

# Haiyan Zhao`

## List of Publications by Year in descending order

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Version: 2024-02-01

23  
papers

525  
citations

1307594

7  
h-index

1281871

11  
g-index

23  
all docs

23  
docs citations

23  
times ranked

456  
citing authors

#	ARTICLE	IF	CITATIONS
1	MPC-based yaw stability control in in-wheel-motored EV via active front steering and motor torque distribution. <i>Mechatronics</i> , 2016, 38, 103-114.	3.3	141
2	Integrated control of in-wheel motor electric vehicles using a triple-step nonlinear method. <i>Journal of the Franklin Institute</i> , 2015, 352, 519-540.	3.4	74
3	Model predictive control allocation for stability improvement of four-wheel drive electric vehicles in critical driving condition. <i>IET Control Theory and Applications</i> , 2015, 9, 2688-2696.	2.1	57
4	A Reduced-Order Nonlinear Clutch Pressure Observer for Automatic Transmission. <i>IEEE Transactions on Control Systems Technology</i> , 2010, 18, 446-453.	5.2	56
5	Modular Integrated Longitudinal, Lateral, and Vertical Vehicle Stability Control for Distributed Electric Vehicles. <i>IEEE Transactions on Vehicular Technology</i> , 2019, 68, 1327-1338.	6.3	50
6	MPC-Based Slip Ratio Control for Electric Vehicle Considering Road Roughness. <i>IEEE Access</i> , 2019, 7, 52405-52413.	4.2	28
7	Velocity Optimization for Braking Energy Management of In-Wheel Motor Electric Vehicles. <i>IEEE Access</i> , 2019, 7, 66410-66422.	4.2	25
8	A regenerative braking system for electric vehicle with four in-wheel motors based on fuzzy control. , 2017, , .		21
9	A regenerative braking control strategy for electric vehicle with four in-wheel motors. , 2016, , .		19
10	Estimation of Vehicle Yaw Rate and Side Slip Angle using Moving Horizon Strategy. , 2006, , .		15
11	Slip ratio estimation for electric vehicle with in-wheel motors based on EKF without detection of vehicle velocity. , 2016, , .		10
12	Coordinated Attitude Control of Longitudinal, Lateral and Vertical Tyre Forces for Electric Vehicles Based on Model Predictive Control. <i>IEEE Transactions on Vehicular Technology</i> , 2022, 71, 2550-2559.	6.3	7
13	MPC-based torque control of permanent magnet synchronous motor for electric vehicles via switching optimization. <i>Control Theory and Technology</i> , 2017, 15, 138-149.	1.6	4
14	A Feedback Linearization Control Scheme Based on Direct Torque Control for Permanent Magnet Synchronous Motor. , 2018, , .		4
15	A dynamic-decoupling controller of current for permanent magnet synchronous motor. , 2017, , .		3
16	Decision-Making Method of Autonomous Vehicles in Urban Environments Considering Traffic Laws. <i>IEEE Transactions on Intelligent Transportation Systems</i> , 2022, 23, 21641-21652.	8.0	3
17	Robust Moving Horizon Estimation for Constrained Linear System with Uncertainties. , 2007, , .		2
18	Integrated control of in-wheel-motored electric vehicles using a model predictive control method. , 2014, , .		2

#	ARTICLE	IF	CITATIONS
19	Nonlinear model predictive slip control based on vertical suspension system for an in-wheel-motored electric vehicle. , 2017, , .		1
20	Integrated Control of longitudinal-vertical Force for Distributed Electric Vehicles. , 2019, , .		1
21	Longitudinal-vertical integrated sliding mode controller for distributed electric vehicles. Science China Information Sciences, 2020, 63, 1.	4.3	1
22	Vehicle State Estimation Based on Recurrent Neural Network. , 2021, , .		1
23	A comprehensive intention prediction method considering vehicle interaction. , 2020, , .		0