Ben M Chen

List of Publications by Year
in descending order

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323 papers	8,497 citations	76196 40 h-index	74018 75 g-index
333 all docs	333 docs citations	333 times ranked	4543 citing authors

#	Article	IF	Citations
1	An analysis and design method for linear systems subject to actuator saturation and disturbance. Automatica, 2002, 38, 351-359.	3.0	709
2	SO-Net: Self-Organizing Network for Point Cloud Analysis. , 2018, , .		543
3	Analysis and design for discrete-time linear systems subject to actuator saturation. Systems and Control Letters, 2002, 45, 97-112.	1.3	401
4	Composite nonlinear feedback control for linear systems with input saturation: theory and an application. IEEE Transactions on Automatic Control, 2003, 48, 427-439.	3.6	378
5	Unmanned Rotorcraft Systems. Advances in Industrial Control, 2011, , .	0.4	213
6	Development of a web-based laboratory for control experiments on a coupled tank apparatus. IEEE Transactions on Education, 2001, 44, 76-86.	2.0	180
7	Design and implementation of an autonomous flight control law for a UAV helicopter. Automatica, 2009, 45, 2333-2338.	3.0	134
8	Modeling and Control of the Yaw Channel of a UAV Helicopter. IEEE Transactions on Industrial Electronics, 2008, 55, 3426-3434.	5.2	132
9	Design and implementation of a robust and nonlinear flight control system for an unmanned helicopter. Mechatronics, 2011, 21, 803-820.	2.0	127
10	A Hard-Disk-Drive Servo System Design Using Composite Nonlinear-Feedback Control With Optimal Nonlinear Gain Tuning Methods. IEEE Transactions on Industrial Electronics, 2010, 57, 1735-1745.	5.2	124
11	Robust and Hâˆž Control. Communications and Control Engineering, 2000, , .	1.0	122
12	An H/sub â^ž/ almost disturbance decoupling robust controller design for a piezoelectric bimorph actuator with hysteresis. IEEE Transactions on Control Systems Technology, 1999, 7, 160-174.	3.2	121
13	Structured H-Infinity Command and Control-Loop Design for Unmanned Helicopters. Journal of Guidance, Control, and Dynamics, 2008, 31, 1093-1102.	1.6	118
14	Hybrid three-dimensional formation control for unmanned helicopters. Automatica, 2013, 49, 424-433.	3.0	108
15	A web-based virtual laboratory on a frequency modulation experiment. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2001, 31, 295-303.	3.3	101
16	UAV LiDAR for below-canopy forest surveys. Journal of Unmanned Vehicle Systems, 2013, 01, 61-68.	0.6	98
17	Composite nonlinear control with state and measurement feedback for general multivariable systems with input saturation. Systems and Control Letters, 2005, 54, 455-469.	1.3	97
18	Modeling and compensation of nonlinearities and friction in a micro hard disk drive servo system with nonlinear feedback control. IEEE Transactions on Control Systems Technology, 2005, 13, 708-721.	3.2	97

