# **Ding Wang**

#### List of Publications by Citations

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167<br/>papers5,819<br/>citations45<br/>h-index73<br/>g-index197<br/>ext. papers7,594<br/>ext. citations5.2<br/>avg, IF6.77<br/>L-index

#	Paper	IF	Citations
167	Optimal control of unknown nonaffine nonlinear discrete-time systems based on adaptive dynamic programming. <i>Automatica</i> , <b>2012</b> , 48, 1825-1832	5.7	265
166	Decentralized stabilization for a class of continuous-time nonlinear interconnected systems using online learning optimal control approach. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2014</b> , 25, 418-28	10.3	199
165	Neural-network-based online HJB solution for optimal robust guaranteed cost control of continuous-time uncertain nonlinear systems. <i>IEEE Transactions on Cybernetics</i> , <b>2014</b> , 44, 2834-47	10.2	182
164	Reinforcement-Learning-Based Robust Controller Design for Continuous-Time Uncertain Nonlinear Systems Subject to Input Constraints. <i>IEEE Transactions on Cybernetics</i> , <b>2015</b> , 45, 1372-85	10.2	177
163	Adaptive Critic Nonlinear Robust Control: A Survey. <i>IEEE Transactions on Cybernetics</i> , <b>2017</b> , 47, 3429-34	45 <b>1</b> 0.2	166
162	Model-Free Optimal Tracking Control via Critic-Only Q-Learning. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2016</b> , 27, 2134-44	10.3	165
161	Finite-horizon neuro-optimal tracking control for a class of discrete-time nonlinear systems using adaptive dynamic programming approach. <i>Neurocomputing</i> , <b>2012</b> , 78, 14-22	5.4	157
160	Adaptive Neural State-Feedback Tracking Control of Stochastic Nonlinear Switched Systems: An Average Dwell-Time Method. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2019</b> , 30, 10	76 <sup>-10</sup> 8	7 <sup>145</sup>
159	Adaptive Dynamic Programming for Control. Communications and Control Engineering, 2013,	0.6	145
158	Data-Based Adaptive Critic Designs for Nonlinear Robust Optimal Control With Uncertain Dynamics. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2016</b> , 46, 1544-1555	7.3	142
157	. IEEE Transactions on Systems, Man, and Cybernetics: Systems, <b>2014</b> , 44, 1015-1027	7.3	136
156	Policy Iteration Algorithm for Online Design of Robust Control for a Class of Continuous-Time Nonlinear Systems. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2014</b> , 11, 627-632	4.9	133
155	Experience Replay for Optimal Control of Nonzero-Sum Game Systems With Unknown Dynamics. <i>IEEE Transactions on Cybernetics</i> , <b>2016</b> , 46, 854-65	10.2	126
154	Neural-network-based zero-sum game for discrete-time nonlinear systems via iterative adaptive dynamic programming algorithm. <i>Neurocomputing</i> , <b>2013</b> , 110, 92-100	5.4	121
153	Reinforcement learning for adaptive optimal control of unknown continuous-time nonlinear systems with input constraints. <i>International Journal of Control</i> , <b>2014</b> , 87, 553-566	1.5	115
152	Adaptive Dynamic Programming with Applications in Optimal Control. <i>Advances in Industrial Control</i> , <b>2017</b> ,	0.3	111
151	Neural-Network-Based Optimal Control for a Class of Unknown Discrete-Time Nonlinear Systems Using Globalized Dual Heuristic Programming. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2012</b> , 9, 628-634	4.9	104

