

Chuong Ngo

List of Publications by Year in descending order

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Version: 2024-02-01

22
papers

263
citations

1040056

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docs citations

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times ranked

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citing authors

#	ARTICLE	IF	CITATIONS
1	A Rotational Invariant Neural Network for Electrical Impedance Tomography Imaging without Reference Voltage: RF-REIM-NET. <i>Diagnostics</i> , 2022, 12, 777.	2.6	5
2	A Wearable, Multi-Frequency Device to Measure Muscle Activity Combining Simultaneous Electromyography and Electrical Impedance Myography. <i>Sensors</i> , 2022, 22, 1941.	3.8	9
3	Determination of the Geometric Parameters of Electrode Systems for Electrical Impedance Myography: A Preliminary Study. <i>Sensors</i> , 2022, 22, 97.	3.8	8
4	A Way of Bionic Control Based on EI, EMG, and FMG Signals. <i>Sensors</i> , 2022, 22, 152.	3.8	9
5	Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. <i>IEEE/ASME Transactions on Mechatronics</i> , 2021, 26, 2080-2091.	5.8	14
6	Design and First Operation of an Active Lower Limb Exoskeleton with Parallel Elastic Actuation. <i>Actuators</i> , 2021, 10, 75.	2.3	10
7	Model-Based Step Length Estimation Using a Pendant-Integrated Mobility Sensor. <i>IEEE Transactions on Neural Systems and Rehabilitation Engineering</i> , 2021, 29, 2655-2665.	4.9	6
8	Everyday Life Tremor Signal Processing in PD Patients using BSN. , 2021, , .		0
9	Impedance-Controlled Variable Stiffness Actuator for Lower Limb Robot Applications. <i>IEEE Transactions on Automation Science and Engineering</i> , 2020, 17, 991-1004.	5.2	59
10	Evaluation and Application of a Customizable Wireless Platform: A Body Sensor Network for Unobtrusive Gait Analysis in Everyday Life. <i>Sensors</i> , 2020, 20, 7325.	3.8	9
11	Estimation of Stride Time Variability in Unobtrusive Long-Term Monitoring Using Inertial Measurement Sensors. <i>IEEE Journal of Biomedical and Health Informatics</i> , 2020, 24, 1-1.	6.3	10
12	Conceptual design, modeling and control of a rigid parallel serial-elastic actuator. <i>Automatisierungstechnik</i> , 2020, 68, 410-422.	0.8	7
13	Implementation of LPV H _∞ Loop-Shaping Control for a Variable Stiffness Actuator. <i>IFAC-PapersOnLine</i> , 2020, 53, 10129-10134.	0.9	3
14	Object-oriented modeling of thoracic fluid balance to study cardiogenic pulmonary congestion in humans. <i>Computer Methods and Programs in Biomedicine</i> , 2019, 180, 104998.	4.7	5
15	Design and Analysis of a Clutched Parallel Elastic Actuator. <i>Actuators</i> , 2019, 8, 67.	2.3	12
16	Peak Detection Algorithm for Gait Segmentation in Long-Term Monitoring for Stride Time Estimation using Inertial Measurement Sensors. , 2019, , .		7
17	Flow-volume loops measured with electrical impedance tomography in pediatric patients with asthma. <i>Pediatric Pulmonology</i> , 2018, 53, 636-644.	2.0	14
18	An object-oriented computational model to study cardiopulmonary hemodynamic interactions in humans. <i>Computer Methods and Programs in Biomedicine</i> , 2018, 159, 167-183.	4.7	13

#	ARTICLE	IF	CITATIONS
19	Electrical impedance tomography as possible guidance for individual positioning of patients with multiple lung injury. <i>Clinical Respiratory Journal</i> , 2018, 12, 68-75.	1.6	10
20	Assessing regional lung mechanics by combining electrical impedance tomography and forced oscillation technique. <i>Biomedizinische Technik</i> , 2018, 63, 673-681.	0.8	5
21	Linearity of electrical impedance tomography during maximum effort breathing and forced expiration maneuvers. <i>Physiological Measurement</i> , 2017, 38, 77-86.	2.1	22
22	Global and regional lung function in cystic fibrosis measured by electrical impedance tomography. <i>Pediatric Pulmonology</i> , 2016, 51, 1191-1199.	2.0	26