Kai-Yew Lum

List of Publications by Year in descending order

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393982 288905 2,199 112 19 40 citations h-index g-index papers 114 114 114 1738 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Combining Global and Local Surrogate Models to Accelerate Evolutionary Optimization. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2007, 37, 66-76.	3.3	319
2	Passive Actuators' Fault-Tolerant Control for Affine Nonlinear Systems. IEEE Transactions on Control Systems Technology, 2010, 18, 152-163.	3.2	196
3	Max-min surrogate-assisted evolutionary algorithm for robust design. IEEE Transactions on Evolutionary Computation, 2006, 10, 392-404.	7.5	174
4	Adaptive autocentering control for an active magnetic bearing supporting a rotor with unknown mass imbalance. IEEE Transactions on Control Systems Technology, 1996, 4, 587-597.	3.2	138
5	Design and implementation of an autonomous flight control law for a UAV helicopter. Automatica, 2009, 45, 2333-2338.	3.0	134
6	Multiagent Information Fusion and Cooperative Control in Target Search. IEEE Transactions on Control Systems Technology, 2013, 21, 1223-1235.	3.2	119
7	Adaptive unknown input observer approach for aircraft actuator fault detection and isolation. International Journal of Adaptive Control and Signal Processing, 2007, 21, 31-48.	2.3	115
8	A Robust Real-Time Embedded Vision System on an Unmanned Rotorcraft for Ground Target Following. IEEE Transactions on Industrial Electronics, 2012, 59, 1038-1049.	5.2	94
9	Design and implementation of a leader-follower cooperative control system for unmanned helicopters. Journal of Control Theory and Applications, 2010, 8, 61-68.	0.8	62
10	Hybrid evolutionary algorithm with Hermite radial basis function interpolants for computationally expensive adjoint solvers. Computational Optimization and Applications, 2008, 39, 97-119.	0.9	59
11	Online References Reshaping and Control Reallocation for Nonlinear Fault Tolerant Control. IEEE Transactions on Control Systems Technology, 2009, 17, 366-379.	3.2	56
12	Consensus of multiâ€agent systems with general linear dynamics via dynamic output feedback control. IET Control Theory and Applications, 2013, 7, 108-115.	1.2	52
13	Comprehensive Nonlinear Modeling of an Unmanned-Aerial-Vehicle Helicopter. , 2008, , .		37
14	Nonlinear Control Allocation for Non-Minimum Phase Systems. IEEE Transactions on Control Systems Technology, 2009, 17, 394-404.	3.2	37
15	Application of absolute stability theory to robust control against loss of actuator effectiveness. IET Control Theory and Applications, 2009, 3, 772-788.	1.2	35
16	Application of passivity and cascade structure to robust control against loss of actuator effectiveness. International Journal of Robust and Nonlinear Control, 2010, 20, 673-693.	2.1	34
17	Fault-tolerant flight tracking control with stuck faults. , 0, , .		31
18	Global stabilization of the spinning top with mass imbalance. Dynamical Systems, 1995, 10, 339-365.	0.7	28

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19	Adaptive Virtual Autobalancing for a Rigid Rotor With Unknown Mass Imbalance Supported by Magnetic Bearings. Journal of Vibration and Acoustics, Transactions of the ASME, 1998, 120, 557-570.	1.0	28
20	A brief overview on miniature fixed-wing unmanned aerial vehicles. , 2010, , .		27
21	Proportional Navigation With Delayed Line-of-Sight Rate. IEEE Transactions on Control Systems Technology, 2013, 21, 247-253.	3.2	26
22	Deep Learning for Landslide Recognition in Satellite Architecture. IEEE Access, 2020, 8, 143665-143678.	2.6	22
23	Constrained Nonlinear Finite-Time Control Allocation. Proceedings of the American Control Conference, 2007, , .	0.0	21
24	Adaptive control allocation for non-linear systems with internal dynamics. IET Control Theory and Applications, 2010, 4, 909-922.	1.2	20
25	A leader-follower formation flight control scheme for UAV helicopters. , 2008, , .		19
26	Development of a vision-based ground target detection and tracking system for a small unmanned helicopter. Science in China Series F: Information Sciences, 2009, 52, 2201-2215.	1.1	19
27	Comprehensive Nonlinear Modeling of a Miniature Unmanned Helicopter. Journal of the American Helicopter Society, 2012, 57, 1-13.	0.5	16
28	Global convergence of unconstrained and bound constrained surrogate-assisted evolutionary search in aerodynamic shape design. , 0, , .		14
29	Adaptive Autocentering Control for an Active Magnetic Bearing Supporting a Rotor with Unknown Mass Imbalance. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1996, 29, 5351-5356.	0.4	12
30	Generalized Serret-Andoyer Transformation and Applications for the Controlled Rigid Body. Journal of Dynamical and Control Systems, 1999, 9, 39-66.	0.4	11
31	Parameter estimation of ARX/NARX model: a neural network based method. , 0, , .		10
32	A gain-varying UIO approach with adaptive threshold for FDI of nonlinear F16 systems. Journal of Control Theory and Applications, 2010, 8, 317-325.	0.8	10
33	Comparisons among robust stability criteria for linear systems with affine parameter uncertainties. Automatica, 2007, 43, 491-498.	3.0	9
34	Design and experiment of data-driven modeling and flutter control of a prototype wing. Journal of Sound and Vibration, 2017, 398, 103-122.	2.1	9
35	Adaptive control for a discrete-time first-order nonlinear system with both parametric and non-parametric uncertainties., 2007,,.		8
36	Reduced-Order Based Flutter Analysis for Complex Aeroelastic Systems. , 2008, , .		8

