Mostafa Mohammadi

List of Publications by Year in descending order

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1684188 1872680 16 279 5 6 citations g-index h-index papers 16 16 16 325 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Aerial Tele-Manipulation with Passive Tool via Parallel Position/Force Control. Applied Sciences (Switzerland), 2021, 11, 8955.	2.5	4
2	The Tele-MAGMaS: An Aerial-Ground Comanipulator System. IEEE Robotics and Automation Magazine, 2018, 25, 66-75.	2.0	20
3	Shared planning and control for mobile robots with integral haptic feedback. International Journal of Robotics Research, 2018, 37, 1395-1420.	8.5	23
4	Autonomous Car Navigation Using Vector Fields. , 2018, , .		1
5	Towards robotic MAGMaS: Multiple aerial-ground manipulator systems. , 2017, , .		21
6	GESTO: A Glove for Enhanced Sensing and Touching Based on Inertial and Magnetic Sensors for Hand Tracking and Cutaneous Feedback. IEEE Transactions on Human-Machine Systems, 2017, 47, 1066-1076.	3. 5	61
7	Cooperative aerial tele-manipulation with haptic feedback. , 2016, , .		26
8	Fingertip force estimation via inertial and magnetic sensors in deformable object manipulation. , 2016, , .		11
9	Using inertial and magnetic sensors for hand tracking and rendering in wearable haptics. , 2015, , .		7
10	A force-based bilateral teleoperation framework for aerial robots in contact with the environment. , 2015, , .		20
11	Decentralized adaptive stabilization control for a quadrotor UAV. , 2013, , .		2
12	Modelling and decentralized adaptive tracking control of a quadrotor UAV. , 2013, , .		12
13	Stable adaptive time-variable delayed bilateral teleoperation for a surgery robot., 2013,,.		O
14	Adaptive Nonlinear Stabilization Control for a Quadrotor UAV: Theory, Simulation and Experimentation. Journal of Intelligent and Robotic Systems: Theory and Applications, 2013, 72, 105-122.	3.4	64
15	Modeling and Adaptive Tracking Control of a Quadrotor UAV. International Journal of Intelligent Mechatronics and Robotics, 2012, 2, 58-81.	0.4	7
16	Implementation considerations for enhancement of data acquisition in PMSM digital control system. , 2011, , .		0