

# Qing-Sheng Luo

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/5052649/publications.pdf>

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9  
papers

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citations

1937685

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2053705

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g-index

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docs citations

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citing authors

#	ARTICLE	IF	CITATIONS
1	An overview of hand-eye calibration. International Journal of Advanced Manufacturing Technology, 2022, 119, 77-97.	3.0	27
2	Model Predictive Control With Integral Compensation for Motion Control of Robot Manipulator in Joint and Task Spaces. IEEE Access, 2020, 8, 107063-107075.	4.2	17
3	A Planning Method for Multi-Axis Point-to-Point Synchronization Based on Time Constraints. IEEE Access, 2020, 8, 85575-85604.	4.2	10
4	Hand-Eye Calibration of EOD Robot by Solving the $AXB = YCZD$ Problem. IEEE Access, 2022, 10, 3415-3429.	4.2	5
5	Special Target Recognition and Location Using Differential Image Detection Technology. , 2010, , .		3
6	Optimizing Kinematic Modeling and Self-Collision Detection of a Mobile Manipulator Robot by Considering the Actual Physical Structure. Applied Sciences (Switzerland), 2021, 11, 10591.	2.5	2
7	Notice of Retraction: Design and research on support plate torsion spring of special electromechanical device. , 2011, , .		0
8	Characteristic analysis and sample modeling of cave depot target. , 2011, , .		0
9	Design Hybrid Iterative Learning Controller for Directly Driving the Wheels of Mobile Platform against Uncertain Parameters and Initial Errors. Applied Sciences (Switzerland), 2021, 11, 8181.	2.5	0