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37	Gain-scheduled flight control via state feedback. , 0, , .		7
38	Integration and Implementation of a Low-cost and Vision-based UAV Tracking System., 2006,,.		7
39	Decentralized "¿½str";½m-Wittenmark Self-Tuning Regulator of a Multi-agent Uncertain Coupled ARMAX System. , 2007, , .		7
40	The Serret-Andoyer formalism in rigid-body dynamics: II. Geometry, stabilization, and control. Regular and Chaotic Dynamics, 2007, 12, 426-447.	0.3	7
41	WLS-based partially decentralized adaptive control for coupled ARMAX multi-agent dynamical system. , 2009, , .		7
42	Comments on "Quadratic stability and stabilization of dynamic interval systems". IEEE Transactions on Automatic Control, 2005, 50, 276-277.	3.6	6
43	Design and Implementation of a Fully Autonomous Flight Control System for a UAV Helicopter. , 2006, ,		6
44	Analysis of PNG Laws with LOS Angular Rate Delay. , 2007, , .		6
45	Observer-based Fault Detection for Piecewise Linear Systems: Discrete-time Cases. Control Applications (CCA), Proceedings of the IEEE International Conference on, 2007, , .	0.0	6
46	Flight Control Design Using Hierarchical Dynamic Inversion and Quasi-steady States., 2008,,.		6
47	Multidisciplinary Design of S-Shaped Intake. , 2008, , .		6
48	Flight control design with hierarchical dynamic inversion. , 2010, , .		6
49	Using BEMD in CNN to Identify Landslide in Satellite Image. , 2019, , .		6
50	S-Shaped Inlet Design Optimization Using the Adjoint Equation Method., 2006,,.		5
51	Airfoil Optimization Design of Drag Minimization with Lift Constraint Using Adjoint Equation Method. , 2006, , .		5
52	Output trajectory tracking for the PVTOL aircraft through control allocation. Control Applications (CCA), Proceedings of the IEEE International Conference on, 2007, , .	0.0	5
53	Adaptive nonlinear control allocation of non-minimum phase uncertain systems. , 2009, , .		5
54	Modeling and Control of a Small-Scale Hybrid Aircraft. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 10385-10390.	0.4	5

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55	GPS signal enhancement and attitude determination for a mini and low-cost unmanned aerial vehicle. Transactions of the Institute of Measurement and Control, 2011, 33, 665-682.	1.1	5
56	Reduced order flutter modeling based on the Hammerstein model with & amp; \pm x03BC; -Markov structure and correlation identification method., 2014,,.		5
57	Aeroelastic responses identification of a high-aspect-ratio flexible wing model and its active flutter suppression strategy., 2016,,.		5
58	Observer-based Fault Detection for Piecewise Linear Systems: Continuous-time Cases. Control Applications (CCA), Proceedings of the IEEE International Conference on, 2007, , .	0.0	4
59	Sliding Mode Guidance Law for Delayed LOS Rate Measurement. , 2008, , .		4
60	A Correlation Least-Squares Method for Hammerstein Model Identification with ARX and $1\frac{1}{4}$ -Markov Structures. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 11183-11189.	0.4	4
61	Fault Detection and Isolation of Nonlinear Systems: An Unknown Input Observer Approach With Sum-of-Squares Techniques. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2012, 134, .	0.9	4
62	An optimization approach to integrated aircraft-controller design. , 0, , .		3
63	Flight Control of VTOL Quadrotor Aircraft via Output Feedback. , 2010, , .		3
64	Identification of a Hammerstein model for wing flutter analysis using CFD data and correlation method. , 2010, , .		3
65	A robust vision system on an unmanned helicopter for ground target seeking and following. , 2010, , .		3
66	A novel Hâ^ \hat{z} UIO design for actuator FDI in finite frequency domain. International Journal of Control, Automation and Systems, 2011, 9, 601-605.	1.6	3
67	Adaptive Virtual Autobalancing for a Magnetic Rotor With Unknown Mass Imbalance: Part I â€" Static Balancing. , 1995, , .		3
68	Adaptive virtual autobalancing for a magnetic rotor with unknown dynamic imbalance. , 0, , .		2
69	Infinite-Dimensional Linearization and Extended Adjoint Method for Nonlinear Homing Loop Analysis. , 2003, , .		2
70	A SOS-based approach to residual generators for discrete-time polynomial nonlinear systems., 2007,,.		2
71	A novel UIO-based approach for fault detection and isolation in finite frequency domain. , 2009, , .		2
72	Analysis of proportional-navigation guidance law with delayed line-of-sight rate. , 2010, , .		2

