologies, 2019, , 146-154.	0.0	2
11	Seleceted Wireless Communication Protocols and their Properties for Use in IoT Systems. Research Papers Faculty of Materials Science and Technology Slovak University of Technology in Trnava, 2019, 27, 26-32.	0.4	4
12	Creating Industrial Network with PROFINET Communication for Education Purposes. Acta Mechanica Slovaca, 2017, 21, 66-72.	0.1	2
13	An automated procedure for identification of a person using gait analysis. International Journal of Advanced Robotic Systems, 2016, 13, 172988141666762.	2.1	4
14	Robotic Arm with 7 DoF for Upper Limb. International Journal of Engineering Research in Africa, 2015, 18, 199-206.	0.7	0
15	Kinematic Analysis of Crank Rocker Mechanism Using MSC Adams/View. Applied Mechanics and Materials, 0, 611, 90-97.	0.2	4