

Xiuxian Li

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

36 papers	397 citations	11 h-index	19 g-index
45 ext. papers	595 ext. citations	5 avg, IF	4.77 L-index

#	Paper	IF	Citations
36	Ultra-Wideband and Odometry-Based Cooperative Relative Localization With Application to Multi-UAV Formation Control. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 2590-2603	10.2	67
35	l1-gain analysis and model reduction problem for Boolean control networks. <i>Information Sciences</i> , 2016 , 348, 68-83	7.7	42
34	Consensus networks with switching topology and time-delays over finite fields. <i>Automatica</i> , 2016 , 68, 39-43	5.7	33
33	Distributed Online Convex Optimization With Time-Varying Coupled Inequality Constraints. <i>IEEE Transactions on Signal Processing</i> , 2020 , 68, 731-746	4.8	28
32	Dynamic Formation Control Over Directed Networks Using Graphical Laplacian Approach. <i>IEEE Transactions on Automatic Control</i> , 2018 , 63, 3761-3774	5.9	26
31	Quantized Consensus of Multi-Agent Networks With Sampled Data and Markovian Interaction Links. <i>IEEE Transactions on Cybernetics</i> , 2019 , 49, 1816-1825	10.2	23
30	Flocking of networked Euler-Lagrange systems with uncertain parameters and time-delays under directed graphs. <i>Nonlinear Dynamics</i> , 2016 , 85, 415-424	5	19
29	Distributed Bounds on the Algebraic Connectivity of Graphs With Application to Agent Networks. <i>IEEE Transactions on Cybernetics</i> , 2017 , 47, 2121-2131	10.2	18
28	Finite-time consensus of second-order multi-agent systems via a structural approach. <i>Journal of the Franklin Institute</i> , 2016 , 353, 3876-3896	4	16
27	Simultaneous cooperative relative localization and distributed formation control for multiple UAVs. <i>Science China Information Sciences</i> , 2020 , 63, 1	3.4	14
26	Distributed Continuous-Time Nonsmooth Convex Optimization With Coupled Inequality Constraints. <i>IEEE Transactions on Control of Network Systems</i> , 2020 , 7, 74-84	4	12
25	Distributed continuous-time algorithm for a general nonsmooth monotropic optimization problem. <i>International Journal of Robust and Nonlinear Control</i> , 2019 , 29, 3252-3266	3.6	11
24	Distributed Online Optimization for Multi-Agent Networks With Coupled Inequality Constraints. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 3575-3591	5.9	11
23	Distributed Proximal Algorithms for Multiagent Optimization With Coupled Inequality Constraints. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 1223-1230	5.9	9
22	Synchronization of networks over finite fields. <i>Automatica</i> , 2020 , 115, 108877	5.7	8
21	Ratio-of-Distance Rigidity Theory With Application to Similar Formation Control. <i>IEEE Transactions on Automatic Control</i> , 2020 , 65, 2598-2611	5.9	8
20	Consensus networks with time-delays over finite fields. <i>International Journal of Control</i> , 2016 , 89, 1000-1008	7	7

19	Distributed Estimation Under Sensor Attacks: Linear and Nonlinear Measurement Models. <i>IEEE Transactions on Signal and Information Processing Over Networks</i> , 2021 , 7, 156-165	2.8	7
18	Preview-Based Discrete-Time Dynamic Formation Control Over Directed Networks via Matrix-Valued Laplacian. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 1251-1263	10.2	6
17	Distributed Nonlinear Estimation Over Unbalanced Directed Networks. <i>IEEE Transactions on Signal Processing</i> , 2020 , 68, 6212-6223	4.8	5
16	Barrier coverage by heterogeneous sensor network with input saturation 2017 ,		4
15	A matrix method to hypergraph transversal and covering problems with application in simplifying Boolean functions 2016 ,		3
14	Distributed Bandit Online Convex Optimization With Time-Varying Coupled Inequality Constraints. <i>IEEE Transactions on Automatic Control</i> , 2020 , 1-1	5.9	3
13	Distributed Algorithms for Computing a Common Fixed Point of a Group of Nonexpansive Operators. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 2130-2145	5.9	3
12	Distributed Aggregative Optimization over Multi-Agent Networks. <i>IEEE Transactions on Automatic Control</i> , 2021 , 1-1	5.9	3
11	A Distributed Proximal Primal-Dual Algorithm for Energy Management with Transmission Losses in Smart Grid. <i>IEEE Transactions on Industrial Informatics</i> , 2022 , 1-1	11.9	2
10	Distributed algorithms for computing a fixed point of multi-agent nonexpansive operators. <i>Automatica</i> , 2020 , 122, 109286	5.7	2
9	A novel approach to time-varying formation control 2017 ,		1
8	Distributed Online Convex Optimization with an Aggregative Variable. <i>IEEE Transactions on Control of Network Systems</i> , 2021 , 1-1	4	1
7	Ratio-of-Distance Rigidity in Distributed Formation Control 2018 ,		1
6	Exponential convergence of distributed optimization for heterogeneous linear multi-agent systems over unbalanced digraphs. <i>Automatica</i> , 2022 , 141, 110259	5.7	1
5	A Survey of ADAS Perceptions With Development in China. <i>IEEE Transactions on Intelligent Transportation Systems</i> , 2022 , 1-16	6.1	0
4	Stabilisation of non-linear DISS systems with uncertainty via encoded feedback. <i>IET Control Theory and Applications</i> , 2017 , 11, 732-739	2.5	
3	Distributed multi-robot sweep coverage for a region with unknown workload distribution. <i>Autonomous Intelligent Systems</i> , 2021 , 1, 1		
2	Recent advances on distributed online optimization. <i>Control Theory and Technology</i> , 2021 , 19, 153-156	1	

- 1 Robust flocking for non-identical second-order nonlinear multi-agent systems. *Autonomous Intelligent Systems*, **2021**, 1, 1