

# Paulo Flores

## List of Publications by Year in descending order

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164  
papers

7,092  
citations

66234

42  
h-index

60497

81  
g-index

202  
all docs

202  
docs citations

202  
times ranked

2096  
citing authors

#	ARTICLE	IF	CITATIONS
1	Compliant contact force models in multibody dynamics: Evolution of the Hertz contact theory. <i>Mechanism and Machine Theory</i> , 2012, 53, 99-121.	2.7	475
2	On the continuous contact force models for soft materials in multibody dynamics. <i>Multibody System Dynamics</i> , 2011, 25, 357-375.	1.7	314
3	A survey and comparison of several friction force models for dynamic analysis of multibody mechanical systems. <i>Nonlinear Dynamics</i> , 2016, 86, 1407-1443.	2.7	292
4	A comprehensive survey of the analytical, numerical and experimental methodologies for dynamics of multibody mechanical systems with clearance or imperfect joints. <i>Mechanism and Machine Theory</i> , 2018, 122, 1-57.	2.7	277
5	Revolute joints with clearance in multibody systems. <i>Computers and Structures</i> , 2004, 82, 1359-1369.	2.4	257
6	A study on dynamics of mechanical systems including joints with clearance and lubrication. <i>Mechanism and Machine Theory</i> , 2006, 41, 247-261.	2.7	249
7	Modeling and simulation of wear in revolute clearance joints in multibody systems. <i>Mechanism and Machine Theory</i> , 2009, 44, 1211-1222.	2.7	249
8	A parametric study on the dynamic response of planar multibody systems with multiple clearance joints. <i>Nonlinear Dynamics</i> , 2010, 61, 633-653.	2.7	231
9	Numerical and experimental investigation on multibody systems with revolute clearance joints. <i>Nonlinear Dynamics</i> , 2011, 65, 383-398.	2.7	213
10	On the contact detection for contact-impact analysis in multibody systems. <i>Multibody System Dynamics</i> , 2010, 24, 103-122.	1.7	200
11	Dynamic Analysis for Planar Multibody Mechanical Systems with Lubricated Joints. <i>Multibody System Dynamics</i> , 2004, 12, 47-74.	1.7	195
12	Modeling and analysis of planar rigid multibody systems with translational clearance joints based on the non-smooth dynamics approach. <i>Multibody System Dynamics</i> , 2010, 23, 165-190.	1.7	187
13	Dynamics of spatial flexible multibody systems with clearance and lubricated spherical joints. <i>Computers and Structures</i> , 2009, 87, 913-929.	2.4	184
14	A new model for dry and lubricated cylindrical joints with clearance in spatial flexible multibody systems. <i>Nonlinear Dynamics</i> , 2011, 64, 25-47.	2.7	180
15	A comparative study of the viscoelastic constitutive models for frictionless contact interfaces in solids. <i>Mechanism and Machine Theory</i> , 2015, 85, 172-188.	2.7	179
16	Study of the effect of contact force model on the dynamic response of mechanical systems with dry clearance joints: computational and experimental approaches. <i>Nonlinear Dynamics</i> , 2013, 73, 325-338.	2.7	169
17	Spatial rigid-multibody systems with lubricated spherical clearance joints: modeling and simulation. <i>Nonlinear Dynamics</i> , 2010, 60, 99-114.	2.7	132
18	ElastoHydroDynamic lubricated cylindrical joints for rigid-flexible multibody dynamics. <i>Computers and Structures</i> , 2013, 114-115, 106-120.	2.4	124

