## Eunsoo Jung

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/5265757/publications.pdf

Version: 2024-02-01

|          |                | 1937685      | 1872680        |  |
|----------|----------------|--------------|----------------|--|
| 7        | 112            | 4            | 6              |  |
| papers   | citations      | h-index      | g-index        |  |
|          |                |              |                |  |
|          |                |              |                |  |
| 7        | 7              | 7            | 130            |  |
| all docs | docs citations | times ranked | citing authors |  |
|          |                |              |                |  |

| # | Article  | IF  | CITATIONS |
|---|--|-----|-----------|
| 1 | Steering, Tunneling, and Stent Delivery of a Multifunctional Magnetic Catheter Robot to Treat Occlusive Vascular Disease. IEEE Transactions on Industrial Electronics, 2021, 68, 391-400.  | 7.9 | 19        |
| 2 | Crawling Magnetic Robot to Perform a Biopsy in Tubular Environments by Controlling a Magnetic Field. Applied Sciences (Switzerland), 2021, 11, 5292.   | 2.5 | 1         |
| 3 | Enhanced steering ability of the distal end of a magnetic catheter by utilizing magnets with optimized magnetization direction. AIP Advances, 2019, 9, 125230.   | 1.3 | 4         |
| 4 | Image-based feedback control of a magnetic catheter to enhance the path-following capability of the position and orientation at its distal part. AIP Advances, 2019, 9, .  | 1.3 | 4         |
| 5 | Selective separating and assembling motion control for delivery and retrieval of an untethered magnetic robot in human blood vessels. AIP Advances, 2019, 9, .   | 1.3 | 5         |
| 6 | Magnetic Navigation System Utilizing a Closed Magnetic Circuit to Maximize Magnetic Field and a Mapping Method to Precisely Control Magnetic Field in Real Time. IEEE Transactions on Industrial Electronics, 2018, 65, 5673-5681. | 7.9 | 45        |
| 7 | Effective Locomotion and Precise Unclogging Motion of an Untethered Flexible-Legged Magnetic Robot for Vascular Diseases. IEEE Transactions on Industrial Electronics, 2018, 65, 1388-1397.  | 7.9 | 34        |