## Hao Guo

## List of Publications by Year in descending order

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2258059 2053705 5 9 69 3 citations h-index g-index papers 9 9 9 69 citing authors all docs docs citations times ranked

#	Article	IF	Citations
1	Continuum robot shape estimation using permanent magnets and magnetic sensors. Sensors and Actuators A: Physical, 2019, 285, 519-530.	4.1	39
2	Design and analysis of a continuum robot for transnasal skull base surgery. International Journal of Medical Robotics and Computer Assisted Surgery, 2021, 17, e2328.	2.3	12
3	A resonant tactile stiffness sensor for lump localization in robot-assisted minimally invasive surgery. Proceedings of the Institution of Mechanical Engineers, Part H: Journal of Engineering in Medicine, 2019, 233, 909-920.	1.8	7
4	Development of a variable-stiffness and shape-detection manipulator based on low-melting-point-alloy for minimally invasive surgery., 2020, 2020, 4895-4898.		3
5	Preliminary Study on Shape Sensing for Continuum Robot Affected by External Load Using Piecewise Fitting Curves., 2019,,.		2
6	A Piezoelectric Tactile Sensor and Human-inspired Tactile Exploration Strategy for Lump Palpation in Tele-operative Robotic Minimally Invasive Surgery. , 2019, , .		2
7	Analysis of a novel manipulator with low melting point alloy initiated stiffness variation and shape detection for minimally invasive surgery. Industrial Robot, 2021, 48, 247-258.	2.1	2
8	A rotary joint based on dielectric elastomer. , 2013, , .		1
9	Multi-continuum manipulators shape reconstruction using inertial navigation sensors and cameras. Industrial Robot, 2021, 48, 401-412.	2.1	1