

# Koichi Suzumori

## List of Publications by Citations

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259  
papers

2,480  
citations

22  
h-index

39  
g-index

306  
ext. papers

3,082  
ext. citations

1.9  
avg, IF

5.32  
L-index

#	Paper	IF	Citations
259	A Bending Pneumatic Rubber Actuator Realizing Soft-bodied Manta Swimming Robot. <i>Proceedings - IEEE International Conference on Robotics and Automation</i> , <b>2007</b> ,		162
258	. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>1999</b> , 4, 286-292	5.5	123
257	A micro ultrasonic motor using a micro-machined cylindrical bulk PZT transducer. <i>Sensors and Actuators A: Physical</i> , <b>2006</b> , 127, 131-138	3.9	108
256	Miniature Pneumatic Curling Rubber Actuator Generating Bidirectional Motion with One Air-Supply Tube. <i>Advanced Robotics</i> , <b>2011</b> , 25, 1311-1330	1.7	88
255	Elastic materials producing compliant robots. <i>Robotics and Autonomous Systems</i> , <b>1996</b> , 18, 135-140	3.5	82
254	Musculoskeletal lower-limb robot driven by multifilament muscles. <i>ROBOMECH Journal</i> , <b>2016</b> , 3,	2.1	68
253	Design of thin McKibben muscle and multifilament structure. <i>Sensors and Actuators A: Physical</i> , <b>2017</b> , 261, 66-74	3.9	64
252	Miniature soft hand with curling rubber pneumatic actuators <b>2009</b> ,		59
251	Fiberless flexible microactuator designed by finite-element method. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>1997</b> , 2, 281-286	5.5	54
250	A Modular Soft Robotic Wrist for Underwater Manipulation. <i>Soft Robotics</i> , <b>2018</b> , 5, 399-409	9.2	50
249	Design of a variable-stiffness robotic hand using pneumatic soft rubber actuators. <i>Smart Materials and Structures</i> , <b>2011</b> , 20, 105015	3.4	46
248	Flexible displacement sensor using injected conductive paste. <i>Sensors and Actuators A: Physical</i> , <b>2008</b> , 143, 272-278	3.9	41
247	Very High Force Hydraulic McKibben Artificial Muscle with a p-Phenylene-2,6-benzobisoxazole Cord Sleeve. <i>Advanced Robotics</i> , <b>2010</b> , 24, 233-254	1.7	36
246	Intelligent Actuators Realizing Snake-like Small Robot for Pipe Inspection <b>2006</b> ,		30
245	Load characteristics of mechanical pectoral fin. <i>Experiments in Fluids</i> , <b>2008</b> , 44, 759-771	2.5	29
244	A Cylindrical Micro-Ultrasonic Motor Using Micromachined Bulk Piezoelectric Vibrator with Glass Case. <i>Japanese Journal of Applied Physics</i> , <b>2006</b> , 45, 4764-4769	1.4	29
243	Index Finger of a Human-Like Robotic Hand Using Thin Soft Muscles. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 92-99	4.2	28

