Shaobing Xu

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/4371939/publications.pdf

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471371 610775 1,039 29 17 24 h-index citations g-index papers 29 29 29 729 citing authors docs citations times ranked all docs

| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | Design, Analysis, and Experiments of Preview Path Tracking Control for Autonomous Vehicles. IEEE Transactions on Intelligent Transportation Systems, 2020, 21, 48-58. | 4.7 | 188 |
| 2 | Eco-Departure of Connected Vehicles With V2X Communication at Signalized Intersections. IEEE Transactions on Vehicular Technology, 2015, 64, 5439-5449. | 3.9 | 107 |
| 3 | Fuel-Optimal Cruising Strategy for Road Vehicles With Step-Gear Mechanical Transmission. IEEE Transactions on Intelligent Transportation Systems, 2015, 16, 3496-3507. | 4.7 | 65 |
| 4 | Performance Enhanced Predictive Control for Adaptive Cruise Control System Considering Road Elevation Information. IEEE Transactions on Intelligent Vehicles, 2017, 2, 150-160. | 9.4 | 63 |
| 5 | Fuel-Saving Cruising Strategies for Parallel HEVs. IEEE Transactions on Vehicular Technology, 2016, 65, 4676-4686. | 3.9 | 55 |
| 6 | Preview Path Tracking Control With Delay Compensation for Autonomous Vehicles. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 2979-2989. | 4.7 | 54 |
| 7 | Instantaneous Feedback Control for a Fuel-Prioritized Vehicle Cruising System on Highways With a Varying Slope. IEEE Transactions on Intelligent Transportation Systems, 2017, 18, 1210-1220. | 4.7 | 45 |
| 8 | A Unified Pseudospectral Computational Framework for Optimal Control of Road Vehicles. IEEE/ASME Transactions on Mechatronics, 2015, 20, 1499-1510. | 3.7 | 42 |
| 9 | Design and Comparison of Fuel-Saving Speed Planning Algorithms for Automated Vehicles. IEEE Access, 2018, 6, 9070-9080. | 2.6 | 41 |
| 10 | Safety assessment of highly automated driving systems in test tracks: A new framework. Accident Analysis and Prevention, 2020, 144, 105664. | 3.0 | 37 |
| 11 | Highway Exiting Planner for Automated Vehicles Using Reinforcement Learning. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 990-1000. | 4.7 | 30 |
| 12 | An Augmented Reality Environment for Connected and Automated Vehicle Testing and Evaluation. , 2018, , . | | 29 |
| 13 | Accurate and Smooth Speed Control for an Autonomous Vehicle. , 2018, , . | | 28 |
| 14 | SUPER: A Novel Lane Detection System. IEEE Transactions on Intelligent Vehicles, 2021, 6, 583-593. | 9.4 | 27 |
| 15 | Eco-Driving Operation of Connected Vehicle With V2I Communication Among Multiple Signalized Intersections. IEEE Intelligent Transportation Systems Magazine, 2021, 13, 107-119. | 2.6 | 26 |
| 16 | Confidence-Aware Reinforcement Learning for Self-Driving Cars. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 7419-7430. | 4.7 | 26 |
| 17 | Integrated energy-oriented cruising control of electric vehicle on highway with varying slopes considering battery aging. Science China Technological Sciences, 2020, 63, 155-165. | 2.0 | 21 |
| 18 | Design and Experiments of Safeguard Protected Preview Lane Keeping Control for Autonomous Vehicles. IEEE Access, 2020, 8, 29944-29953. | 2.6 | 19 |

| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 19 | Trustworthy safety improvement for autonomous driving using reinforcement learning. Transportation Research Part C: Emerging Technologies, 2022, 138, 103656. | 3.9 | 18 |
| 20 | A geometry-driven car-following distance estimation algorithm robust to road slopes. Transportation Research Part C: Emerging Technologies, 2019, 102, 274-288. | 3.9 | 17 |
| 21 | System and Experiments of Model-Driven Motion Planning and Control for Autonomous Vehicles. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 5975-5988. | 5.9 | 16 |
| 22 | Design and Test of Speed Tracking Control for the Self-Driving Lincoln MKZ Platform. IEEE Transactions on Intelligent Vehicles, 2020, 5, 324-334. | 9.4 | 15 |
| 23 | Graph-Embedded Lane Detection. IEEE Transactions on Image Processing, 2021, 30, 2977-2988. | 6.0 | 15 |
| 24 | Legendre pseudospectral computation of optimal speed profiles for vehicle eco-driving system. , 2014, , . | | 14 |
| 25 | Efficient and accurate computation of model predictive control using pseudospectral discretization. Neurocomputing, 2016, 177, 363-372. | 3.5 | 14 |
| 26 | Periodicity based cruising control of passenger cars for optimized fuel consumption., 2014,,. | | 13 |
| 27 | Accurate Pseudospectral Optimization of Nonlinear Model Predictive Control for High-Performance Motion Planning. IEEE Transactions on Intelligent Vehicles, 2023, 8, 1034-1045. | 9.4 | 10 |
| 28 | Monocular Connected-Vehicle Position Estimation on Sloping and Uneven Roads. IEEE Intelligent Transportation Systems Magazine, 2022, 14, 228-241. | 2.6 | 4 |
| 29 | Fuel Economy Analysis of Periodic Cruise Control Strategies for Power-Split HEVs at Medium and Low Speed. , 0, , . | | 0 |