#	Article	IF	Citations
19	A Robust Real-Time Embedded Vision System on an Unmanned Rotorcraft for Ground Target Following. IEEE Transactions on Industrial Electronics, 2012, 59, 1038-1049.	5.2	94
20	H-Infinity Static Output-feedback Control for Rotorcraft. Journal of Intelligent and Robotic Systems: Theory and Applications, 2009, 54, 629-646.	2.0	92
21	Improving Transient Performance in Tracking General References Using Composite Nonlinear Feedback Control and Its Application to High-Speed XY-Table Positioning Mechanism. IEEE Transactions on Industrial Electronics, 2007, 54, 1039-1051.	5.2	87
22	Linear Systems Theory. , 2004, , .		86
23	Perspective rectification of document images using fuzzy set and morphological operations. Image and Vision Computing, 2005, 23, 541-553.	2.7	86
24	Optimal sensor placement for target localisation and tracking in 2D and 3D. International Journal of Control, 2013, 86, 1687-1704.	1.2	86
25	Discrete-time composite nonlinear feedback control with an application in design of a hard disk drive servo system. IEEE Transactions on Control Systems Technology, 2003, 11, 16-23.	3.2	82
26	An output feedback H//sub infin// controller design for linear systems subject to sensor nonlinearities. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2003, 50, 914-921.	0.1	79
27	Design and implementation of a hardware-in-the-loop simulation system for small-scale UAV helicopters. Mechatronics, 2009, 19, 1057-1066.	2.0	78
28	Systematic design methodology and construction of UAV helicopters. Mechatronics, 2008, 18, 545-558.	2.0	68
29	Distributed control of angle-constrained cyclic formations using bearing-only measurements. Systems and Control Letters, 2014, 63, 12-24.	1.3	66
30	Design and implementation of a leader-follower cooperative control system for unmanned helicopters. Journal of Control Theory and Applications, 2010, 8, 61-68.	0.8	62
31	On improvement of transient performance in tracking control for a class of nonlinear systems with input saturation. Systems and Control Letters, 2006, 55, 132-138.	1.3	61
32	MLFcGAN: Multilevel Feature Fusion-Based Conditional GAN for Underwater Image Color Correction. IEEE Geoscience and Remote Sensing Letters, 2020, 17, 1488-1492.	1.4	61
33	Design and implementation of a hard disk drive servo system using robust and perfect tracking approach. IEEE Transactions on Control Systems Technology, 2001, 9, 221-233.	3.2	58
34	An overview on development of miniature unmanned rotorcraft systems. Frontiers of Electrical and Electronic Engineering in China: Selected Publications From Chinese Universities, 2010, 5, 1-14.	0.6	57
35	A Robust Real-Time Vision System for Autonomous Cargo Transfer by an Unmanned Helicopter. IEEE Transactions on Industrial Electronics, 2015, 62, 1210-1219.	5.2	57
36	Structural controllability of switched linear systems. Automatica, 2013, 49, 3531-3537.	3.0	56

#	Article	IF	Citations
37	Accurate 3D Localization for MAV Swarms by UWB and IMU Fusion. , 2018, , .		56
38	A reduced order observer based controller design for H/sub â^ž/-optimization. IEEE Transactions on Automatic Control, 1994, 39, 355-360.	3.6	55
39	Self-sensing actuation for nanopositioning and active-mode damping in dual-stage HDDs. IEEE/ASME Transactions on Mechatronics, 2006, 11, 328-338.	3.7	55
40	Development of a Real-time Onboard and Ground Station Software System for a UAV Helicopter. Journal of Aerospace Computing, Information, and Communication, 2007, 4, 933-955.	0.8	52
41	Design and implementation of a dual-stage actuated HDD servo system via composite nonlinear control approach. Mechatronics, 2004, 14, 965-988.	2.0	49
42	Theory of LTR for non-minimum phase systems, recoverable target loops, and recovery in a subspace Part 1. Analysis. International Journal of Control, 1991, 53, 1067-1115.	1.2	47
43	A new stable compensator design for exact and approximate loop transfer recovery. Automatica, 1991, 27, 257-280.	3.0	44
44	Modeling and Control System Design for a UAV Helicopter. , 2006, , .		43
45	Hybrid formation control of the Unmanned Aerial Vehicles. Mechatronics, 2011, 21, 886-898.	2.0	42
46	Graph-theoretic characterisations of structural controllability for multi-agent system with switching topology. International Journal of Control, 2013, 86, 222-231.	1.2	41
47	Google map aided visual navigation for UAVs in GPS-denied environment. , 2015, , .		38
48	Vision-Based Target Three-Dimensional Geolocation Using Unmanned Aerial Vehicles. IEEE Transactions on Industrial Electronics, 2018, 65, 8052-8061.	5.2	38
49	Comprehensive Nonlinear Modeling of an Unmanned-Aerial-Vehicle Helicopter. , 2008, , .		37
50	A robust online path planning approach in cluttered environments for micro rotorcraft drones. Control Theory and Technology, 2016, 14, 83-96.	1.0	37
51	A new approach to the design of mode switching control in hard disk drive servo systems. Control Engineering Practice, 2002, 10, 925-939.	3.2	36
52	Further results on almost disturbance decoupling with global asymptotic stability for nonlinear systems. Automatica, 1999, 35, 709-717.	3.0	35
53	Design and implementation of an unmanned aerial vehicle for autonomous firefighting missions. , 2016, , .		35
54	Deep learning for 2D scan matching and loop closure. , 2017, , .		35

