

# H Jin Kim

## List of Publications by Year in Descending Order

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**Version:** 2024-04-20

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

162  
papers

2,971  
citations

30  
h-index

50  
g-index

186  
ext. papers

3,903  
ext. citations

3.6  
avg, IF

5.91  
L-index

#	Paper	IF	Citations
162	Learning and Generalizing Cooperative Manipulation Skills Using Parametric Dynamic Movement Primitives. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2022</b> , 1-12	4.9	
161	Online Distributed Trajectory Planning for Quadrotor Swarm With Feasibility Guarantee Using Linear Safe Corridor. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 7, 4869-4876	4.2	2
160	Unsupervised Reinforcement Learning for Transferable Manipulation Skill Discovery. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 1-1	4.2	
159	Automating Reinforcement Learning with Example-based Resets. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 1-1	4.2	0
158	Aerial Chasing of a Dynamic Target in Complex Environments. <i>International Journal of Control, Automation and Systems</i> , <b>2022</b> , 20, 2032-2042	2.9	
157	Low-Latency and Scene-Robust Optical Flow Stream and Angular Velocity Estimation. <i>IEEE Access</i> , <b>2021</b> , 9, 155988-155997	3.5	
156	Fast Computation of Tight Funnels for Piecewise Polynomial Systems <b>2021</b> , 1-1		
155	Autonomous Aerial Dual-Target Following Among Obstacles. <i>IEEE Access</i> , <b>2021</b> , 9, 143104-143120	3.5	1
154	Aerial Manipulator Pushing a Movable Structure Using a DOB-Based Robust Controller. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 723-730	4.2	4
153	Fast Funnel Computation Using Multivariate Bernstein Polynomial. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 1351-1358	4.2	1
152	Online Trajectory Planning for Multiple Quadrotors in Dynamic Environments Using Relative Safe Flight Corridor. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 659-666	4.2	11
151	Real-Time Rotational Motion Estimation With Contrast Maximization Over Globally Aligned Events. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 6016-6023	4.2	5
150	Realtime Object-aware Monocular Depth Estimation in Onboard Systems. <i>International Journal of Control, Automation and Systems</i> , <b>2021</b> , 19, 3179-3189	2.9	
149	Hybrid Reinforcement Learning Control for a Micro Quadrotor Flight <b>2021</b> , 5, 505-510		4
148	Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2021</b> , 26, 765-776	5.5	3
147	Multirobot Collaborative Monocular SLAM Utilizing Rendezvous. <i>IEEE Transactions on Robotics</i> , <b>2021</b> , 1-18	6.5	6
146	Linear RGB-D SLAM for Structured Environments. <i>IEEE Transactions on Pattern Analysis and Machine Intelligence</i> , <b>2021</b> , PP,	13.3	2

145	Spatio-semantic Task Recognition: Unsupervised Learning of Task-discriminative Features for Segmentation and Imitation. <i>International Journal of Control, Automation and Systems</i> , <b>2021</b> , 19, 3409	2.9	
144	Pose Correction Algorithm for Relative Frames Between Keyframes in SLAM. <i>Lecture Notes in Computer Science</i> , <b>2021</b> , 326-340	0.9	
143	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2020</b> , 56, 4974-4983	3.7	6
142	Real-Time Optimal Trajectory Generation and Control of a Multi-Rotor With a Suspended Load for Obstacle Avoidance. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 1915-1922	4.2	6
141	Design, Fabrication, and Analysis of Flapping and Folding Wing Mechanism for a Robotic Bird. <i>Journal of Bionic Engineering</i> , <b>2020</b> , 17, 229-240	2.7	9
140	Stable Flight of a Flapping-Wing Micro Air Vehicle Under Wind Disturbance. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 5685-5692	4.2	6
139	. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 5905-5912	4.2	4
138	Fail-Safe Flight of a Fully-Actuated Quadrotor in a Single Motor Failure. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 6403-6410	4.2	4
137	Integrated Motion Planner for Real-time Aerial Videography with a Drone in a Dense Environment <b>2020</b> ,		9
136	Trajectory Planning with Safety Guaranty for a Multirotor based on the Forward and Backward Reachability Analysis <b>2020</b> ,		1
135	Efficient Multi-Agent Trajectory Planning with Feasibility Guarantee using Relative Bernstein Polynomial <b>2020</b> ,		11
134	Aerial Manipulation using Model Predictive Control for Opening a Hinged Door <b>2020</b> ,		4
133	Robust Translational Force Control of Multi-Rotor UAV for Precise Acceleration Tracking. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2020</b> , 17, 562-573	4.9	9
132	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2020</b> , 56, 1602-1612	3.7	21
131	Collision-Free Path Planning for Cooperative Aerial Manipulators Under Velocity and Curvature Constraints. <i>IEEE Access</i> , <b>2019</b> , 7, 171153-171162	3.5	3
130	Cargo Transportation Strategy using T3-Multirotor UAV <b>2019</b> ,		3
129	Networked Operation of a UAV Using Gaussian Process-Based Delay Compensation and Model Predictive Control <b>2019</b> ,		1
128	Incorporating Safety Into Parametric Dynamic Movement Primitives. <i>IEEE Robotics and Automation Letters</i> , <b>2019</b> , 4, 2260-2267	4.2	3

