Eunsoo Jung

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/5265757/publications.pdf

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| | | 1937685 | 1872680 | |
|----------|----------------|--------------|----------------|--|
| 7 | 112 | 4 | 6 | |
| papers | citations | h-index | g-index | |
| | | | | |
| | | | | |
| 7 | 7 | 7 | 130 | |
| all docs | docs citations | times ranked | citing authors | |
| | | | | |

| # | Article | IF | CITATIONS |
|---|--|-----|-----------|
| 1 | Magnetic Navigation System Utilizing a Closed Magnetic Circuit to Maximize Magnetic Field and a Mapping Method to Precisely Control Magnetic Field in Real Time. IEEE Transactions on Industrial Electronics, 2018, 65, 5673-5681. | 7.9 | 45 |
| 2 | Effective Locomotion and Precise Unclogging Motion of an Untethered Flexible-Legged Magnetic Robot for Vascular Diseases. IEEE Transactions on Industrial Electronics, 2018, 65, 1388-1397. | 7.9 | 34 |
| 3 | Steering, Tunneling, and Stent Delivery of a Multifunctional Magnetic Catheter Robot to Treat Occlusive Vascular Disease. IEEE Transactions on Industrial Electronics, 2021, 68, 391-400. | 7.9 | 19 |
| 4 | Selective separating and assembling motion control for delivery and retrieval of an untethered magnetic robot in human blood vessels. AIP Advances, 2019, 9, . | 1.3 | 5 |
| 5 | Enhanced steering ability of the distal end of a magnetic catheter by utilizing magnets with optimized magnetization direction. AIP Advances, 2019, 9, 125230. | 1.3 | 4 |
| 6 | Image-based feedback control of a magnetic catheter to enhance the path-following capability of the position and orientation at its distal part. AIP Advances, 2019, 9, . | 1.3 | 4 |
| 7 | Crawling Magnetic Robot to Perform a Biopsy in Tubular Environments by Controlling a Magnetic Field. Applied Sciences (Switzerland), 2021, 11, 5292. | 2.5 | 1 |