## Amos G Winter, V

List of Publications by Year in descending order

Source: https:||exaly.com/author-pdf/4383316/publications.pdf
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1 Justification for community-scale photovoltaic-powered electrodialysis desalination systems for inland rural villages in India. Desalination, 2014, 352, 82-91.
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A robust model of brackish water electrodialysis desalination with experimental comparison at
8.2 different size scales. Desalination, 2018, 443, 27-43.

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Localized fluidization burrowing mechanics of <i>Ensis directus</i>. Journal of Experimental Biology,
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2012, 215, 2072-2080.

Feasibility study of an electrodialysis system for in-home water desalination in urban India.
Development Engineering, 2017, 2, 38-46.
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The Effects of Prosthesis Inertial Properties on Prosthetic Knee Moment and Hip Energetics Required
5 to Achieve Able-Bodied Kinematics. IEEE Transactions on Neural Systems and Rehabilitation
$4.9 \quad 34$ Engineering, 2016, 24, 754-763.

6 Optimization and design of a low-cost, village-scale, photovoltaic-powered, electrodialysis reversal desalination system for rural India. Desalination, 2019, 452, 265-278.
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Cost-optimal design of a batch electrodialysis system for domestic desalination of brackish
$7 \quad \begin{aligned} & \text { Cost-optimal design of a batch electrodialysis sys } \\ & \text { groundwater. Desalination, 2018, 443, 198-211. }\end{aligned}$
$8 \quad$ Identification and Evaluation of the Atlantic Razor Clam (Ensis directus) for Biologically Inspired
8 Subsea Burrowing Systems. Integrative and Comparative Biology, 2011, 51, 151-157.

9 Field demonstration of a cost-optimized solar powered electrodialysis reversal desalination system in rural India. Desalination, 2020, 476, 114217.

Developing World Users as Lead Users: A Case Study in Engineering Reverse Innovation. Journal of
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Teaching RoboClam to Dig: The design, testing, and genetic algorithm optimization of a biomimetic
robot. , 2010, , .17 to Lower Leg Trajectory. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2018, 26,
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Design and Testing of a Prosthetic Foot With Interchangeable Custom Springs for Evaluating Lower
19 Leg Trajectory Error, an Optimization Metric for Prosthetic Feet. Journal of Mechanisms and Robotics,
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2018, 10, .
20 Experimental Demonstration of the Lower Leg Trajectory Error Framework Using Physiological Data as Inputs. Journal of Biomechanical Engineering, 2021, 143, .

Knee Swing Phase Flexion Resistance Affects Several Key Features of Leg Swing Important to Safe
21 Transfemoral Prosthetic Gait. IEEE Transactions on Neural Systems and Rehabilitation Engineering,
$4.9 \quad 6$
2021, 29, 965-973.

Control of Flow Limitation in Flexible Tubes. Journal of Mechanical Design, Transactions of the ASME, 2017, 139, .

23 Design of spiral-wound electrodialysis modules. Desalination, 2019, 458, 54-65.

Lower Leg Trajectory Error: A novel optimization parameter for designing passive prosthetic feet. , 2015, , .
25 Analytical model for predicting activation pressure and flow rate of pressure-compensating inline

drip emitters and its use in low-pressure emitter design. Irrigation Science, 2022, 40, $217-237$.$\quad$\begin{tabular}{l}
Biomechanical evaluation over level ground walking of user-specific prosthetic feet designed using <br>
the lower leg trajectory error framework. Scientific Reports, 2022, 12, 5306. <br>
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| Design of a Four-Bar Latch Mechanism and a Shear-Based Rotary Viscous Damper for Single-Axis |
| :--- |
| Prosthetic Knees. Journal of Mechanisms and Robotics, 2022, 14, . | <br>

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Modular Design of a Passive, Low-Cost Prosthetic Knee Mechanism to Enable Able-Bodied Kinematics <br>
for Users With Transfemoral Amputation. , 2017, , .
\end{tabular}

29 Passive Prosthetic Foot Shape and Size Optimization Using Lower Leg Trajectory Error. , 2017, , .

