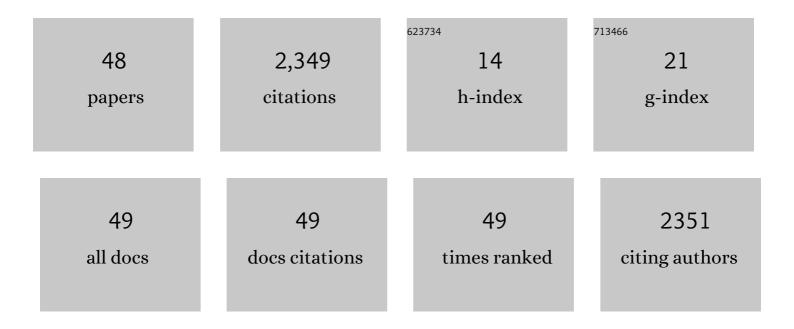
Danil Prokhorov

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/5367043/publications.pdf Version: 2024-02-01



| # | Article | IF | CITATIONS |
|----|---|------|-----------|
| 1 | Force Anticipation and Its Potential Implications on Feedforward and Feedback Human Motor Control. Human Factors, 2021, 63, 647-662. | 3.5 | 4 |
| 2 | Risk-Bounded Control Using Stochastic Barrier Functions. , 2021, 5, 1831-1836. | | 8 |
| 3 | Reachability analysis of deep ReLU neural networks using facet-vertex incidence. , 2021, , . | | 11 |
| 4 | Risk-bounded Control using Stochastic Barrier Functions. , 2021, , . | | 0 |
| 5 | Safe Navigation in Human Occupied Environments Using Sampling and Control Barrier Functions. , 2021, , . | | 10 |
| 6 | Human Model-Based Active Driving System in Vehicular Dynamic Simulation. IEEE Transactions on Intelligent Transportation Systems, 2020, 21, 1903-1914. | 8.0 | 5 |
| 7 | Feature Pyramid and Hierarchical Boosting Network for Pavement Crack Detection. IEEE Transactions on Intelligent Transportation Systems, 2020, 21, 1525-1535. | 8.0 | 460 |
| 8 | Requirements-Driven Test Generation for Autonomous Vehicles With Machine Learning Components. IEEE Transactions on Intelligent Vehicles, 2020, 5, 265-280. | 12.7 | 63 |
| 9 | Application of Simulation-Based Methods on Autonomous Vehicle Control with Deep Neural Network: Work-in-Progress. , 2020, , . | | 0 |
| 10 | Specification-guided Software Fault Localization for Autonomous Mobile Systems. , 2020, , . | | 2 |
| 11 | Toward Next Generation of Autonomous Systems with Al. , 2019, , . | | 1 |
| 12 | Merging in Congested Freeway Traffic Using Multipolicy Decision Making and Passive Actor-Critic Learning. IEEE Transactions on Intelligent Vehicles, 2019, 4, 287-297. | 12.7 | 38 |
| 13 | Fast construction of correcting ensembles for legacy Artificial Intelligence systems: Algorithms and a case study. Information Sciences, 2019, 485, 230-247. | 6.9 | 12 |
| 14 | Learning Deep Neural Network Controllers for Dynamical Systems with Safety Guarantees: Invited Paper. , 2019, , . | | 11 |
| 15 | Model-Free Real-Time EV Charging Scheduling Based on Deep Reinforcement Learning. IEEE Transactions on Smart Grid, 2019, 10, 5246-5257. | 9.0 | 300 |
| 16 | Differential Features for Pedestrian Detection: A Taylor Series Perspective. IEEE Transactions on Intelligent Transportation Systems, 2019, 20, 2913-2922. | 8.0 | 14 |
| 17 | Multi-Level Contextual RNNs With Attention Model for Scene Labeling. IEEE Transactions on Intelligent Transportation Systems, 2018, 19, 3475-3485. | 8.0 | 28 |
| 18 | Cross-Domain Traffic Scene Understanding: A Dense Correspondence-Based Transfer Learning Approach. IEEE Transactions on Intelligent Transportation Systems, 2018, 19, 745-757. | 8.0 | 33 |

