

Peter S Lum

List of Publications by Year in descending order

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Version: 2024-02-01

55
papers

3,824
citations

186209

28
h-index

206029

48
g-index

56
all docs

56
docs citations

56
times ranked

3131
citing authors

#	ARTICLE	IF	CITATIONS
1	A trade-off between kinematic and dynamic control of bimanual reaching in virtual reality. <i>Journal of Neurophysiology</i> , 2022, 127, 1279-1288.	0.9	2
2	Perceived effort affects choice of limb and reaction time of movements. <i>Journal of Neurophysiology</i> , 2021, 125, 63-73.	0.9	13
3	Clinical Test of a Wearable, High DOF, Spring Powered Hand Exoskeleton (HandSOME II). <i>IEEE Transactions on Neural Systems and Rehabilitation Engineering</i> , 2021, 29, 1877-1885.	2.7	11
4	Shoulder position and handedness differentially affect excitability and intracortical inhibition of hand muscles. <i>Experimental Brain Research</i> , 2021, 239, 1517-1530.	0.7	0
5	Tele-rehabilitation of upper-extremity hemiparesis after stroke: Proof-of-concept randomized controlled trial of in-home Constraint-Induced Movement therapy. <i>Restorative Neurology and Neuroscience</i> , 2021, 39, 303-318.	0.4	9
6	Pilot Test of Dosage Effects in HEXORR II for Robotic Hand Movement Therapy in Individuals With Chronic Stroke. <i>Frontiers in Rehabilitation Sciences</i> , 2021, 2, .	0.5	1
7	A tracking device for a wearable high-DOF passive hand exoskeleton. , 2021, 2021, 6643-6646.		4
8	Home-Based Therapy After Stroke Using the Hand Spring Operated Movement Enhancer (HandSOME II). <i>Frontiers in Neurobotics</i> , 2021, 15, 773477.	1.6	4
9	Conceptualizing the Experience of Exoskeletons in Home Hand Rehabilitation After Stroke. <i>Archives of Physical Medicine and Rehabilitation</i> , 2020, 101, e134-e135.	0.5	1
10	Characterizing upper extremity motor behavior in the first week after stroke. <i>PLoS ONE</i> , 2020, 15, e0221668.	1.1	19
11	HandMATE: Wearable Robotic Hand Exoskeleton and Integrated Android App for At Home Stroke Rehabilitation. , 2020, 2020, 4867-4872.		24
12	Conceptualization of Hand-TaPS to measure the subjective experience of dynamic hand orthoses in promoting functional recovery at home after stroke. <i>Technology and Disability</i> , 2020, 32, 285-294.	0.3	3
13	Improving Accelerometry-Based Measurement of Functional Use of the Upper Extremity After Stroke: Machine Learning Versus Counts Threshold Method. <i>Neurorehabilitation and Neural Repair</i> , 2020, 34, 1078-1087.	1.4	30
14	An Elbow Exoskeleton for Upper Limb Rehabilitation With Series Elastic Actuator and Cable-Driven Differential. <i>IEEE Transactions on Robotics</i> , 2019, 35, 1464-1474.	7.3	74
15	Pilot testing of the spring operated wearable enhancer for arm rehabilitation (SpringWear). <i>Journal of NeuroEngineering and Rehabilitation</i> , 2018, 15, 13.	2.4	20
16	Machine Learning Approaches to Predict Functional Upper Extremity Use in Individuals with Stroke. , 2018, , .		3
17	Robust Classification of Functional and Nonfunctional Arm Movement after Stroke Using a Single Wrist-Worn Sensor Device. , 2018, , .		5
18	Neural coupling between homologous muscles during bimanual tasks: effects of visual and somatosensory feedback. <i>Journal of Neurophysiology</i> , 2017, 117, 655-664.	0.9	9