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55	Autonomous Navigation of UAV in Foliage Environment. Journal of Intelligent and Robotic Systems: Theory and Applications, 2016, 84, 259-276.	2.0	34
56	Construction and parameterization of all static and dynamic H/sub 2/-optimal state feedback solutions, optimal fixed modes and fixed decoupling zeros. IEEE Transactions on Automatic Control, 1993, 38, 248-261.	3.6	33
57	Finite-time stabilisation of cyclic formations using bearing-only measurements. International Journal of Control, 2014, 87, 715-727.	1.2	33
58	Design and Implementation of a Flight Control System for an Unmanned Rotorcraft using <scp>RPT</scp> Control Approach. Asian Journal of Control, 2013, 15, 95-119.	1.9	32
59	IPMGAN: Integrating physical model and generative adversarial network for underwater image enhancement. Neurocomputing, 2021, 453, 538-551.	3.5	32
60	Multivehicle Flocking With Collision Avoidance via Distributed Model Predictive Control. IEEE Transactions on Cybernetics, 2021, 51, 2651-2662.	6.2	32
61	Systematic Design and Implementation of a Micro Unmanned Quadrotor System. Unmanned Systems, 2014, 02, 121-141.	2.7	31
62	Design and Implementation of a Hybrid UAV With Model-Based Flight Capabilities. IEEE/ASME Transactions on Mechatronics, 2018, 23, 1114-1125.	3.7	31
63	Hâˆž disturbance observer design for high precision track following in hard disk drives. IET Control Theory and Applications, 2009, 3, 1591-1598.	1.2	30
64	On Improving Transient Performance in Tracking Control for a Class of Nonlinear Discrete-Time Systems With Input Saturation. IEEE Transactions on Automatic Control, 2007, 52, 1307-1313.	3.6	29
65	Design and mathematical modeling of a 4-standard-propeller (4SP) quadrotor. , 2012, , .		29
66	Deep Learning Based Automatic Crack Detection and Segmentation for Unmanned Aerial Vehicle Inspections. , 2019, , .		29
67	Improving transient performance in tracking control for linear multivariable discrete-time systems with input saturation. Systems and Control Letters, 2007, 56, 25-33.	1.3	28
68	Vision-aided Estimation of Attitude, Velocity, and Inertial Measurement Bias for UAV Stabilization. Journal of Intelligent and Robotic Systems: Theory and Applications, 2016, 81, 531-549.	2.0	28
69	Full and reduced-order observer-based controller design forH2-optimization. International Journal of Control, 1993, 58, 803-834.	1.2	27
70	A brief overview on miniature fixed-wing unmanned aerial vehicles. , 2010, , .		27
71	A mono-camera and scanning laser range finder based UAV indoor navigation system. , 2013, , .		27
72	Simultaneous finite- and infinite-zero assignments of linear systems. Automatica, 1995, 31, 643-648.	3.0	26

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73	A Unified Control Scheme for Track Seeking and Following of a Hard Disk Drive Servo System. IEEE Transactions on Control Systems Technology, 2010, 18, 294-306.	3.2	26
74	Systems design and implementation with jerk-optimized trajectory generation for UAV calligraphy. Mechatronics, 2015, 30, 65-75.	2.0	26
75	System integration of a vision-guided UAV for autonomous landing on moving platform. , 2016, , .		25
76	Autonomous reconfigurable hybrid tail-sitter UAV U-Lion. Science China Information Sciences, 2017, 60, 1.	2.7	25
77	Model Predictive Local Motion Planning With Boundary State Constrained Primitives. IEEE Robotics and Automation Letters, 2019, 4, 3577-3584.	3.3	25
78	Explicit expressions for cascade factorization of general nonminimum phase systems. IEEE Transactions on Automatic Control, 1992, 37, 358-363.	3.6	24
79	On the problem of robust and perfect tracking for linear systems with external disturbances. International Journal of Control, 2001, 74, 158-174.	1.2	24
80	On the problem of general structural assignments of linear systems through sensor/actuator selection. Automatica, 2003, 39, 233-241.	3.0	24
81	On selection of nonlinear gain in composite nonlinear feedback control for a class of linear systems. , 2007, , .		24
82	Singular Perturbation Control for Vibration Rejection in HDDs Using the PZT Active Suspension as Fast Subsystem Observer. IEEE Industrial Electronics Magazine, 2007, 54, 1375-1386.	2.3	24
83	Drones for cooperative search and rescue in post-disaster situation. , 2015, , .		24
84	Linear systems toolkit in Matlab: structural decompositions and their applications. Journal of Control Theory and Applications, 2005, 3, 287-294.	0.8	23
85	Adaptive estimation and rejection of unknown sinusoidal disturbances through measurement feedback for a class of non-minimum phase non-linear MIMO systems. International Journal of Adaptive Control and Signal Processing, 2006, 20, 77-97.	2.3	23
86	Exact computation of the infimum in H/sub infinity /-optimization via output feedback. IEEE Transactions on Automatic Control, 1992, 37, 70-78.	3.6	22
87	On properties of the special coordinate basis of linear systems. International Journal of Control, 1998, 71, 981-1003.	1.2	22
88	A partition approach for the restoration of camera images of planar and curled document. Image and Vision Computing, 2006, 24, 837-848.	2.7	22
89	Vision-based formation for UAVs. , 2014, , .		22
90	Towards long-endurance flight: Design and implementation of a variable-pitch gasoline-engine quadrotor. , 2016, , .		22

