Liuyuan Deng

List of Publications by Year in descending order

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1478505 1474206 14 250 9 6 citations h-index g-index papers 14 14 14 193 docs citations times ranked citing authors all docs

#	Article	IF	Citations
1	Restricted Deformable Convolution-Based Road Scene Semantic Segmentation Using Surround View Cameras. IEEE Transactions on Intelligent Transportation Systems, 2020, 21, 4350-4362.	8.0	71
2	CNN based semantic segmentation for urban traffic scenes using fisheye camera., 2017,,.		70
3	Neutral Cross-Entropy Loss Based Unsupervised Domain Adaptation for Semantic Segmentation. IEEE Transactions on Image Processing, 2021, 30, 4516-4525.	9.8	24
4	Semantic Segmentation-Based Lane-Level Localization Using Around View Monitoring System. IEEE Sensors Journal, 2019, 19, 10077-10086.	4.7	21
5	Shadow Detection and Removal for Illumination Consistency on the Road. IEEE Transactions on Intelligent Vehicles, 2020, 5, 534-544.	12.7	20
6	Fusing geometrical and visual information via superpoints for the semantic segmentation of 3D road scenes. Tsinghua Science and Technology, 2020, 25, 498-507.	6.1	12
7	Gated-Residual Block for Semantic Segmentation Using RGB-D Data. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 11836-11844.	8.0	12
8	Shadow detection and removal for illumination consistency on the road., 2017,,.		6
9	An extended probabilistic self-localization algorithm using hybrid maps. , 2014, , .		4
10	A Terrain-Based Vehicle Localization Approach Robust to Braking. IEEE Transactions on Intelligent Transportation Systems, 2019, 20, 2923-2932.	8.0	4
11	G2P: a new descriptor for pedestrian detection. Neural Computing and Applications, 2020, 32, 4665-4674.	5.6	3
12	Stixel World Based Long-Term Object Tracking for Intelligent Driving. Communications in Computer and Information Science, 2017, , 113-118.	0.5	2
13	G2P: A new descriptor for pedestrian detection. , 2017, , .		1
14	Semantic Segmentation-Based Road Marking Detection Using Around View Monitoring System. Journal of Shanghai Jiaotong University (Science), 0, , 1.	0.9	0