#	ARTICLE	IF	CITATIONS
19	Home-Based Therapy After Stroke Using the Hand Spring Operated Movement Enhancer (HandSOME). IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2017, 25, 2305-2312.	2.7	48
20	Measuring Functional Arm Movement after Stroke Using a Single Wrist-Worn Sensor and Machine Learning. Journal of Stroke and Cerebrovascular Diseases, 2017, 26, 2880-2887.	0.7	56
21	Hand rehabilitation after stroke using a wearable, high DOF, spring powered exoskeleton. , 2016, 2016, 578-581.		23
22	Spring operated wearable enhancer for arm rehabilitation (SpringWear) after stroke. , 2016, 2016, 4893-4896.		7
23	Dynamic motor tracking is sensitive to subacute mTBI. Experimental Brain Research, 2016, 234, 3173-3184.	0.7	7
24	Using Wearable Sensors and Machine Learning Models to Separate Functional Upper Extremity Use From Walking-Associated Arm Movements. Archives of Physical Medicine and Rehabilitation, 2016, 97, 224-231.	0.5	32
25	Proximal arm kinematics affect grip force-load force coordination. Journal of Neurophysiology, 2015, 114, 2265-2277.	0.9	3
26	Internal models of upper limb prosthesis users when grasping and lifting a fragile object with their prosthetic limb. Experimental Brain Research, 2014, 232, 3785-3795.	0.7	36
27	Robotic Therapy Provides a Stimulus for Upper Limb Motor Recovery After Stroke That Is Complementary to and Distinct From Conventional Therapy. Neurorehabilitation and Neural Repair, 2014, 28, 367-376.	1.4	64
28	Concurrent neuromechanical and functional gains following upper-extremity power training post-stroke. Journal of NeuroEngineering and Rehabilitation, 2013, 10, 1.	2.4	138
29	Compensation for the intrinsic dynamics of the InMotion2 robot. Journal of Neuroscience Methods, 2013, 214, 15-20.	1.3	8
30	Poster 45 Telerehabilitation Versus Outpatient Delivery of Constraint-Induced Movement therapy: Update on a Randomized Controlled Trial. Archives of Physical Medicine and Rehabilitation, 2013, 94, e27-e28.	0.5	2
31	Clinical Effects of Using HEXORR (Hand Exoskeleton Rehabilitation Robot) for Movement Therapy in Stroke Rehabilitation. American Journal of Physical Medicine and Rehabilitation, 2013, 92, 947-958.	0.7	25
32	Cortical effects of repetitive finger flexion- vs. extension-resisted tracking movements: a TMS study. Journal of Neurophysiology, 2013, 109, 1009-1016.	0.9	18
33	Robotic Approaches for Rehabilitation of Hand Function After Stroke. American Journal of Physical Medicine and Rehabilitation, 2012, 91, S242-S254.	0.7	126
34	Characterization of Compensatory Trunk Movements During Prosthetic Upper Limb Reaching Tasks. Archives of Physical Medicine and Rehabilitation, 2012, 93, 2029-2034.	0.5	90
35	Hand Spring Operated Movement Enhancer (HandSOME): A Portable, Passive Hand Exoskeleton for Stroke Rehabilitation. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2011, 19, 391-399.	2.7	164
36	Development and pilot testing of HEXORR: Hand EXOskeleton Rehabilitation Robot. Journal of NeuroEngineering and Rehabilitation, 2010, 7, 36.	2.4	219

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37	Feedforward control strategies of subjects with transradial amputation in planar reaching. <i>Journal of Rehabilitation Research and Development</i> , 2010, 47, 201.	1.6	34
38	Gains in Upper Extremity Function After Stroke via Recovery or Compensation: Potential Differential Effects on Amount of Real-World Limb Use. <i>Topics in Stroke Rehabilitation</i> , 2009, 16, 237-253.	1.0	135
39	Improving backdrivability in geared rehabilitation robots. <i>Medical and Biological Engineering and Computing</i> , 2009, 47, 441-447.	1.6	57
40	Trans-radial upper extremity amputees are capable of adapting to a novel dynamic environment. <i>Experimental Brain Research</i> , 2008, 188, 589-601.	0.7	30
41	Effect of Training on Upper-Extremity Prosthetic Performance and Motor Learning: A Single-Case Study. <i>Archives of Physical Medicine and Rehabilitation</i> , 2008, 89, 1199-1204.	0.5	44
42	Greater reliance on impedance control in the nondominant arm compared with the dominant arm when adapting to a novel dynamic environment. <i>Experimental Brain Research</i> , 2007, 182, 567-577.	0.7	62
43	Cerebral palsy: New approaches to therapy. <i>Current Neurology and Neuroscience Reports</i> , 2007, 7, 147-155.	2.0	41
44	Combined Functional Task Practice and Dynamic High Intensity Resistance Training Promotes Recovery of Upper-extremity Motor Function in Post-stroke Hemiparesis. <i>Journal of Neurologic Physical Therapy</i> , 2006, 30, 99-115.	0.7	60
45	Activity-based therapies. <i>NeuroRx</i> , 2006, 3, 428-438.	6.0	72
46	A telerehabilitation approach to delivery of constraint-induced movement therapy. <i>Journal of Rehabilitation Research and Development</i> , 2006, 43, 391.	1.6	68
47	MIME robotic device for upper-limb neurorehabilitation in subacute stroke subjects: A follow-up study. <i>Journal of Rehabilitation Research and Development</i> , 2006, 43, 631.	1.6	381
48	Reliability of Dynamic Muscle Performance in the Hemiparetic Upper Limb. <i>Journal of Neurologic Physical Therapy</i> , 2005, 29, 9-17.	0.7	25
49	AutoCITE. <i>Stroke</i> , 2005, 36, 1301-1304.	1.0	115
50	Effects of velocity on maximal torque production in poststroke hemiparesis. <i>Muscle and Nerve</i> , 2004, 30, 732-742.	1.0	67
51	Evidence for strength imbalances as a significant contributor to abnormal synergies in hemiparetic subjects. <i>Muscle and Nerve</i> , 2003, 27, 211-221.	1.0	85
52	Robotic stroke therapy assistant. <i>Robotica</i> , 2003, 21, 33-44.	1.3	50
53	Robotic Devices for Movement Therapy After Stroke: Current Status and Challenges to Clinical Acceptance. <i>Topics in Stroke Rehabilitation</i> , 2002, 8, 40-53.	1.0	181
54	Robot-assisted movement training compared with conventional therapy techniques for the rehabilitation of upper-limb motor function after stroke. <i>Archives of Physical Medicine and Rehabilitation</i> , 2002, 83, 952-959.	0.5	993

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55	Human control of a simple two-hand grasp. <i>Biological Cybernetics</i> , 1992, 67, 553-564.	0.6	26