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73	FDI UIOs with multiple considerations for flight systems: An LMI approach. , 2012, , .		2
74	Fuzzy grey sliding mode control for maximum power point tracking of photovoltaic systems. , 2013, , .		2
75	Reduced-order modeling and flutter suppression control of an experimental wing. , 2016, , .		2
76	A Serret-Andoyer transformation analysis for the controlled rigid body. , 0, , .		1
77	A CFD and CSD Interaction Algorithm for Complex Configurations. , 2002, , .		1
78	ROBUST STABILITY ANALYSIS OF LINEAR SYSTEMS WITH AFFINE PARAMETER UNCERTAINTIES. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2005, 38, 535-540.	0.4	1
79	Integrated-optimal design of airplane and flight control using genetic algorithms. , 2007, , .		1
80	Detectability in games of pursuit evasion with antagonizing players. , 2007, , .		1
81	Comments on "\$H_{infty}\$ Filtering for Fuzzy Singularly Perturbed Systems With Pole Placement Constraints: An LMI Approach. IEEE Transactions on Signal Processing, 2007, 55, 716-717.	3.2	1
82	A fault detection and diagnosis scheme for discrete nonlinear system using output probability density estimation. , $2008, , .$		1
83	Fault detection and isolation for nonlinear F16 models using a gain-varying UIO approach. , 2009, , .		1
84	A H-infinity Fault Detection and Diagnosis Scheme for Discrete Nonlinear System Using Output Probability Density Estimation. , 2009, , .		1
85	Observer-based nonlinear control allocation. , 2010, , .		1
86	Flutter-Boundary Prediction Using System Identification-Based Reduced-Order Aeroelasticity Analysis. , 2012, , .		1
87	Targets tracking by UAVs in an urban area. , 2013, , .		1
88	Investigation of the Rao-Blackwellized particle filter for two jump-Markov inertia measurement models. , 2013, , .		1
89	Jump-Markov process estimation based on distributed Rao-Blackwellized particle filter. , 2014, , .		1
90	Automated image tracking based on the CAMSHIFT algorithm with adaboost and target trajectory and size estimation. , 2014 , , .		1

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91	Simultaneous localization and mapping based on particle filter for sparse environment. , 2014, , .		1
92	Adaptive Virtual Autobalancing for a Magnetic Rotor With Unknown Mass Imbalance: Part II — Dynamic Balancing. , 1995, , .		1
93	Adaptive virtual autobalancing for a magnetic rotor with unknown mass imbalance. , 0, , .		O
94	Global stabilization of the spinning top with mass imbalance. , 0, , .		0
95	Robust stability and performance analysis for parameter dependent systems using mixed multipliers. , 0, , .		0
96	PASSIVATION-BASED INTEGRATED GUIDANCE AND CONTROL OF UNDERACTUATED MARINE CRAFT. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2007, 40, 147-152.	0.4	0
97	Joint aerodynamics and electromagnetics design of S-shaped intake using proper orthogonal decomposition method., 2008,,.		0
98	A fault diagnosis scheme for time-varying fault using output probability density estimation. , 2008, , .		0
99	Surveillance for a simply connected region: A one-center disk-covering problem. , 2010, , .		0
100	Extended blending techniques with applications in robust tracking control and fault-tolerant control. , $2010, , .$		0
101	FDI of disturbed nonlinear systems: A nonlinear UIO approach with SOS techniques. , 2010, , .		0
102	Hammerstein Model-Based Correlation UIO Method for Fault Detection of Nonlinear Flight Control Systems. , 2010, , .		0
103	Editorial: Special issue on Measurement & Estimation for Unmanned Navigation. Transactions of the Institute of Measurement and Control, 2011, 33, 647-649.	1.1	0
104	Servant robot navigation using gesture recognition and fuzzy logic sensor fusion., 2014,,.		0
105	Simulation study of homography-based vision-aided inertial navigation for aerial vehicles. , 2014, , .		0
106	Greetings from the general chairs and program chairs. , 2014, , .		0
107	Subsystem identification of reduced-order model for an aeroservo-elastic closed-loop system. , 2016, , .		0
108	Flutter Suppression for a Prototype Wing - Numerical Modeling, Control Law Design, and Experimental Results. , $2016,$, .		0

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109	Discussion on: New Energy-Based Nonlinear Controller for Hydraulic Piston Actuators. European Journal of Control, 2004, 10, 386-389.	1.6	0
110	CONSTRAINED OPTIMIZATION OF MULTILAYERED ANTI-REFLECTION COATINGS USING GENETIC ALGORITHMS. Advances in Natural Computation, 2004, , 603-622.	0.1	0
111	FUZZY-GREY REACHING LAW SLIDING MODE CONTROL FOR PHOTOVOLTAICS MAXIMUM POWER POINT TRACKING. Control and Intelligent Systems, 2014, 42, .	0.3	0
112	Identification of MIMO Hammerstein System Using Non-Stationary Separable Inputs. , 2020, , .		0