242	Flow control valve for pneumatic actuators using particle excitation by PZT vibrator. <i>Sensors and Actuators A: Physical</i> , <b>2009</b> , 155, 285-289	3.9	28
241	Fabrication of 8 Weave Muscles and Their Application to Soft Power Support Suit for Upper Limbs Using Thin McKibben Muscle. <i>IEEE Robotics and Automation Letters</i> , <b>2019</b> , 4, 2532-2538	4.2	27
240	Trends in hydraulic actuators and components in legged and tough robots: a review. <i>Advanced Robotics</i> , <b>2018</b> , 32, 458-476	1.7	27
239	New mobile pressure control system for pneumatic actuators, using reversible chemical reactions of water. <i>Sensors and Actuators A: Physical</i> , <b>2013</b> , 201, 148-153	3.9	25
238	Automatic pipe negotiation control for snake-like robot <b>2008</b> ,		23
237	Development of large intestine endoscope changing its stiffness <b>2009</b> ,		22
236	Droplet generation using a torsional Langevin-type transducer and a micropore plate. <i>Sensors and Actuators A: Physical</i> , <b>2009</b> , 155, 168-174	3.9	22
235	New concept and fundamental experiments of a smart pneumatic artificial muscle with a conductive fiber. <i>Sensors and Actuators A: Physical</i> , <b>2016</b> , 250, 48-54	3.9	21
234	Muscle textile to implement soft suit to shift balancing posture of the body <b>2018</b> ,		20
233	A proposal of a new rotational-compliant joint with oil-hydraulic McKibben artificial muscles. <i>Advanced Robotics</i> , <b>2018</b> , 32, 511-523	1.7	20
232	An ultrasonic motor for cryogenic temperature using bolt-clamped Langevin-type transducer. <i>Sensors and Actuators A: Physical</i> , <b>2012</b> , 184, 134-140	3.9	19
231	Development of an Intelligent Chair Tool System Applying New Intelligent Pneumatic Actuators. <i>Advanced Robotics</i> , <b>2010</b> , 24, 1503-1528	1.7	19
230	<b>2010</b> ,		19
229	Development of an Intelligent Pneumatic Cylinder for Distributed Physical Human-Machine Interaction. <i>Advanced Robotics</i> , <b>2009</b> , 23, 203-225	1.7	19
228	Comparative Assessment of Several Nutation Motor Types. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2009</b> , 14, 82-92	5.5	19
227	Applying Flexible Microactuators to Pipeline Inspection Robots <b>1993</b> , 515-520		19
226	Development of a 20-m-long Giacometti arm with balloon body based on kinematic model with air resistance <b>2017</b> ,		18
225	Flexible artificial muscle by bundle of McKibben fiber actuators <b>2011</b> ,		18

224	Braiding Thin McKibben Muscles to Enhance Their Contracting Abilities. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 3240-3246	4.2	18
223	Design and evaluation of orifice arrangement for particle-excitation flow control valve. <i>Sensors and Actuators A: Physical</i> , <b>2011</b> , 171, 283-291	3.9	16
222	Development of very high force hydraulic McKibben artificial muscle and its application to shape-adaptable power hand <b>2009</b> ,		16
221	In-Pipe Inspection Micro Robot Adaptable to Changes in Pipe Diameter. <i>Journal of Robotics and Mechatronics</i> , <b>2003</b> , 15, 609-615	0.7	16
220	Long-Legged Hexapod Giacometti Robot Using Thin Soft McKibben Actuator. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 100-107	4.2	16
219	New Soft Robot Hand Configuration With Combined Biotensegrity and Thin Artificial Muscle. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4345-4351	4.2	15
218	Integrated flexible microactuator systems. <i>Robotica</i> , <b>1996</b> , 14, 493-498	2.1	15
217	A Method of Designing and Fabricating Mckibben Muscles Driven by 7 MPa Hydraulics. <i>International Journal of Automation Technology</i> , <b>2012</b> , 6, 482-487	0.8	15
216	Active Textile Braided in Three Strands with Thin McKibben Muscle. <i>Soft Robotics</i> , <b>2019</b> , 6, 250-262	9.2	14
215	Novel design of rubber tube actuator improving mountability and drivability for assisting colonoscope insertion <b>2011</b> ,		14
214	IPMC Monolithic Thin Film Robots Fabricated Through a Multi-Layer Casting Process. <i>IEEE Robotics and Automation Letters</i> , <b>2019</b> , 4, 1335-1342	4.2	13
213	A Compact McKibben Muscle Based Bending Actuator for Close-to-Body Application in Assistive Wearable Robots. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 3042-3049	4.2	13
212	Long bending rubber mechanism combined contracting and extending fluidic actuators <b>2013</b> ,		13
211	A NEW PNEUMATIC CONTROL SYSTEM USING MULTIPLEX PNEUMATIC TRANSMISSION. <i>Proceedings of the JFPS International Symposium on Fluid Power</i> , <b>2008</b> , 2008, 439-442		13
210	Bolt-Clamped Langevin-Type Transducer for Ultrasonic Motor used at Ultralow Temperature. <i>Journal of Advanced Mechanical Design, Systems and Manufacturing</i> , <b>2012</b> , 6, 104-112	0.6	12
209	Development of Worm-Rack Driven Cylindrical Crawler Unit. <i>Journal of Advanced Mechanical Design, Systems and Manufacturing</i> , <b>2013</b> , 7, 422-431	0.6	12
208	<b>2010</b> ,		12
207	Multiplex pneumatic control method for multi-drive system. <i>Sensors and Actuators A: Physical</i> , <b>2010</b> , 164, 88-94	3.9	12