150	Integral Reinforcement Learning for Linear Continuous-Time Zero-Sum Games With Completely Unknown Dynamics. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2014</b> , 11, 706-714	4.9	99
149	An iterative adaptive dynamic programming algorithm for optimal control of unknown discrete-time nonlinear systems with constrained inputs. <i>Information Sciences</i> , <b>2013</b> , 220, 331-342	7.7	99
148	Event-Based Robust Control for Uncertain Nonlinear Systems Using Adaptive Dynamic Programming. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2018</b> , 29, 37-50	10.3	97
147	An Approximate Optimal Control Approach for Robust Stabilization of a Class of Discrete-Time Nonlinear Systems With Uncertainties. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2016</b> , 46, 713-717	7.3	95
146	Novel iterative neural dynamic programming for data-based approximate optimal control design. <i>Automatica</i> , <b>2017</b> , 81, 240-252	5.7	95
145	Adaptive Neural Output-Feedback Control for a Class of Nonlower Triangular Nonlinear Systems With Unmodeled Dynamics. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2018</b> , 29, 3658-	<sup>10</sup> 3	95
144	Neural-Network-Based Distributed Adaptive Robust Control for a Class of Nonlinear Multiagent Systems With Time Delays and External Noises. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2016</b> , 46, 750-758	7.3	94
143	Neural-network-based robust optimal control design for a class of uncertain nonlinear systems via adaptive dynamic programming. <i>Information Sciences</i> , <b>2014</b> , 282, 167-179	7.7	94
142	Neural-network-observer-based optimal control for unknown nonlinear systems using adaptive dynamic programming. <i>International Journal of Control</i> , <b>2013</b> , 86, 1554-1566	1.5	90
141	Policy Gradient Adaptive Dynamic Programming for Data-Based Optimal Control. <i>IEEE Transactions on Cybernetics</i> , <b>2017</b> , 47, 3341-3354	10.2	84
140	Self-Learning Optimal Regulation for Discrete-Time Nonlinear Systems Under Event-Driven Formulation. <i>IEEE Transactions on Automatic Control</i> , <b>2020</b> , 65, 1272-1279	5.9	80
139	A Novel Neural-Network-Based Adaptive Control Scheme for Output-Constrained Stochastic Switched Nonlinear Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2019</b> , 49, 418	-432	77
138	Event-Driven Adaptive Robust Control of Nonlinear Systems With Uncertainties Through NDP Strategy. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2017</b> , 47, 1358-1370	7.3	75
137	Full-range adaptive cruise control based on supervised adaptive dynamic programming. <i>Neurocomputing</i> , <b>2014</b> , 125, 57-67	5.4	70
136	Guaranteed cost neural tracking control for a class of uncertain nonlinear systems using adaptive dynamic programming. <i>Neurocomputing</i> , <b>2016</b> , 198, 80-90	5.4	69
135	Intelligent Optimal Control With Critic Learning for a Nonlinear Overhead Crane System. <i>IEEE Transactions on Industrial Informatics</i> , <b>2018</b> , 14, 2932-2940	11.9	65
134	Decentralized Control for Large-Scale Nonlinear Systems With Unknown Mismatched Interconnections via Policy Iteration. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2018</b> , 48, 1725-1735	7.3	59
133	On Mixed Data and Event Driven Design for Adaptive-Critic-Based Nonlinear \$H_{infty}\$ Control.  **IEEE Transactions on Neural Networks and Learning Systems, 2018, 29, 993-1005	10.3	56

