

# Jeongseob Lee

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/4239961/publications.pdf>

Version: 2024-02-01

4  
papers

155  
citations

3311381

1  
h-index

3475538

1  
g-index

4  
all docs

4  
docs citations

4  
times ranked

121  
citing authors

#	ARTICLE	IF	CITATIONS
1	ODAR: Aerial Manipulation Platform Enabling Omnidirectional Wrench Generation. IEEE/ASME Transactions on Mechatronics, 2018, 23, 1907-1918.	5.8	118
2	LASDRA: Large-Size Aerial Skeleton System with Distributed Rotor Actuation. , 2018, , .		36
3	User Interface Design for Semi-Autonomous Teleoperation of Manipulator-Stage System on Flexible Beam. , 2018, , .		1
4	Model-Free Optimal Estimation and Sensor Placement Framework for Elastic Kinematic Chain. , 2019, , .		0