206	Distributed Physical Human Machine Interaction Using Intelligent Pneumatic Cylinders <b>2008</b> ,		12
205	Snake-like robot negotiating three-dimensional pipelines <b>2007</b> ,		12
204	Development of Contraction and Extension Artificial Muscles with Different Braid Angles and Their Application to Stiffness Changeable Bending Rubber Mechanisms by Their Combination. <i>Journal of Robotics and Mechatronics</i> , <b>2011</b> , 23, 582-588	0.7	12
203	Design of a weight-compensated and coupled tendon-driven articulated long-reach manipulator <b>2016</b> ,		12
202	<b>2013</b> ,		11
201	Emulsion Generating Microchannel Device Oscillated by 2.25 MHz Ultrasonic Vibrator. <i>Japanese Journal of Applied Physics</i> , <b>2010</b> , 49, 07HE13	1.4	11
200	<b>2006</b> ,		11
199	Development of a stable localized visual inspection system for underwater structures. <i>Advanced Robotics</i> , <b>2016</b> , 30, 1415-1429	1.7	11
198	Real-time position control of intelligent pneumatic actuator (IPA) system using optical encoder and pressure sensor. <i>Sensor Review</i> , <b>2013</b> , 33, 341-351	1.4	10
197	Controller Design for Simulation Control of Intelligent Pneumatic Actuators (IPA) System. <i>Procedia Engineering</i> , <b>2012</b> , 41, 593-599		10
196	Micro pneumatic curling actuator - Nematode actuator - <b>2009</b> ,		10
195	Development of Pneumatic Wobble Motors.. <i>JSME International Journal Series C-Mechanical Systems Machine Elements and Manufacturing</i> , <b>1999</b> , 42, 392-397		10
194	Micro-Walking Robot Driven by Flexible Microactuator. <i>Journal of Robotics and Mechatronics</i> , <b>1993</b> , 5, 537-541	0.7	10
193	A study on temperature dependence of an ultrasonic motor for cryogenic environment. <i>Japanese Journal of Applied Physics</i> , <b>2015</b> , 54, 07HE15	1.4	9
192	Development of Nutation Motors (1st Report, Driving Principle and Basic Characteristics of Pneumatic Nutation Motor). <i>Nippon Kikai Gakkai Ronbunshu, C Hen/Transactions of the Japan Society of Mechanical Engineers, Part C</i> , <b>2006</b> , 72, 1194-1199		9
191	Ultrasonic Motor Using Two Sector-Shaped Piezoelectric Transducers for Sample Spinning in High Magnetic Field. <i>Journal of Robotics and Mechatronics</i> , <b>2013</b> , 25, 384-391	0.7	9
190	An Ultrasonic Motor for Use at Ultralow Temperature Using Lead Magnesium Niobate/Lead Titanate Single Crystal. <i>Japanese Journal of Applied Physics</i> , <b>2012</b> , 51, 07GE09	1.4	9
189	Electrically-Driven Soft Fluidic Actuators Combining Stretchable Pumps With Thin McKibben Muscles. <i>Frontiers in Robotics and AI</i> , <b>2019</b> , 6, 146	2.8	9