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19	An enhanced formulation to model spatial revolute joints with radial and axial clearances. <i>Mechanism and Machine Theory</i> , 2017, 116, 123-144.	2.7	117
20	Lubricated revolute joints in rigid multibody systems. <i>Nonlinear Dynamics</i> , 2009, 56, 277-295.	2.7	110
21	Modeling and analysis of friction including rolling effects in multibody dynamics: a review. <i>Multibody System Dynamics</i> , 2019, 45, 223-244.	1.7	110
22	A Parametric Study on the Baumgarte Stabilization Method for Forward Dynamics of Constrained Multibody Systems. <i>Journal of Computational and Nonlinear Dynamics</i> , 2011, 6, .	0.7	107
23	Dynamics of Multibody Systems With Spherical Clearance Joints. <i>Journal of Computational and Nonlinear Dynamics</i> , 2006, 1, 240-247.	0.7	105
24	Dynamic Response of Multibody Systems with Multiple Clearance Joints. <i>Journal of Computational and Nonlinear Dynamics</i> , 2012, 7, .	0.7	98
25	The effect of the lubricated revolute joint parameters and hydrodynamic force models on the dynamic response of planar multibody systems. <i>Nonlinear Dynamics</i> , 2012, 69, 635-654.	2.7	94
26	Nonlinear dynamics and chaotic control of a flexible multibody system with uncertain joint clearance. <i>Nonlinear Dynamics</i> , 2016, 86, 1571-1597.	2.7	94
27	Exact and Approximate Algorithms for the Optimization of Area and Delay in Multiple Constant Multiplications. <i>IEEE Transactions on Computer-Aided Design of Integrated Circuits and Systems</i> , 2008, 27, 1013-1026.	1.9	92
28	On the constraints violation in forward dynamics of multibody systems. <i>Multibody System Dynamics</i> , 2017, 39, 385-419.	1.7	88
29	Coupling dynamics of a geared multibody system supported by ElastoHydroDynamic lubricated cylindrical joints. <i>Multibody System Dynamics</i> , 2015, 33, 259-284.	1.7	81
30	Translational Joints With Clearance in Rigid Multibody Systems. <i>Journal of Computational and Nonlinear Dynamics</i> , 2008, 3, .	0.7	79
31	A mathematical framework for rigid contact detection between quadric and superquadric surfaces. <i>Multibody System Dynamics</i> , 2010, 24, 255-280.	1.7	78
32	Development of a planar multibody model of the human knee joint. <i>Nonlinear Dynamics</i> , 2010, 60, 459-478.	2.7	78
33	Search algorithms for the multiple constant multiplications problem: Exact and approximate. <i>Microprocessors and Microsystems</i> , 2010, 34, 151-162.	1.8	75
34	Contact Force Models for Multibody Dynamics. <i>Solid Mechanics and Its Applications</i> , 2016, , .	0.1	71
35	Portuguese higher education students's adaptation to online teaching and learning in times of the COVID-19 pandemic: personal and contextual factors. <i>Higher Education</i> , 2022, 83, 1389-1408.	2.8	69
36	Application of the nonsmooth dynamics approach to model and analysis of the contact-impact events in cam-follower systems. <i>Nonlinear Dynamics</i> , 2012, 69, 2117-2133.	2.7	66

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37	Influence of the contactâ€™impact force model on the dynamic response of multi-body systems. Proceedings of the Institution of Mechanical Engineers, Part K: Journal of Multi-body Dynamics, 2006, 220, 21-34.	0.5	64
38	Study of the friction-induced vibration and contact mechanics of artificial hip joints. Tribology International, 2014, 70, 1-10.	3.0	60
39	An investigation of a novel LuGre-based friction force model. Mechanism and Machine Theory, 2021, 166, 104493.	2.7	54
40	Nonlinear vibration and dynamics of ceramic on ceramic artificial hip joints: a spatial multibody modelling. Nonlinear Dynamics, 2014, 76, 1365-1377.	2.7	53
41	Dynamic modeling and analysis of wear in spatial hard-on-hard couple hip replacements using multibody systems methodologies. Nonlinear Dynamics, 2015, 82, 1039-1058.	2.7	52
42	A three-dimensional approach for contact detection between realistic wheel and rail surfaces for improved railway dynamic analysis. Mechanism and Machine Theory, 2020, 149, 103825.	2.7	48
43	A Kriging Model for Dynamics of Mechanical Systems With Revolute Joint Clearances. Journal of Computational and Nonlinear Dynamics, 2014, 9, .	0.7	42
44	Implementation of a non-Hertzian contact model for railway dynamic application. Multibody System Dynamics, 2020, 48, 41-78.	1.7	42
45	A Study on the Dynamics of Spatial Mechanisms With Frictional Spherical Clearance Joints. Journal of Computational and Nonlinear Dynamics, 2017, 12, .	0.7	41
46	Dynamic behaviour of planar rigid multi-body systems including revolute joints with clearance. Proceedings of the Institution of Mechanical Engineers, Part K: Journal of Multi-body Dynamics, 2007, 221, 161-174.	0.5	36
47	A finite element model of a 3D dry revolute joint incorporated in a multibody dynamic analysis. Multibody System Dynamics, 2019, 45, 293-313.	1.7	32
48	A review of squeaking in ceramic total hip prostheses. Tribology International, 2016, 93, 239-256.	3.0	31
49	Micro-CT based finite element modelling and experimental characterization of the compressive mechanical properties of 3-D zirconia scaffolds for bone tissue engineering. Journal of the Mechanical Behavior of Biomedical Materials, 2020, 102, 103516.	1.5	31
50	Examination and comparison of different methods to model closed loop kinematic chains using Lagrangian formulation with cut joint, clearance joint constraint and elastic joint approaches. Mechanism and Machine Theory, 2021, 160, 104294.	2.7	31
51	Strain shielding in distal femur after patellofemoral arthroplasty under different activity conditions. Journal of Biomechanics, 2010, 43, 477-484.	0.9	28
52	On the Frictional Contacts in Multibody System Dynamics. Computational Methods in Applied Sciences (Springer), 2016, , 67-91.	0.1	27
53	A compendium of contact force models inspired by Hunt and Crossley's cornerstone work. Mechanism and Machine Theory, 2022, 167, 104501.	2.7	27
54	A Computational Approach for Cam Size Optimization of Disc Cam-Follower Mechanisms With Translating Roller Followers. Journal of Mechanisms and Robotics, 2013, 5, .	1.5	26