132	Intelligent Critic Control With Disturbance Attenuation for Affine Dynamics Including an Application to a Microgrid System. <i>IEEE Transactions on Industrial Electronics</i> , <b>2017</b> , 64, 4935-4944	8.9	53
131	Adaptive Neural Output-Feedback Controller Design of Switched Nonlower Triangular Nonlinear Systems With Time Delays. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2020</b> , 31, 4084-	4 <del>0</del> 93 <sup>3</sup>	53
130	Neuro-optimal control for a class of unknown nonlinear dynamic systems using SN-DHP technique. <i>Neurocomputing</i> , <b>2013</b> , 121, 218-225	5.4	52
129	Event-Driven Nonlinear Discounted Optimal Regulation Involving a Power System Application. <i>IEEE Transactions on Industrial Electronics</i> , <b>2017</b> , 64, 8177-8186	8.9	51
128	Model-Free Optimal Control for Affine Nonlinear Systems With Convergence Analysis. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2015</b> , 12, 1461-1468	4.9	51
127	Model-Free Adaptive Control for Unknown Nonlinear Zero-Sum Differential Game. <i>IEEE Transactions on Cybernetics</i> , <b>2018</b> , 48, 1633-1646	10.2	50
126	Data-driven controller design for general MIMO nonlinear systems via virtual reference feedback tuning and neural networks. <i>Neurocomputing</i> , <b>2016</b> , 171, 815-825	5.4	50
125	Learning and Guaranteed Cost Control With Event-Based Adaptive Critic Implementation. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2018</b> , 29, 6004-6014	10.3	49
124	Data-Driven Iterative Adaptive Critic Control Toward an Urban Wastewater Treatment Plant. <i>IEEE Transactions on Industrial Electronics</i> , <b>2021</b> , 68, 7362-7369	8.9	47
123	Improving the Critic Learning for Event-Based Nonlinear \$H_{infty}\$ Control Design. <i>IEEE Transactions on Cybernetics</i> , <b>2017</b> , 47, 3417-3428	10.2	45
122	Error bounds of adaptive dynamic programming algorithms for solving undiscounted optimal control problems. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2015</b> , 26, 1323-34	10.3	43
121	Adaptive-Critic-Based Robust Trajectory Tracking of Uncertain Dynamics and Its Application to a SpringMassDamper System. <i>IEEE Transactions on Industrial Electronics</i> , <b>2018</b> , 65, 654-663	8.9	43
120	Discrete-time online learning control for a class of unknown nonaffine nonlinear systems using reinforcement learning. <i>Neural Networks</i> , <b>2014</b> , 55, 30-41	9.1	42
119	Neural Network Learning and Robust Stabilization of Nonlinear Systems With Dynamic Uncertainties. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2018</b> , 29, 1342-1351	10.3	41
118	Decentralized guaranteed cost control of interconnected systems with uncertainties: A learning-based optimal control strategy. <i>Neurocomputing</i> , <b>2016</b> , 214, 297-306	5.4	39
117	Event-based input-constrained nonlinear HIstate feedback with adaptive critic and neural implementation. <i>Neurocomputing</i> , <b>2016</b> , 214, 848-856	5.4	38
116	Centralized and decentralized event-triggered control for group consensus with fixed topology in continuous time. <i>Neurocomputing</i> , <b>2015</b> , 161, 267-276	5.4	37
115	Data-Driven Finite-Horizon Approximate Optimal Control for Discrete-Time Nonlinear Systems Using Iterative HDP Approach. <i>IEEE Transactions on Cybernetics</i> , <b>2018</b> , 48, 2948-2961	10.2	36

