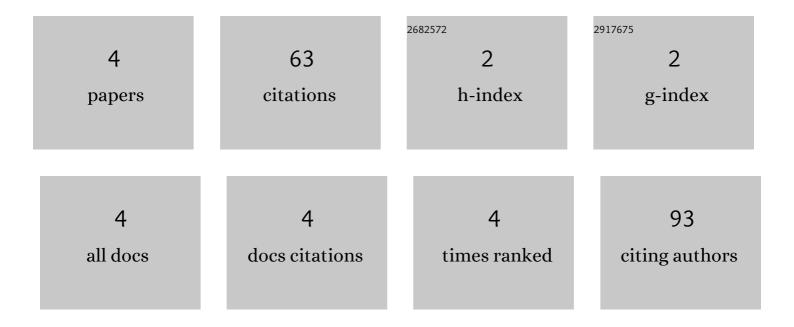
## Yunjeong Kim

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/4531008/publications.pdf Version: 2024-02-01



YUNIFONG KIM

#	Article	IF	CITATIONS
1	Global Trajectory Planning Based on DWMR Dynamics in Circular C-space. International Journal of Control, Automation and Systems, 2019, 17, 2624-2633.	2.7	0
2	Time-Optimal Trajectory Planning Based on Dynamics for Differential-Wheeled Mobile Robots With a Geometric Corridor. IEEE Transactions on Industrial Electronics, 2017, 64, 5502-5512.	7.9	41
3	Efficient time-optimal two-corner trajectory planning algorithm for differential-driven wheeled mobile robots with bounded motor control inputs. Robotics and Autonomous Systems, 2015, 64, 35-43.	5.1	21
4	Time-optimal cornering trajectory planning for differential-driven wheeled mobile robots with motor current and voltage constraints. , 2013, , .		1