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55	Spatial revolute joints with clearances for dynamic analysis of multi-body systems. Proceedings of the Institution of Mechanical Engineers, Part K: Journal of Multi-body Dynamics, 2006, 220, 257-271.	0.5	25
56	Contact mechanics for dynamical systems: a comprehensive review. Multibody System Dynamics, 2022, 54, 127-177.	1.7	25
57	Effects of poly-ether-ether ketone (PEEK) veneer thickness on the reciprocating friction and wear behavior of PEEK/Ti6Al4V structures in artificial saliva. Wear, 2016, 368-369, 84-91.	1.5	24
58	A kinematic characterization of human walking by using CaTraSys. Mechanism and Machine Theory, 2015, 86, 125-139.	2.7	23
59	On the generation of enhanced lookup tables for wheel-rail contact models. Wear, 2019, 434-435, 202993.	1.5	23
60	A particle swarm-based algorithm for optimization of multi-layered and graded dental ceramics. Journal of the Mechanical Behavior of Biomedical Materials, 2018, 77, 461-469.	1.5	19
61	Coupling multi-body dynamics and fluid dynamics to model lubricated spherical joints. Archive of Applied Mechanics, 2020, 90, 2091-2111.	1.2	19
62	Modeling of the condyle elements within a biomechanical knee model. Multibody System Dynamics, 2012, 28, 181-197.	1.7	18
63	Concepts and Formulations for Spatial Multibody Dynamics. SpringerBriefs in Applied Sciences and Technology, 2015, , .	0.2	18
64	A Computational Analysis of Squeaking Hip Prostheses. Journal of Computational and Nonlinear Dynamics, 2015, 10, .	0.7	17
65	A Methodology for Quantifying the Kinematic Position Errors due to Manufacturing and Assembly Tolerances. Strojniski Vestnik/Journal of Mechanical Engineering, 2011, 57, 457-467.	0.6	16
66	Influence of the Hip Joint Modeling Approaches on the Kinematics of Human Gait. Journal of Tribology, 2016, 138, .	1.0	16
67	Trends in the Control of Hexapod Robots: A Survey. Robotics, 2021, 10, 100.	2.1	16
68	Influence of the contact model on the dynamic response of the human knee joint. Proceedings of the Institution of Mechanical Engineers, Part K: Journal of Multi-body Dynamics, 2011, 225, 344-358.	0.5	15
69	Nickel-cobalt-based materials for diamond cutting tools. International Journal of Advanced Manufacturing Technology, 2018, 95, 1059-1067.	1.5	15
70	Wheel-rail contact models in the presence of switches and crossings. Vehicle System Dynamics, 2023, 61, 838-870.	2.2	15
71	Modelling lubricated revolute joints in multibody mechanical systems. Proceedings of the Institution of Mechanical Engineers, Part K: Journal of Multi-body Dynamics, 2004, 218, 183-190.	0.5	11
72	Biomechanical behaviour of cancellous bone on patellofemoral arthroplasty with Journey prosthesis: a finite element study. Computer Methods in Biomechanics and Biomedical Engineering, 2015, 18, 1090-1098.	0.9	11