188	<b>2019,</b>		8
187	Modeling of Synthetic Fiber Ropes and Frequency Response of Long-Distance CableBulley System. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 1743-1750	4.2	8
186	GPC Controller Design for an Intelligent Pneumatic Actuator. <i>Procedia Engineering</i> , <b>2012</b> , 41, 657-663		8
185	Development of Pneumatic Actuated Seating System to aid chair design <b>2010,</b>		8
184	Development of Variable Stiffness Colonoscope Consisting of Pneumatic Drive Devices. <i>International Journal of Automation Technology</i> , <b>2011</b> , 5, 551-558	0.8	8
183	Recurrent Braiding of Thin McKibben Muscles to Overcome Their Limitation of Contraction. <i>Soft Robotics</i> , <b>2020</b> , 7, 251-258	9.2	8
182	Design of knee support device based on four-bar linkage and hydraulic artificial muscle. <i>ROBOMECH Journal</i> , <b>2020</b> , 7,	2.1	8
181	A Proposal of Super Long Reach Articulated Manipulator with Gravity Compensation using Thrusters <b>2018,</b>		8
180	Soft manipulator using thin McKibben actuator <b>2018,</b>		8
179	Microdroplet generation using an ultrasonic torsional transducer which has a micropore with a tapered nozzle. <i>Archive of Applied Mechanics</i> , <b>2016</b> , 86, 1751-1762	2.2	7
178	Development of a gas/liquid phase change actuator for high temperatures. <i>ROBOMECH Journal</i> , <b>2016</b> , 3,	2.1	7
177	Static analysis of powered low-back orthosis driven by thin pneumatic artificial muscles considering body surface deformation <b>2015,</b>		7
176	<b>2015,</b>		7
175	Programmable System on Chip Distributed Communication and Control Approach for Human Adaptive Mechanical System. <i>Journal of Computer Science</i> , <b>2010</b> , 6, 852-861	0.5	7
174	Design and control of new intelligent pneumatic cylinder for intelligent chair tool application <b>2009,</b>		7
173	Beautiful Flexible Microactuator changing its structural color with variable pitch grating <b>2011,</b>		7
172	Roadmap on soft robotics: multifunctionality, adaptability and growth without borders. <i>Multifunctional Materials</i> ,	5.2	7
171	Modeling and Force Control of Thin Soft McKibben Actuator. <i>International Journal of Automation Technology</i> , <b>2016</b> , 10, 487-493	0.8	7

