Saba Al-Wais

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/4241483/publications.pdf

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| 8 papers | 163 citations | 1937457 4 h-index | 2272820 4 g-index |
|-------------|------------------|-------------------------|-------------------------|
| 8 | 8 | 8 | 219 |
| all docs | docs citations | times ranked | citing authors |

| # | Article | IF | CITATIONS |
|---|---|-----|-----------|
| 1 | Omnidirectional Robot Indoor Localisation using Two Pixy Cameras and Artificial Colour Code Signature Beacons., 2020,,. | | 1 |
| 2 | Label Self-Advised Support Vector Machine (LSA-SVM)—Automated Classification of Foot Drop Rehabilitation Case Study. Biosensors, 2019, 9, 114. | 2.3 | 5 |
| 3 | Improved Delay-Dependent Stability Criteria for Telerobotic Systems With Time-Varying Delays. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2018, 48, 2470-2484. | 5.9 | 22 |
| 4 | Robust Hâ^ž cost guaranteed integral sliding mode control for the synchronization problem of nonlinear tele-operation system with variable time-delay. ISA Transactions, 2018, 72, 25-36. | 3.1 | 20 |
| 5 | Stability analysis of nonlinear telerobotic systems with time-varying communication channel delays using general integral inequalities. Information Sciences, 2018, 465, 353-372. | 4.0 | 19 |
| 6 | H <inf>â^ž</inf> based state feedback robust controller for nonlinear tele-operation system with variable time-delays. , 2017, , . | | 1 |
| 7 | Integral Sliding Mode Controller for Trajectory Tracking of a Phantom Omni Robot. , 2016, , . | | 4 |
| 8 | Kinematic and dynamic modelling of UR5 manipulator. , 2016, , . | | 91 |