

Yunjeong Kim

List of Publications by Year in descending order

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4
papers

63
citations

2682572
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4
docs citations

4
times ranked

93
citing authors

#	ARTICLE	IF	CITATIONS
1	Time-Optimal Trajectory Planning Based on Dynamics for Differential-Wheeled Mobile Robots With a Geometric Corridor. IEEE Transactions on Industrial Electronics, 2017, 64, 5502-5512.	7.9	41
2	Efficient time-optimal two-corner trajectory planning algorithm for differential-driven wheeled mobile robots with bounded motor control inputs. Robotics and Autonomous Systems, 2015, 64, 35-43.	5.1	21
3	Time-optimal cornering trajectory planning for differential-driven wheeled mobile robots with motor current and voltage constraints. , 2013, , .		1
4	Global Trajectory Planning Based on DWMR Dynamics in Circular C-space. International Journal of Control, Automation and Systems, 2019, 17, 2624-2633.	2.7	0