170	Omnidirectional Soft Robot Platform with Flexible Actuators for Medical Assistive Device. <i>International Journal of Automation Technology</i> , <b>2016</b> , 10, 494-502	0.8	7
169	Development of Active Links for Physical Man-Machine Interaction. <i>Journal of Robotics and Mechatronics</i> , <b>2005</b> , 17, 293-301	0.7	7
168	Comparison in Characteristics of Textile Woven by Thin Pneumatic Artificial Muscle. <i>The Abstracts of the International Conference on Advanced Mechatronics Toward Evolutionary Fusion of IT and Mechatronics ICAM</i> , <b>2015</b> , 2015.6, 43-44		7
167	Untethered three-arm pneumatic robot using hose-free pneumatic actuator <b>2016</b> ,		7
166	Proposal of flexible robotic arm with thin McKibben actuators mimicking octopus arm structure <b>2016</b> ,		7
165	Predictive Functional Controller design for pneumatic actuator with stiffness characteristic <b>2013</b> ,		6
164	A new mobile pressure control system for pneumatic actuators using reversible chemical reactions of water <b>2013</b> ,		6
163	Multifilament pneumatic artificial muscles to mimic the human neck <b>2017</b> ,		6
162	Experimental investigation of conductive fibers for a smart pneumatic artificial muscle <b>2015</b> ,		6
161	Nonlinear mathematical model of an Intelligent Pneumatic Actuator (IPA) systems: Position and force controls <b>2012</b> ,		6
160	An Ultrasonic Motor for Use at Ultralow Temperature Using Lead Magnesium Niobate/Lead Titanate Single Crystal. <i>Japanese Journal of Applied Physics</i> , <b>2012</b> , 51, 07GE09	1.4	6
159	Development and control of a multifingered robotic hand using a pneumatic tendon-driven actuator. <i>Journal of Intelligent Material Systems and Structures</i> , <b>2012</b> , 23, 345-352	2.3	6
158	Three-Port Valve to Generate Length-Controllable Slug Flow for Chemical Process(Machine Elements, Design and Manufacturing). <i>Nippon Kikai Gakkai Ronbunshu, C Hen/Transactions of the Japan Society of Mechanical Engineers, Part C</i> , <b>2010</b> , 76, 734-740		6
157	Development of nutation motors (improvement of pneumatic nutation motor by optimizing diaphragm design). <i>Journal of Mechanical Science and Technology</i> , <b>2010</b> , 24, 25-28	1.6	6
156	Micro rubber structure realizing multi-legged passive walking <b>2008</b> ,		6
155	Application of Micro-Electro-Mechanical Systems (MEMS) as Sensors: A Review. <i>Journal of Robotics and Mechatronics</i> , <b>2020</b> , 32, 281-288	0.7	6
154	Super-low friction and lightweight hydraulic cylinder using multi-directional forging magnesium alloy and its application to robotic leg. <i>Advanced Robotics</i> , <b>2018</b> , 32, 524-534	1.7	6
153	Energy regenerative hose-free pneumatic actuator. <i>Sensors and Actuators A: Physical</i> , <b>2016</b> , 249, 1-7	3.9	5

152	A functional adhesive robot skin with integrated micro rubber suction cups <b>2012,</b>		5
151	Development of large intestine endoscope changing its stiffness -2nd report: Improvement of stiffness change device and insertion experiment- <b>2010,</b>		5
150	NEW PNEUMATIC ACTUATORS PRODUCING BREAKTHROUGH IN MECHATRONICS. <i>Proceedings of the JFPS International Symposium on Fluid Power, 2008,</i> 2008, 197-202		5
149	Force Feedback Mouse with Differential Mechanism for Omni-Traveling <b>2007,</b>		5
148	Electrostatic linear microactuator mechanism for focusing a CCD camera. <i>Journal of Lightwave Technology, 1999,</i> 17, 43-47	4	5
147	Particle-Excitation Flow-Control Valve using Piezo Vibration-Improvement for a High Flow Rate and Research on Controllability. <i>IEEJ Transactions on Sensors and Micromachines, 2017,</i> 137, 32-37	0.2	5
146	Gas/Liquid Phase Change Actuator for Use in Extreme Temperature Environments. <i>International Journal of Automation Technology, 2014,</i> 8, 140-146	0.8	5
145	Development of a Rubber Soft Actuator Driven with Gas/Liquid Phase Change. <i>International Journal of Automation Technology, 2016,</i> 10, 517-524	0.8	5
144	Development of Electromagnetic Nutation Motor (Electromagnetic Investigation). <i>Journal of Robotics and Mechatronics, 2004,</i> 16, 327-332	0.7	5
143	New Robotics Pioneered by Fluid Power. <i>Journal of Robotics and Mechatronics, 2020,</i> 32, 854-862	0.7	5
142	Development of Micro Inspection Robot for Small Piping.. <i>Journal of the Robotics Society of Japan, 1999,</i> 17, 389-395	0.1	5
141	Bundled Wire Drive: Proposal and Feasibility Study of a Novel Tendon-Driven Mechanism Using Synthetic Fiber Ropes. <i>IEEE Robotics and Automation Letters, 2019,</i> 4, 966-972	4.2	5
140	New Hydraulic Components for Tough Robots. <i>Springer Tracts in Advanced Robotics, 2019,</i> 401-451	0.5	4
139	PF-IPMC: Paper/Fabric Assisted IPMC Actuators for 3D Crafts. <i>IEEE Robotics and Automation Letters, 2020,</i> 5, 4035-4041	4.2	4
138	A small three-way valve using particle excitation with piezoelectric transducers for hydraulic actuators. <i>Advanced Robotics, 2018,</i> 32, 500-510	1.7	4
137	Development of a hand rehabilitation system to prevent contracture for finger joints based on the therapy of occupational therapists (Massage a hand and range of motion exercises using pneumatic soft actuators). <i>Transactions of the JSME (in Japanese), 2014,</i> 80, TRANS0348-TRANS0348	0.2	4
136	Next-generation Actuators Leading New Robotics. <i>Journal of the Robotics Society of Japan, 2015,</i> 33, 656-659	0.1	4
135	Intelligent pneumatic assisted therapy on ankle rehabilitation <b>2015,</b>		4