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73	The journal of Mechanism and Machine Theory: Celebrating 55 years since its foundation. Mechanism and Machine Theory, 2019, 142, 103599.	2.7	11
74	Investigation on the Baumgarte Stabilization Method for Dynamic Analysis of Constrained Multibody Systems. , 2009, , 305-312.		10
75	Synthesis of a Mechanism for Human Gait Rehabilitation: An Introductory Approach. Mechanisms and Machine Science, 2015, , 121-128.	0.3	10
76	Wear behaviour of tetragonal zirconia polycrystal with a porous surface. International Journal of Refractory Metals and Hard Materials, 2018, 75, 85-93.	1.7	10
77	Crashworthiness analysis of an aircraft fuselage section with an auxiliary fuel tank using a hybrid multibody/plastic hinge approach. International Journal of Crashworthiness, 2020, 25, 95-105.	1.1	10
78	Unilateral anterior knee pain is associated with increased patellar lateral position after stressed lateral translation. Knee Surgery, Sports Traumatology, Arthroscopy, 2020, 28, 454-462.	2.3	10
79	On the Modeling of Biomechanical Systems for Human Movement Analysis: A Narrative Review. Archives of Computational Methods in Engineering, 2022, 29, 4915-4958.	6.0	10
80	Development of mechanical engineering curricula at the University of Minho. European Journal of Engineering Education, 2007, 32, 539-549.	1.5	9
81	A Lookup-Table-Based Approach for Spatial Analysis of Contact Problems. Journal of Computational and Nonlinear Dynamics, 2014, 9, .	0.7	9
82	A new device for patellofemoral instrumented stress-testing provides good reliability and validity. Knee Surgery, Sports Traumatology, Arthroscopy, 2020, 28, 389-397.	2.3	9
83	Current Perspectives on the Biomechanical Modelling of the Human Lower Limb: A Systematic Review. Archives of Computational Methods in Engineering, 2021, 28, 601-636.	6.0	9
84	Patients with different patellofemoral disorders display a distinct ligament stiffness pattern under instrumented stress testing. Journal of ISAKOS, 2020, 5, 74-79.	1.1	9
85	A Recursive Algorithm for the Forward Kinematic Analysis of Robotic Systems Using Euler Angles. Robotics, 2022, 11, 15.	2.1	9
86	The first fifty years of the Mechanism and Machine Theory: Standing back and looking forward. Mechanism and Machine Theory, 2018, 125, 8-20.	2.7	8
87	Contact-Impact Force Models for Mechanical Systems. , 2008, , 47-66.		8
88	High heterogeneity in in vivo instrumented-assisted patellofemoral joint stress testing: a systematic review. Knee Surgery, Sports Traumatology, Arthroscopy, 2019, 27, 745-757.	2.3	7
89	Design, Modelling and Control of an Active Weight-Bearing Knee Exoskeleton with a Series Elastic Actuator. , 2019, , .		7
90	Compliant contact force approach for forward dynamic modeling and analysis of biomechanical systems. Procedia IUTAM, 2011, 2, 58-67.	1.2	6

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91	Thermo-Mechanical Behaviour of Human Nasal Cartilage. <i>Polymers</i> , 2020, 12, 177.	2.0	6
92	Euler Angles, Bryant Angles and Euler Parameters. <i>SpringerBriefs in Applied Sciences and Technology</i> , 2015, , 15-22.	0.2	6
93	Modeling and Analysis of Rigid Multibody Systems with Translational Clearance Joints Based on the Nonsmooth Dynamics Approach. <i>Computational Methods in Applied Sciences (Springer)</i> , 2011, , 107-130.	0.1	6
94	Dissipative Contact Force Models. <i>Solid Mechanics and Its Applications</i> , 2016, , 27-52.	0.1	5
95	Effects of workersâ€™ Body Mass Index and task conditions on exertion psychophysics during Vertical Handling Tasks. <i>Work</i> , 2019, 63, 231-241.	0.6	5
96	Dynamic Modeling and Analysis of Pool Balls Interaction. <i>Computational Methods in Applied Sciences (Springer)</i> , 2020, , 79-86.	0.1	5
97	Obesity effects on muscular activity during lifting and lowering tasks. <i>International Journal of Occupational Safety and Ergonomics</i> , 2021, 27, 217-225.	1.1	5
98	A biomechanical multibody foot model for forward dynamic analysis. , 2012, ,		4
99	Development of a biomechanical spine model for dynamic analysis. , 2012, ,		4
100	Comparison of Different Methods to Control Constraints Violation in Forward Multibody Dynamics. , 2013, ,		4
101	Patellofemoral Evaluation: Do We Need an Objective Kinematic Approach?. , 2014, , 37-44.		4
102	Spatial Joints with Clearance: Dry Contact Models. , 2008, , 133-169.		4
103	Editorial: 50th anniversary of the Mechanism and Machine Theory. <i>Mechanism and Machine Theory</i> , 2016, 106, 190-192.	2.7	3
104	Utilization of Non-Conformal Wheel Surfaces for Railway Dynamics. <i>Mechanisms and Machine Science</i> , 2019, , 3291-3300.	0.3	3
105	Cam Size Optimization of Disc Cam-Follower Mechanisms with Translating Roller Followers. , 2010, , 225-233.		3
106	A Systematic and General Approach to Kinematic Position Errors Due to Manufacturing and Assemble Tolerances. , 2007, , 43.		2
107	Kinematics of the Roller Motion and CAM Size Optimization of Disc CAM-Follower Mechanisms With Translating Roller Followers. , 2009, ,		2
108	Clinical diagnosis of patellofemoral disorders. , 2013, ,		2