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114	Data-based robust optimal control of continuous-time affine nonlinear systems with matched uncertainties. <i>Information Sciences</i> , <b>2016</b> , 366, 121-133	7.7	36	
113	Neural-network-based decentralized control of continuous-time nonlinear interconnected systems with unknown dynamics. <i>Neurocomputing</i> , <b>2015</b> , 165, 90-98	5.4	35	
112	Event-Triggered Adaptive Critic Control Design for Discrete-Time Constrained Nonlinear Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2020</b> , 50, 3158-3168	7.3	35	
111	Control-Limited Adaptive Dynamic Programming for Multi-Battery Energy Storage Systems. <i>IEEE Transactions on Smart Grid</i> , <b>2019</b> , 10, 4235-4244	10.7	32	
110	Distributed control algorithm for bipartite consensus of the nonlinear time-delayed multi-agent systems with neural networks. <i>Neurocomputing</i> , <b>2016</b> , 174, 928-936	5.4	30	
109	Neural robust stabilization via event-triggering mechanism and adaptive learning technique. <i>Neural Networks</i> , <b>2018</b> , 102, 27-35	9.1	29	
108	Neural network robust tracking control with adaptive critic framework for uncertain nonlinear systems. <i>Neural Networks</i> , <b>2018</b> , 97, 11-18	9.1	28	
107	Dual iterative adaptive dynamic programming for a class of discrete-time nonlinear systems with time-delays. <i>Neural Computing and Applications</i> , <b>2013</b> , 23, 1851-1863	4.8	26	
106	Data-based Self-learning Optimal Control: Research Progress and Prospects. <i>Zidonghua Xuebao/Acta Automatica Sinica</i> , <b>2013</b> , 39, 1858		26	
105	Neural-network-based adaptive guaranteed cost control of nonlinear dynamical systems with matched uncertainties. <i>Neurocomputing</i> , <b>2017</b> , 245, 46-54	5.4	25	
104	A neural-network-based iterative GDHP approach for solving a class of nonlinear optimal control problems with control constraints. <i>Neural Computing and Applications</i> , <b>2013</b> , 22, 219-227	4.8	25	
103	Robust adaptive critic control design with network-based event-triggered formulation. <i>Nonlinear Dynamics</i> , <b>2017</b> , 90, 2023-2035	5	23	
102	Feature selection and feature learning for high-dimensional batch reinforcement learning: A survey. <i>International Journal of Automation and Computing</i> , <b>2015</b> , 12, 229-242	3.5	22	
101	Event-Based Constrained Robust Control of Affine Systems Incorporating an Adaptive Critic Mechanism. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2017</b> , 47, 1602-1612	7.3	21	
100	Adaptive near-optimal controllers for non-linear decentralised feedback stabilisation problems. <i>IET Control Theory and Applications</i> , <b>2017</b> , 11, 799-806	2.5	21	
99	Approximate neural optimal control with reinforcement learning for a torsional pendulum device. <i>Neural Networks</i> , <b>2019</b> , 117, 1-7	9.1	21	
98	A neural-network-based online optimal control approach for nonlinear robust decentralized stabilization. <i>Soft Computing</i> , <b>2016</b> , 20, 707-716	3.5	20	
97	Adaptive tracking control for a class of continuous-time uncertain nonlinear systems using the approximate solution of HJB equation. <i>Neurocomputing</i> , <b>2017</b> , 260, 432-442	5.4	18	

96	An Approximate Neuro-Optimal Solution of Discounted Guaranteed Cost Control Design. <i>IEEE Transactions on Cybernetics</i> , <b>2020</b> ,	10.2	18
95	Bipartite output consensus in networked multi-agent systems of high-order power integrators with signed digraph and input noises. <i>International Journal of Systems Science</i> , <b>2016</b> , 47, 3116-3131	2.3	17
94	Bounded robust control design for uncertain nonlinear systems using single-network adaptive dynamic programming. <i>Neurocomputing</i> , <b>2017</b> , 266, 128-140	5.4	16
93	The intelligent critic framework for advanced optimal control. <i>Artificial Intelligence Review</i> , <b>2022</b> , 55, 1-22	9.7	16
92	Data-Based Optimal Control for Weakly Coupled Nonlinear Systems Using Policy Iteration. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2018</b> , 48, 511-521	7.3	15
91	Manifold Regularized Reinforcement Learning. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2018</b> , 29, 932-943	10.3	15
90	Decentralized adaptive optimal stabilization of nonlinear systems with matched interconnections. <i>Soft Computing</i> , <b>2018</b> , 22, 2705-2715	3.5	15
89	Intelligent Critic Control With Robustness Guarantee of Disturbed Nonlinear Plants. <i>IEEE Transactions on Cybernetics</i> , <b>2020</b> , 50, 2740-2748	10.2	15
88	Model-Free HIDptimal Tracking Control of Constrained Nonlinear Systems via an Iterative Adaptive Learning Algorithm. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2020</b> , 50, 40	97-410	)8 <sup>14</sup>
87	Error Bound Analysis of \$Q\$ -Function for Discounted Optimal Control Problems With Policy Iteration. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2017</b> , 47, 1207-1216	7.3	13
86	Neural optimal tracking control of constrained nonaffine systems with a wastewater treatment application. <i>Neural Networks</i> , <b>2021</b> , 143, 121-132	9.1	13
85	Event-triggered constrained control with DHP implementation for nonaffine discrete-time systems. <i>Information Sciences</i> , <b>2020</b> , 519, 110-123	7.7	12
84	Robust Policy Learning Control of Nonlinear Plants With Case Studies for a Power System Application. <i>IEEE Transactions on Industrial Informatics</i> , <b>2020</b> , 16, 1733-1741	11.9	12
83	Developing nonlinear adaptive optimal regulators through an improved neural learning mechanism. <i>Science China Information Sciences</i> , <b>2017</b> , 60, 1	3.4	11
82	A novel neural optimal control framework with nonlinear dynamics: Closed-loop stability and simulation verification. <i>Neurocomputing</i> , <b>2017</b> , 266, 353-360	5.4	11
81	Direct adaptive control for a class of discrete-time unknown nonaffine nonlinear systems using neural networks. <i>International Journal of Robust and Nonlinear Control</i> , <b>2015</b> , 25, 1844-1861	3.6	11
8o	Generalized value iteration for discounted optimal control with stability analysis. <i>Systems and Control Letters</i> , <b>2021</b> , 147, 104847	2.4	11
79	Neural critic learning toward robust dynamic stabilization. <i>International Journal of Robust and Nonlinear Control</i> , <b>2020</b> , 30, 2020-2032	3.6	10