127	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2019</b> , 55, 236-250	3-7	24
126	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2019</b> , 55, 82-94	3-7	35
125	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2019</b> , 55, 830-845	3-7	8
124	Real-time Optimal Planning and Model Predictive Control of a Multi-rotor with a Suspended Load <b>2019</b> ,		4
123	Online Trajectory Generation of a MAV for Chasing a Moving Target in 3D Dense Environments <b>2019</b> ,		10
122	Robust Real-time RGB-D Visual Odometry in Dynamic Environments via Rigid Motion Model <b>2019</b> ,		4
121	Fast and Safe Policy Adaptation via Alignment-based Transfer <b>2019</b> ,		1
120	Fast Trajectory Planning for Multiple Quadrotors using Relative Safe Flight Corridor <b>2019</b> ,		3
119	Robust Trajectory Planning for a Multirotor against Disturbance based on Hamilton-Jacobi Reachability Analysis <b>2019</b> ,		12
118	<b>2019</b> ,		2
117	Efficient networked UAV control using event-triggered predictive control. <i>IFAC-PapersOnLine</i> , <b>2019</b> , 52, 412-417	0-7	2
116	Autonomous flight with robust visual odometry under dynamic lighting conditions. <i>Autonomous Robots</i> , <b>2019</b> , 43, 1605-1622	3	9
115	An Integrated Framework for Cooperative Aerial Manipulators in Unknown Environments. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 2307-2314	4-2	15
114	Cooperative Aerial Manipulation Using Multirotors With Multi-DOF Robotic Arms. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2018</b> , 23, 702-713	5-5	32
113	Adaptive Range Estimation in Perspective Vision System Using Neural Networks. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2018</b> , 23, 972-977	5-5	7
112	Toward a Secure Drone System: Flying With Real-Time Homomorphic Authenticated Encryption. <i>IEEE Access</i> , <b>2018</b> , 6, 24325-24339	3-5	46
111	Planning and Control for Collision-Free Cooperative Aerial Transportation. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2018</b> , 15, 189-201	4-9	54
110	A Robust Control Approach for Hydraulic Excavators Using $\mathcal{E}$ -synthesis. <i>International Journal of Control, Automation and Systems</i> , <b>2018</b> , 16, 1615-1628	2-9	14

109	Visual Inertial Odometry with Pentafoveal Geometric Constraints. <i>International Journal of Control, Automation and Systems</i> , <b>2018</b> , 16, 1962-1970	2.9	2
108	Adaptive Flow Separation Control Over an Asymmetric Airfoil. <i>International Journal of Aeronautical and Space Sciences</i> , <b>2018</b> , 19, 305-315	1.2	2
107	Robust Gust Load Alleviation Control using Disturbance Observer for Generic Flexible Wing Aircraft in Cruising Condition <b>2018</b> ,		2
106	Vision-based Target Tracking for a Skid-steer Vehicle using Guided Policy Search with Field-of-view Constraint <b>2018</b> ,		3
105	Learning-based Path Tracking Control of a Flapping-wing Micro Air Vehicle <b>2018</b> ,		2
104	Design, modeling and control of t3-multirotor: a tilting thruster type multirotor <b>2018</b> ,		3
103	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2018</b> , 54, 3096-3107	3.7	40
102	Soft robot review. <i>International Journal of Control, Automation and Systems</i> , <b>2017</b> , 15, 3-15	2.9	226
101	Constraint-Based Cooperative Control of Multiple Aerial Manipulators for Handling an Unknown Payload. <i>IEEE Transactions on Industrial Informatics</i> , <b>2017</b> , 13, 2780-2790	11.9	41
100	Trajectory tracking control of multirotors from modelling to experiments: A survey. <i>International Journal of Control, Automation and Systems</i> , <b>2017</b> , 15, 281-292	2.9	51
99	Convergence-enhanced dense RGB-D odometry with a rotational motion prior from a gyroscope <b>2017</b> ,		1
98	Autonomous lane keeping based on approximate Q-learning <b>2017</b> ,		4
97	Motion planning with movement primitives for cooperative aerial transportation in obstacle environment <b>2017</b> ,		15
96	Autonomous swing-angle estimation for stable slung-load flight of multi-rotor UAVs <b>2017</b> ,		9
95	Three-link planar arm control using reinforcement learning <b>2017</b> ,		2
94	Inverse reinforcement learning control for trajectory tracking of a multirotor UAV. <i>International Journal of Control, Automation and Systems</i> , <b>2017</b> , 15, 1826-1834	2.9	15
93	Robust visual localization in changing lighting conditions <b>2017</b> ,		9
92	Aerial grasping of cylindrical object using visual servoing based on stochastic model predictive control <b>2017</b> ,		27