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109	Design of a New Knee Orthosis Locking System. , 2013, , .		2
110	A Study on the Dynamics of Spatial Mechanisms With Frictional Spherical Clearance Joints. , 2016, , .		2
111	A new approach to implement a customized anatomic insole in orthopaedic footwear of lower limb orthosis. IOP Conference Series: Materials Science and Engineering, 2017, 254, 232006.	0.3	2
112	An Optimization Approach to Generate Accurate and Efficient Lookup Tables for Engineering Applications. , 2019, , 1446-1457.		2
113	Modelling and simulation of alternative designs for the femurâ€“implant interface of Journey patellofemoral prosthesis. Proceedings of the Institution of Mechanical Engineers, Part L: Journal of Materials: Design and Applications, 2019, 233, 1619-1628.	0.7	2
114	Thermographic differences due to dynamic work tasks on individuals with different obesity levels: a preliminary study. Computer Methods in Biomechanics and Biomedical Engineering: Imaging and Visualization, 2020, 8, 323-333.	1.3	2
115	Kinematics differences between obese and non-obese workers during vertical handling tasks. International Journal of Industrial Ergonomics, 2020, 77, 102955.	1.5	2
116	Modeling, Analysis and Simulation of 3D Elastohydrodynamic Revolute Joints in Multibody Systems. Mechanisms and Machine Science, 2015, , 199-209.	0.3	2
117	Differences in muscular activity between obese and non-obese workers during manual lifting. DYNA (Colombia), 2016, 83, 55-62.	0.2	2
118	Fundamental Concepts in Multibody Dynamics. SpringerBriefs in Applied Sciences and Technology, 2015, , 5-9.	0.2	2
119	Contact Detection Approach Between Wheel and Rail Surfaces. Mechanisms and Machine Science, 2020, , 405-412.	0.3	2
120	A bibliometric overview of Mechanism and Machine Theory journal: Publication trends from 1990 to 2020. Mechanism and Machine Theory, 2022, 175, 104965.	2.7	2
121	A Parametric Study on the Baumgarte Stabilization Method for Forward Dynamics of Constrained Multibody Systems. , 2009, , .		1
122	Dynamic Response of Multibody Systems With Multiple Clearance Joints. , 2011, , .		1
123	Pure Elastic Contact Force Models. Solid Mechanics and Its Applications, 2016, , 15-25.	0.1	1
124	Demonstrative Application Examples. Solid Mechanics and Its Applications, 2016, , 135-168.	0.1	1
125	Professor Bernard (â€œBernieâ€) Roth: A short biography. Mechanism and Machine Theory, 2018, 125, 3-7.	2.7	1
126	Study of the Influence of the Revolute Joint Model on the Dynamic Behavior of Multibody Mechanical Systems: Modeling and Simulation. , 2007, , .		1