# (2016-2021)

78	Intelligent optimal tracking with asymmetric constraints of a nonlinear wastewater treatment system. <i>International Journal of Robust and Nonlinear Control</i> , <b>2021</b> , 31, 6773-6787	3.6	10
77	A novel decomposition-based multiobjective evolutionary algorithm using improved multiple adaptive dynamic selection strategies. <i>Information Sciences</i> , <b>2021</b> , 556, 472-494	7.7	10
76	Optimal Control of Unknown Nonlinear Discrete-Time Systems Using the Iterative Globalized Dual Heuristic Programming Algorithm <b>2013</b> , 52-77		9
75	Terrain recognition improves the performance of neural-machine interface for locomotion mode recognition <b>2013</b> ,		9
74	Adaptive Decentralized Asymptotic Tracking Control for Large-Scale Nonlinear Systems With Unknown Strong Interconnections. <i>IEEE/CAA Journal of Automatica Sinica</i> , <b>2021</b> , 1-14	7	9
73	Advanced policy learning near-optimal regulation. <i>IEEE/CAA Journal of Automatica Sinica</i> , <b>2019</b> , 6, 743-7	' <del>4</del> 9	8
72	Data-based composite control design with critic intelligence for a wastewater treatment platform. <i>Artificial Intelligence Review</i> , <b>2020</b> , 53, 3773-3785	9.7	7
71	Improved value iteration for neural-network-based stochastic optimal control design. <i>Neural Networks</i> , <b>2020</b> , 124, 280-295	9.1	7
70	Data-Based Nonaffine Optimal Tracking Control Using Iterative DHP Approach. <i>IFAC-PapersOnLine</i> , <b>2020</b> , 53, 4246-4251	0.7	6
69	Asymptotically stable critic designs for approximate optimal stabilization of nonlinear systems subject to mismatched external disturbances. <i>Neurocomputing</i> , <b>2020</b> , 396, 201-208	5.4	6
68	Self-Learning Robust Control Synthesis and Trajectory Tracking of Uncertain Dynamics. <i>IEEE Transactions on Cybernetics</i> , <b>2020</b> ,	10.2	6
67	Offline and Online Adaptive Critic Control Designs With Stability Guarantee Through Value Iteration. <i>IEEE Transactions on Cybernetics</i> , <b>2021</b> , PP,	10.2	6
66	Adaptive dynamic programming for infinite horizon optimal robust guaranteed cost control of a class of uncertain nonlinear systems <b>2015</b> ,		5
65	Connectivity preserved nonlinear time-delayed multiagent systems using neural networks and event-based mechanism. <i>Neural Computing and Applications</i> , <b>2018</b> , 29, 361-369	4.8	4
64	Output-based high-order bipartite consensus under directed antagonistic networks 2014,		4
63	Approximate optimal solution of the DTHJB equation for a class of nonlinear affine systems with unknown dead-zone constraints. <i>Soft Computing</i> , <b>2014</b> , 18, 349-357	3.5	4
62	Neuro-Optimal Trajectory Tracking With Value Iteration of Discrete-Time Nonlinear Dynamics. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2021</b> , PP,	10.3	4
61	Adaptive-critic-based event-driven nonlinear robust state feedback <b>2016</b> ,		4