91	Indoor Localization Without a Prior Map by Trajectory Learning From Crowdsourced Measurements. <i>IEEE Transactions on Instrumentation and Measurement</i> , <b>2017</b> , 66, 2825-2835	5.2	24
90	Estimation, Control, and Planning for Autonomous Aerial Transportation. <i>IEEE Transactions on Industrial Electronics</i> , <b>2017</b> , 64, 3369-3379	8.9	42
89	Online Learning Control of Hydraulic Excavators Based on Echo-State Networks. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2017</b> , 14, 249-259	4.9	33
88	Vision-based deep reinforcement learning to control a manipulator <b>2017</b> ,		1
87	Model predictive control of a multi-rotor with a slung load for avoiding obstacles <b>2017</b> ,		2
86	<b>2017</b> ,		6
85	Path planning for remotely controlled UAVs using Gaussian process filter <b>2017</b> ,		3
84	Collision avoidance of robotic arm of aerial manipulator <b>2017</b> ,		1
83	Trajectory generation for networked UAVs using online learning for delay compensation <b>2017</b> ,		2
82	Path Tracking for a Skid-steer Vehicle using Model Predictive Control with On-line Sparse Gaussian Process. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 5755-5760	0.7	9
81	Bayesian Online Learning for Information-based Multi-Agent Exploration with Unknown Radio Signal Distribution. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 2621-2626	0.7	
80	Smooth trajectory generation for soft catching a flying object with an aerial vehicle <b>2017</b> ,		1
79	Real-time rigid motion segmentation using grid-based optical flow <b>2017</b> ,		1
78	Robust Control of an Equipment-Added Multirotor Using Disturbance Observer. <i>IEEE Transactions on Control Systems Technology</i> , <b>2017</b> , 1-8	4.8	36
77	Time-efficient dense visual 12-DoF state estimator using RGB-D camera <b>2017</b> ,		1
76	Nonsingular Sliding Mode Guidance for Impact Time Control. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2016</b> , 39, 61-68	2.1	125
75	Mapless indoor localization by trajectory learning from a crowd <b>2016</b> ,		4
74	Entry optimization using mixed integer linear programming. <i>International Journal of Control, Automation and Systems</i> , <b>2016</b> , 14, 282-290	2.9	

73	Vision-Guided Aerial Manipulation Using a Multirotor With a Robotic Arm. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2016</b> , 21, 1912-1923	5.5	83
72	. <i>IEEE Transactions on Robotics</i> , <b>2016</b> , 32, 99-112	6.5	5
71	Autonomous flight and vision-based target tracking for a flapping-wing MAV <b>2016</b> ,		5
70	Robust acceleration control of a hexarotor UAV with a disturbance observer <b>2016</b> ,		22
69	Tracking of multiple moving targets using mobile networks based on mutual information <b>2016</b> ,		1
68	Path tracking control and identification of tire parameters using on-line model-based reinforcement learning <b>2016</b> ,		3
67	Impact time control guidance considering seeker's field-of-view limits <b>2016</b> ,		10
66	Adaptive control of a shape memory alloy actuator using neural-network feedforward and RISE feedback. <i>International Journal of Precision Engineering and Manufacturing</i> , <b>2016</b> , 17, 409-418	1.7	7
65	Decentralized trajectory optimization using virtual motion camouflage and particle swarm optimization. <i>Autonomous Robots</i> , <b>2015</b> , 38, 161-177	3	4
64	A Distributed Support Vector Machine Learning Over Wireless Sensor Networks. <i>IEEE Transactions on Cybernetics</i> , <b>2015</b> , 45, 2599-611	10.2	30
63	Real-time monocular image-based 6-DoF localization. <i>International Journal of Robotics Research</i> , <b>2015</b> , 34, 476-492	5.7	26
62	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , <b>2015</b> , 51, 1310-1323	3.7	40
61	Target localization in wireless sensor networks using online semi-supervised support vector regression. <i>Sensors</i> , <b>2015</b> , 15, 12539-59	3.8	31
60	Distributed estimation using online semi-supervised particle filter for mobile sensor networks. <i>IET Control Theory and Applications</i> , <b>2015</b> , 9, 418-427	2.5	14
59	Endoscopic Camera Manipulation planning of a surgical robot using Rapidly-Exploring Random Tree algorithm <b>2015</b> ,		5
58	Operating an unknown drawer using an aerial manipulator <b>2015</b> ,		43
57	Control of an aerial manipulator using on-line parameter estimator for an unknown payload <b>2015</b> ,		11
56	Robust visual odometry to irregular illumination changes with RGB-D camera <b>2015</b> ,		1