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127	Spatial Multibody Systems with Lubricated Spherical Joints: Modeling and Simulation. , 2010, , 397-404.		1
128	Tribological Behavior of 316L Stainless Steel Reinforced with CuCoBe+Diamond Composites by Laser Sintering and Hot Pressing: A Comparative Statistical Study. Lecture Notes in Computer Science, 2020, , 231-246.	1.0	1
129	Planar Joints with Clearance: Dry Contact Models. , 2008, , 67-100.		1
130	Radix <sup>2</sup> recoding with common subexpression elimination for multiple constant multiplication. IET Circuits, Devices and Systems, 2020, 14, 990-994.	0.9	1
131	Dynamic Modeling of a Human-Inspired Robot Based on a Newton-Euler Approach. CISM International Centre for Mechanical Sciences, Courses and Lectures, 2022, , 79-90.	0.3	1
132	Development of Mechanical Engineering Curricula at the University of Minho. , 2006, , 353.		0
133	Modeling Expected Wear in Revolute Joints With Clearance in Multibody Mechanical Systems. , 2007, , 357.		0
134	A Methodology to Detect the Precise Instant of Contact in Multibody Dynamics. , 2011, , .		0
135	On the Contact Modeling and Analysis of the Human Knee Joint. , 2011, , .		0
136	A Novel Continuous Contact Force Model for Multibody Dynamics. , 2011, , .		0
137	Development of a new femoral component for patellofemoral prosthesis. , 2012, , .		0
138	An Overview on Continuous Contact Force Models for Multibody Dynamics. , 2012, , .		0
139	Mechatronic medical device for wrist rehabilitation. , 2013, , .		0
140	Computational and Experimental Analysis of Mechanical Systems With Revolute Clearance Joints. , 2013, , .		0
141	Influence of the Lubrication Model on the Dynamic Response of Mechanical Systems. , 2013, , .		0
142	A DOE- and Kriging-Based Model for Studying on the Dynamics of Multibody Mechanical Systems With Revolute Joint Clearance. , 2013, , .		0
143	An Overview of Several Formulations for Dry and Lubricated Revolute Joint Clearances in Planar Rigid-Multi-Body Mechanical Systems. , 2014, , .		0
144	Development and Early Results of a New Concept of an Orthopedic Footwear Stirrup. Mechanisms and Machine Science, 2015, , 699-707.	0.3	0

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145	A medical device for support of the ankle pathologies diagnosis. , 2015, , .		0
146	Numerical Methods in Multibody System Dynamics. Solid Mechanics and Its Applications, 2016, , 93-134.	0.1	0
147	Computational Modelling of Human Lower Limb for Reproduction of Walking Dynamics with Muscles: Healthy and Pathological Cases. Mechanisms and Machine Science, 2019, , 3227-3236.	0.3	0
148	Computational Modelling of Human Lower Limb for Reproduction of Walking Dynamics with Muscles: Healthy and Pathological Cases. , 2019, , .		0
149	Railway Dynamics with Curved Contact Patch. Mechanisms and Machine Science, 2022, , 105-113.	0.3	0
150	On the Utilization of Simplified Methodologies for the Wheel-Rail Contact. Mechanisms and Machine Science, 2022, , 114-121.	0.3	0
151	Kinematic Analysis of the Roller Follower Motion in Translating Cam-Follower Mechanisms. , 2010, , 253-259.		0
152	A Lookup Table-Based Approach for Spatial Analysis of Contact Problems. , 2013, , .		0
153	A New Approach to Eliminate the Constraints Violation at the Position and Velocity Levels in Constrained Mechanical Multibody Systems. Mechanisms and Machine Science, 2015, , 385-393.	0.3	0
154	Vector of Coordinates, Velocities and Accelerations. SpringerBriefs in Applied Sciences and Technology, 2015, , 27-29.	0.2	0
155	Methods to Solve the Equations of Motion. SpringerBriefs in Applied Sciences and Technology, 2015, , 61-66.	0.2	0
156	Demonstrative Example of Application. SpringerBriefs in Applied Sciences and Technology, 2015, , 79-83.	0.2	0
157	Equations of Motion for Constrained Systems. SpringerBriefs in Applied Sciences and Technology, 2015, , 49-53.	0.2	0
158	Correction of the Initial Conditions. SpringerBriefs in Applied Sciences and Technology, 2015, , 75-78.	0.2	0
159	Undergraduatesâ€™ Views of Assessment in Higher Education: A Study carried out in Portugal. , 0, , .		0
160	Analysis of Infrared Imaging During Vertical Handling Tasks in Workers with Different Levels of Obesity. Advances in Intelligent Systems and Computing, 2018, , 447-455.	0.5	0
161	Workersâ€™ Body Constitution as a Risk Factor During Manual Materials Handling. Advances in Intelligent Systems and Computing, 2019, , 898-903.	0.5	0
162	On the Computational Biomechanics of the Intervertebral Disc. Lecture Notes in Computational Vision and Biomechanics, 2020, , 223-240.	0.5	0

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163	Multibody Systems Formulation. , 2008, , 23-45.		0
164	Lubricated Joints for Mechanical Systems. , 2008, , 101-131.		0