60	Adaptive-critic-based hybrid intelligent optimal tracking for a class of nonlinear discrete-time systems. <i>Engineering Applications of Artificial Intelligence</i> , <b>2021</b> , 105, 104443	7.2	4
59	Neural-network-based discounted optimal control via an integrated value iteration with accuracy guarantee. <i>Neural Networks</i> , <b>2021</b> , 144, 176-186	9.1	4
58	Continuous-time group consensus using distributed event-triggered control 2015,		3
57	Finite-horizon neural optimal tracking control for a class of nonlinear systems with unknown dynamics <b>2012</b> ,		3
56	A Novel Value Iteration Scheme With Adjustable Convergence Rate <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2022</b> , PP,	10.3	3
55	Adaptation-Oriented Near-Optimal Control and Robust Synthesis of an Overhead Crane System. <i>Lecture Notes in Computer Science</i> , <b>2017</b> , 42-50	0.9	3
54	Neuro-Optimal Control for Discrete Stochastic Processes via a Novel Policy Iteration Algorithm. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2020</b> , 50, 3972-3985	7.3	3
53	Discounted near-optimal regulation of constrained nonlinear systems via generalized value iteration. International Journal of Robust and Nonlinear Control,	3.6	3
52	Time-/Event-Triggered Adaptive Neural Asymptotic Tracking Control for Nonlinear Systems With Full-State Constraints and Application to a Single-Link Robot. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2021</b> , PP,	10.3	3
51	Overview of Adaptive Dynamic Programming. Advances in Industrial Control, 2017, 1-33	0.3	2
50	Learning Algorithms for Differential Games of Continuous-Time Systems. <i>Advances in Industrial Control</i> , <b>2017</b> , 417-480	0.3	2
49	Value Iteration ADP for Discrete-Time Nonlinear Systems. <i>Advances in Industrial Control</i> , <b>2017</b> , 37-90	0.3	2
48	Approximate policy iteration with unsupervised feature learning based on manifold regularization <b>2015</b> ,		2
47	Distributed algorithm for dissensus of a class of networked multiagent systems using output information. <i>Soft Computing</i> , <b>2018</b> , 22, 273-282	3.5	2
46	Data-driven iterative adaptive dynamic programming algorithm for approximate optimal control of unknown nonlinear systems <b>2014</b> ,		2
45	Long short-term memory based on a reward/punishment strategy for recurrent neural networks <b>2017</b> ,		2
44	Constrained online optimal control for continuous-time nonlinear systems using neuro-dynamic programming <b>2014</b> ,		2
43	System Stability of Learning-Based Linear Optimal Control With General Discounted Value Iteration <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2022</b> , PP,	10.3	2