134	Evaluation of generated micro droplets using micropore plates oscillated by ultrasonic torsional transducers. <i>Sensors and Actuators A: Physical</i> , <b>2012</b> , 185, 92-92	3.9	4
133	Evaluation of electro conductive film and strain gage as displacement sensor for pneumatic artificial muscle <b>2011</b> ,		4
132	Micro rubber structure realizing multi-legged passive walking -integration and miniaturization by micro rubber molding process- <b>2009</b> ,		4
131	Design and evaluation of low-profile micro ultrasonic motors using sector shaped piezoelectric vibrators <b>2008</b> ,		4
130	Pneumatic Valve Operated by Multiplex Pneumatic Transmission. <i>Journal of Advanced Mechanical Design, Systems and Manufacturing</i> , <b>2008</b> , 2, 222-229	0.6	4
129	New Pneumatic Rubber Leg Mechanism for Omnidirectional Locomotion. <i>International Journal of Automation Technology</i> , <b>2014</b> , 8, 222-230	0.8	4
128	A novel long-reach robot with propulsion through water-jet <b>2016</b> ,		4
127	Shape Recognition of a Tensegrity With Soft Sensor Threads and Artificial Muscles Using a Recurrent Neural Network. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 6228-6234	4.2	4
126	Soft Tensegrity Robot Driven by Thin Artificial Muscles for the Exploration of Unknown Spatial Configurations. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 7, 5349-5356	4.2	4
125	Predictive Functional Control with Observer (PFC-O) Design and Loading Effects Performance for a Pneumatic System. <i>Arabian Journal for Science and Engineering</i> , <b>2015</b> , 40, 633-643		3
124	. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 3058-3065	4.2	3
123	. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4042-4048	4.2	3
122	Optimization of orifice position in particle-excitation valve for proportional flow control. <i>ROBOMECH Journal</i> , <b>2017</b> , 4,	2.1	3
121	System Identification model for an Intelligent Pneumatic Actuator (IPA) system <b>2012</b> ,		3
120	An Ultrasonic Motor Using a Titanium Transducer for a Cryogenic Environment. <i>Japanese Journal of Applied Physics</i> , <b>2013</b> , 52, 07HE13	1.4	3
119	Expectations about New Actuators. <i>Nippon Kikai Gakkai Ronbunshu, C Hen/Transactions of the Japan Society of Mechanical Engineers, Part C</i> , <b>2011</b> , 77, 2412-2419		3
118	Experimental analysis on pneumatic flow control valve driven by PZT vibrator <b>2010</b> ,		3
117	<b>2011</b> ,		3