55	A multi-class classification approach for target localization in wireless sensor networks. <i>Journal of Mechanical Science and Technology</i> , <b>2014</b> , 28, 323-329	1.6	5
54	Utilizing online learning based on echo-state networks for the control of a hydraulic excavator. <i>Mechatronics</i> , <b>2014</b> , 24, 986-1000	3	25
53	Optimal sensor placement for RSS-based localization using Gaussian process <b>2014</b> ,		2
52	Robust control of a quadrotor using Takagi-Sugeno fuzzy model and an LMI approach <b>2014</b> ,		6
51	Real-time 6-DOF monocular visual SLAM in a large-scale environment <b>2014</b> ,		34
50	Target tracking and classification from labeled and unlabeled data in wireless sensor networks. <i>Sensors</i> , <b>2014</b> , 14, 23871-84	3.8	5
49	Design of a base station for MEMS CCR localization in an optical sensor network. <i>Sensors</i> , <b>2014</b> , 14, 8313-29	3.29	1
48	Online estimation using semi-supervised least square SVR <b>2014</b> ,		1
47	Semisupervised Location Awareness in Wireless Sensor Networks Using Laplacian Support Vector Regression. <i>International Journal of Distributed Sensor Networks</i> , <b>2014</b> , 10, 265801	1.7	3
46	Path tracking for a hydraulic excavator utilizing proportional-derivative and linear quadratic control <b>2014</b> ,		4
45	Policy Improvements for Probabilistic Pursuit-Evasion Game. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , <b>2014</b> , 74, 709-724	2.9	3
44	Fully Autonomous Vision-Based Net-Recovery Landing System for a Fixed-Wing UAV. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2013</b> , 18, 1320-1333	5.5	60
43	Trajectory Optimization Using Virtual Motion Camouflage and Particle Swarm Optimization. <i>Lecture Notes in Computer Science</i> , <b>2013</b> , 594-604	0.9	5
42	Joint detection and tracking of boundaries using cooperative mobile sensor networks <b>2013</b> ,		1
41	Target Localization Using Ensemble Support Vector Regression in Wireless Sensor Networks. <i>IEEE Transactions on Cybernetics</i> , <b>2013</b> , 43, 1189-98	10.2	49
40	LMI-Based Gain Synthesis for Simple Robust Quadrotor Control. <i>IEEE Transactions on Automation Science and Engineering</i> , <b>2013</b> , 10, 1173-1178	4.9	67
39	Predictive Target Detection and Sleep Scheduling for Wireless Sensor Networks <b>2013</b> ,		1
38	Aerial manipulation using a quadrotor with a two DOF robotic arm <b>2013</b> ,		19