### (2021-2021)

42	Adaptive Critic for Event-Triggered Unknown Nonlinear Optimal Tracking Design With Wastewater Treatment Applications <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2021</b> , PP,	10.3	2	
41	Distributed Control for Nonlinear Time-Delayed Multi-Agent Systems with Connectivity Preservation Using Neural Networks. <i>Lecture Notes in Computer Science</i> , <b>2015</b> , 34-42	0.9	2	
40	Adaptive critic optimization to decentralized event-triggered control of continuous-time nonlinear interconnected systems. <i>Optimal Control Applications and Methods</i> ,	1.7	2	
39	Adaptive Optimal Control for Unknown Constrained Nonlinear Systems With a Novel Quasi-Model Network. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2021</b> , PP,	10.3	2	
38	Policy Gradient Adaptive Critic Design with Dynamic Prioritized Experience Replay for Wastewater Treatment Process Control. <i>IEEE Transactions on Industrial Informatics</i> , <b>2021</b> , 1-1	11.9	2	
37	Optimal Control of Unknown Continuous-Time Nonaffine Nonlinear Systems. <i>Advances in Industrial Control</i> , <b>2017</b> , 309-344	0.3	1	
36	Connectivity preservation of second-order nonlinear multiagent systems with hybrid event-driven and time-driven control. <i>International Journal of Systems Science</i> , <b>2018</b> , 49, 1368-1382	2.3	1	
35	Distributed control of second-order nonlinear time-delayed multiagent systems with disturbance using neural networks <b>2016</b> ,		1	
34	Neural network adaptive critic control with disturbance rejection 2017,		1	
33	Adaptive critic designs for solving event-based Hitontrol problems 2017,		1	
32	A novel self-learning optimal control approach for decentralized guaranteed cost control of a class of complex nonlinear systems <b>2015</b> ,		1	
31	Decentralized control for a class of nonlinear interconnected systems using integral policy iteration <b>2014</b> ,		1	
30	A data-based neural policy learning strategy towards robust tracking control design for uncertain dynamic systems. <i>International Journal of Systems Science</i> ,1-14	2.3	1	
29	Dynamic Transfer Reference Point Oriented MOEA/D Involving Local Objective-Space Knowledge. <i>IEEE Transactions on Evolutionary Computation</i> , <b>2022</b> , 1-1	15.6	1	
28	Dynamic multi-objective intelligent optimal control toward wastewater treatment processes. <i>Science China Technological Sciences</i> , <b>2022</b> , 65, 569	3.5	1	
27	Mixed Driven Iterative Adaptive Critic Control Design Towards Nonaffine Discrete-Time Plants. <i>IFAC-PapersOnLine</i> , <b>2020</b> , 53, 3803-3808	0.7	1	
26	Event-Triggered Adaptive Dynamic Programming for Uncertain Nonlinear Systems. <i>Communications in Computer and Information Science</i> , <b>2017</b> , 13-26	0.3	1	
25	Adaptive neural tracking control of high-order nonlinear systems with quantized input. <i>Neurocomputing</i> , <b>2021</b> , 456, 156-167	5.4	1	

24	Stability and Admissibility Analysis for Zero-Sum Games Under General Value Iteration Formulation <i>IEEE Transactions on Neural Networks and Learning Systems</i> , <b>2022</b> , PP,	10.3	1
23	Online Value Iteration for Intelligent Discounted Tracking Design of Constrained Systems. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , <b>2022</b> , 1-1	3.5	1
22	ADP-Based Supplementary Design for Load Frequency Control of Power Systems. <i>Studies in Systems, Decision and Control</i> , <b>2019</b> , 281-304	0.8	О
21	Decentralized Control of Continuous-Time Interconnected Nonlinear Systems. <i>Advances in Industrial Control</i> , <b>2017</b> , 387-415	0.3	
20	Data-Based Neuro-Optimal Temperature Control of Water Gas Shift Reaction. <i>Advances in Industrial Control</i> , <b>2017</b> , 571-590	0.3	
19	Policy Iteration for Optimal Control of Discrete-Time Nonlinear Systems. <i>Advances in Industrial Control</i> , <b>2017</b> , 151-175	0.3	
18	Error Bounds of Adaptive Dynamic Programming Algorithms. Advances in Industrial Control, 2017, 223-2	2 <b>64</b> 3	
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