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| # | Article | IF | CITATIONS |
|----|---|------|-----------|
| 19 | A Data-Driven Approach for Real-Time Residential EV Charging Management. , 2018, , . | | 10 |
| 20 | Deep Neural Network for Structural Prediction and Lane Detection in Traffic Scene. IEEE Transactions on Neural Networks and Learning Systems, 2017, 28, 690-703. | 11.3 | 326 |
| 21 | RGB-D Scene Labeling with Multimodal Recurrent Neural Networks. , 2017, , . | | 4 |
| 22 | Learning to tell brake and turn signals in videos using CNN-LSTM structure. , 2017, , . | | 15 |
| 23 | A benchmark for cross-weather traffic scene understanding. , 2016, , . | | 2 |
| 24 | Learning to tell brake lights with convolutional features. , 2016, , . | | 8 |
| 25 | Challenges in Perception and Decision Making for Intelligent Automotive Vehicles: A Case Study. IEEE Transactions on Intelligent Vehicles, 2016, 1, 20-32. | 12.7 | 57 |
| 26 | Cross datasets vegetation detection with spatial prior and local context. , 2016, , . | | 0 |
| 27 | MUlti-Store Tracker (MUSTer): A cognitive psychology inspired approach to object tracking. , 2015, , . | | 470 |
| 28 | Robust Multitask Multiview Tracking in Videos. IEEE Transactions on Neural Networks and Learning Systems, 2015, 26, 2874-2890. | 11.3 | 65 |
| 29 | Spatial Prior for Nonparametric Road Scene Parsing. , 2015, , . | | 3 |
| 30 | Detection and motion planning for roadside parked vehicles at long distance. , 2015, , . | | 4 |
| 31 | Clipping in Neurocontrol by Adaptive Dynamic Programming. IEEE Transactions on Neural Networks and Learning Systems, 2014, 25, 1909-1920. | 11.3 | 9 |
| 32 | Tracking Using Multilevel Quantizations. Lecture Notes in Computer Science, 2014, , 155-171. | 1.3 | 40 |
| 33 | An Equivalence Between Adaptive Dynamic Programming With a Critic and Backpropagation Through Time. IEEE Transactions on Neural Networks and Learning Systems, 2013, 24, 2088-2100. | 11.3 | 35 |
| 34 | Tracking via Robust Multi-task Multi-view Joint Sparse Representation. , 2013, , . | | 116 |
| 35 | Simple and Fast Calculation of the Second-Order Gradients for Globalized Dual Heuristic Dynamic Programming in Neural Networks. IEEE Transactions on Neural Networks and Learning Systems, 2012, 23, 1671-1676. | 11.3 | 41 |
| 36 | Multi-agent framework for remote diagnostics. , 2010, , . | | 3 |

Multi-agent framework for remote diagnostics. , 2010, , . 36

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| # | Article | IF | CITATIONS |
|----|--|-----|-----------|
| 37 | A Convolutional Learning System for Object Classification in 3-D Lidar Data. IEEE Transactions on Neural Networks, 2010, 21, 858-863. | 4.2 | 42 |
| 38 | A self-learning sensor fusion system for object classification. , 2009, , . | | 1 |
| 39 | Risk estimator for control in intelligent transportation system. , 2009, , . | | 4 |
| 40 | Where-what network 1: "Where" and "what" assist each other through top-down connections. , 2008, , . | | 27 |
| 41 | Intelligent Systems for Modeling and Control: Advances in Design and Validation. , 2008, , . | | 0 |
| 42 | Adaptive Classification of Temporal Signals in Fixed-Weight Recurrent Neural Networks: An Existence Proof. Neural Computation, 2008, 20, 2564-2596. | 2.2 | 5 |
| 43 | Neural Networks in Automotive Applications. Studies in Computational Intelligence, 2008, , 101-123. | 0.9 | 9 |
| 44 | Application of an Effective Data-Driven Approach to Real-time time Fault Diagnosis in Automotive Engines. , 2007, , . | | 15 |
| 45 | Toyota Prius HEV neurocontrol. Neural Networks (IJCNN), International Joint Conference on, 2007, , . | 0.0 | 12 |
| 46 | Unsupervised adaptive optimization of motion-sensitive systems guided by measurement uncertainty. , 2007, , . | | 1 |
| 47 | Toward effective combination of off-line and on-line training in ADP framework. , 2007, , . | | 11 |
| 48 | Finite form realizations of adaptive control algorithms. , 2003, , . | | 7 |