116	Design and Evaluation of Emulsion Generation Device Using Ultrasonic Vibration and Microchannel. <i>Japanese Journal of Applied Physics</i> , <b>2011</b> , 50, 07HE24	1.4	3
115	Pneumatic flow control valve using particle excitation by PZT transducer <b>2009</b> ,		3
114	Development of Active 80-faced Polyhedron for haptic physical human-machine interface <b>2009</b> ,		3
113	PD-Fuzzy Logic Controller Design for Position Control of Intelligent Pneumatic Actuator System. <i>Communications in Computer and Information Science</i> , <b>2012</b> , 288-295	0.3	3
112	Droplets generation in the flowing ambient liquid by using an ultrasonic torsional transducer <b>2012</b> ,		3
111	Fabrication and evaluation of various types of micro one-way valves through micro rubber molding process. <i>Journal of Mechanical Science and Technology</i> , <b>2010</b> , 24, 219-222	1.6	3
110	Analysis of the multi-balloon dielectric elastomer actuator for traveling wave motion. <i>Sensors and Actuators A: Physical</i> , <b>2021</b> , 113243	3.9	3
109	Droplets generation using micropore plate driven by Langevin type transducer		3
108	Development of Hiryu-II: A Long-Reach Articulated Modular Manipulator Driven by Thrusters. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4963-4969	4.2	3
107	A small three-way valve using particle excitation driven by a single piezoelectric transducer for hydraulic actuator. <i>Sensors and Actuators A: Physical</i> , <b>2020</b> , 316, 112363	3.9	3
106	A method to 3D print a programmable continuum actuator with single material using internal constraint. <i>Sensors and Actuators A: Physical</i> , <b>2021</b> , 324, 112674	3.9	3
105	Highly responsive and stable flow control valve using a PZT transducer <b>2016</b> ,		3
104	Soft Polymer-Electrolyte-Fuel-Cell Tube Realizing Air-Hose-Free Thin McKibben Muscles <b>2019</b> ,		3
103	Self-excitation pneumatic soft actuator inspired by vocal cords. <i>Sensors and Actuators A: Physical</i> , <b>2021</b> , 331, 112816	3.9	3
102	<b>2020</b> ,		2
101	Tendon-driven Elastic Telescopic Arm -Integration of Linear Motion and Bending Motion- <b>2020</b> ,		2
100	Hydraulic Control by Flow Control Valve Using Particle Excitation. <i>JFPS International Journal of Fluid Power System</i> , <b>2017</b> , 10, 38-46	0.3	2
99	Comparison between PFC and PID control system for tendon-driven balloon actuator <b>2013</b> ,		2

98	Proposal of tendon-driven elastic telescopic arm and initial bending experiment <b>2017</b> ,		2
97	System Identification and Embedded Controller Design for Pneumatic Actuator with Stiffness Characteristic. <i>Mathematical Problems in Engineering</i> , <b>2014</b> , 2014, 1-13	1.1	2
96	Generalized predictive controller using Bat algorithm for double acting pneumatic cylinder <b>2013</b> ,		2
95	Predictive Functional Control of Tendon-Driven Actuator Using Pneumatic Balloon. <i>Journal of Advanced Mechanical Design, Systems and Manufacturing</i> , <b>2013</b> , 7, 752-762	0.6	2
94	Development of Active Separation System for Slug Flow in Chemical Process. <i>Nippon Kikai Gakkai Ronbunshu, C Hen/Transactions of the Japan Society of Mechanical Engineers, Part C</i> , <b>2011</b> , 77, 1109-1118		2
93	A micro ultrasonic motor controlled by using a built-in micro magnetic encoder <b>2010</b> ,		2
92	A low-profile micro ultrasonic motor for NMR sample spinning in high magnetic field <b>2011</b> ,		2
91	Continuous air control using particle excitation valve <b>2011</b> ,		2
90	A cylindrical ultrasonic motor for NMR sample spinning in high magnetic field <b>2009</b> ,		2
89	Optimum design of pneumatic multi-chamber rubber tube actuator generating traveling deformation waves for colonoscope insertion <b>2008</b> ,		2
88	Development of Micro Rotary Reactor Causing Spiral Laminar Flow Interfaces. <i>IEEJ Transactions on Sensors and Micromachines</i> , <b>2007</b> , 127, 47-52	0.2	2
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