37	Force and moment blending control for agile dual missiles <b>2013</b> ,		2
36	Robust proportional navigation guidance against highly maneuvering targets <b>2013</b> ,		2
35	Simultaneous task assignment and path planning using mixed-integer linear programming and potential field method <b>2013</b> ,		2
34	Backstepping Control on SE(3) of a Micro Quadrotor for Stable Trajectory Tracking <b>2013</b> ,		8
33	Application of Echo-State Networks to the Position Control of Shape-Memory Alloys. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2013</b> , 46, 712-717		2
32	Optimization of Decentralized Task Assignment for Heterogeneous UAVs. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2013</b> , 46, 251-256		3
31	Nonlinear Learning Control of Ionic Polymer Metal Composites. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2013</b> , 46, 233-238		2
30	Adaptive feedforward control of ionic polymer metal composites with disturbance cancellation. <i>Journal of Mechanical Science and Technology</i> , <b>2012</b> , 26, 205-212	1.6	9
29	Roll-pitch-yaw integrated synthesis for high angle-of-attack missiles. <i>Aerospace Science and Technology</i> , <b>2012</b> , 23, 270-279	4.9	10
28	Autonomous landing of a VTOL UAV on a moving platform using image-based visual servoing <b>2012</b> ,		130
27	Development of a path-tracking control system based on model predictive control using infrastructure sensors. <i>Vehicle System Dynamics</i> , <b>2012</b> , 50, 1001-1023	2.8	27
26	Autonomous Flight of the Rotorcraft-Based UAV Using RISE Feedback and NN Feedforward Terms. <i>IEEE Transactions on Control Systems Technology</i> , <b>2012</b> , 20, 1392-1399	4.8	46
25	Multi-target tracking using distributed SVM training over wireless sensor networks <b>2012</b> ,		3
24	Adaptive Image-Based Visual Servoing for an Underactuated Quadrotor System. <i>Journal of Guidance, Control, and Dynamics</i> , <b>2012</b> , 35, 1335-1353	2.1	55
23	Onboard flight control of a micro quadrotor using single strapdown optical flow sensor <b>2012</b> ,		12
22	Intrinsic high-frequency characteristics of graphene layers. <i>New Journal of Physics</i> , <b>2010</b> , 12, 113031	2.9	14
21	Asymptotic attitude tracking of the rotorcraft-based UAV via RISE feedback and NN feedforward <b>2010</b> ,		6
20	Electro-actuation characteristics of Cl <sub>2</sub> and SF <sub>6</sub> plasma-treated IPMC actuators. <i>Smart Materials and Structures</i> , <b>2010</b> , 19, 105013	3.4	4

19	Cucker-Smale Flocking With Inter-Particle Bonding Forces. <i>IEEE Transactions on Automatic Control</i> , <b>2010</b> , 55, 2617-2623	5.9	81
18	Adaptive visual servo control for a quadrotor helicopter <b>2010</b> ,		2
17	Model predictive flight control using adaptive support vector regression. <i>Neurocomputing</i> , <b>2010</b> , 73, 1031-1037	5.4	34
16	O <sub>2</sub> plasma treatment for ionic polymer metal nano composite (IPMNC) actuator. <i>Sensors and Actuators B: Chemical</i> , <b>2010</b> , 147, 170-179	8.5	12
15	Adaptive inverse control using support vector regression <b>2009</b> ,		2
14	Feedback linearization vs. adaptive sliding mode control for a quadrotor helicopter. <i>International Journal of Control, Automation and Systems</i> , <b>2009</b> , 7, 419-428	2.9	392
13	Model-predictive active steering and obstacle avoidance for autonomous ground vehicles. <i>Control Engineering Practice</i> , <b>2009</b> , 17, 741-750	3.9	120
12	Nonlinear Model Predictive Formation Flight. <i>IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans</i> , <b>2009</b> , 39, 1116-1125		65
11	Microfabricated coupled-cavity backward-wave oscillator for terahertz imaging <b>2008</b> ,		2
10	Obstacle Avoidance for Wheeled Robots in Unknown Environments using Model Predictive Control. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2008</b> , 41, 6792-6797		4
9	Electrothermal noise analysis in frequency tuning of nanoresonators. <i>Solid-State Electronics</i> , <b>2008</b> , 52, 1388-1393	1.7	7
8	Safe steering of UGVs in polygonal environments <b>2007</b> ,		1
7	Robust control of ionic polymer-metal composites. <i>Smart Materials and Structures</i> , <b>2007</b> , 16, 2457-2463	3.4	43
6	Radio-frequency transmission characteristics of a multi-walled carbon nanotube. <i>Nanotechnology</i> , <b>2007</b> , 18, 255701	3.4	30
5	Observer-based nonlinear model predictive tracking control for bank-to-turn missiles <b>2007</b> ,		1
4	Passive electrical properties of multi-walled carbon nanotubes up to 0.1 THz. <i>New Journal of Physics</i> , <b>2007</b> , 9, 265-265	2.9	23
3	Trajectory Generation for Rendezvous of Unmanned Aerial Vehicles with Kinematic Constraints. <i>Proceedings - IEEE International Conference on Robotics and Automation</i> , <b>2007</b> ,		4
2	Adjustable impact-time-control guidance law against non-maneuvering target under limited field of view. <i>Proceedings of the Institution of Mechanical Engineers, Part G: Journal of Aerospace Engineering</i> , <b>2007</b> , 095441002110129	0.9	3

- 1 Impact angle guidance law to prevent the detection degradation of a seeker. *Proceedings of the Institution of Mechanical Engineers, Part G: Journal of Aerospace Engineering*, 095441002110440 0.9