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91	High-Precision Multi-UAV Teaming for the First Outdoor Night Show in Singapore. Unmanned Systems, 2018, 06, 39-65.	2.7	21
92	A Survey of Motion and Task Planning Techniques for Unmanned Multicopter Systems. Unmanned Systems, 2021, 09, 165-198.	2.7	21
93	FG-Net: A Fast and Accurate Framework for Large-Scale LiDAR Point Cloud Understanding. IEEE Transactions on Cybernetics, 2023, 53, 553-564.	6.2	20
94	A leader-follower formation flight control scheme for UAV helicopters. , 2008, , .		19
95	Development of a vision-based ground target detection and tracking system for a small unmanned helicopter. Science in China Series F: Information Sciences, 2009, 52, 2201-2215.	1.1	19
96	Autonomous navigation of UAV in forest. , 2014, , .		19
97	Necessary and sufficient conditions for a nonminimum phase plant to have a recoverable target loopâ€"A stable compensator design for LTR. Automatica, 1992, 28, 493-507.	3.0	18
98	A nonâ€recursive method for solving the general discreteâ€time riccati equations related to the H_{â^ž} control problem. International Journal of Robust and Nonlinear Control, 1994, 4, 503-519.	2.1	18
99	Design, fabrication, sensor fusion, and control of a micro Xâ€"Y stage media platform for probe-based storage systems. Mechatronics, 2009, 19, 1158-1168.	2.0	18
100	Development of an Unmanned Coaxial Rotorcraft for the DARPA UAVForge Challenge. Unmanned Systems, 2013, 01, 211-245.	2.7	18
101	A high fidelity simulator for a quadrotor UAV using ROS and Gazebo. , 2015, , .		18
102	Search and Rescue Using Multiple Drones in Post-Disaster Situation. Unmanned Systems, 2016, 04, 83-96.	2.7	18
103	Cooperative control of multiple unmanned aerial systems for heavy duty carrying. Annual Reviews in Control, 2018, 46, 44-57.	4.4	18
104	Thruster Allocation and Mapping of Aerial and Aquatic Modes for a Morphable Multimodal Quadrotor. IEEE/ASME Transactions on Mechatronics, 2020, 25, 2065-2074.	3.7	18
105	The discreteâ€time H_{â^ž} control problem with measurement feedback. International Journal of Robust and Nonlinear Control, 1994, 4, 457-479.	2.1	17
106	Robust and perfect tracking of discrete-time systems. Automatica, 2002, 38, 293-299.	3.0	17
107	Construction, modeling and control of a mini autonomous UAV helicopter. , 2008, , .		17
108	Discrete-time mode switching control with application to a PMSM position servo system. Mechatronics, 2013, 23, 1191-1201.	2.0	17

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109	An efficient UAV navigation solution for confined but partially known indoor environments. , 2014, , .		17
110	A Morphable Aerial-Aquatic Quadrotor with Coupled Symmetric Thrust Vectoring. , 2020, , .		17
111	Necessary and sufficient conditions under which anH2optimal control problem has a unique solution. International Journal of Control, 1993, 58, 337-348.	1.2	16
112	Mappings of the finite and infinite zero structures and invertibility structures of general linear multivariable systems under the bilinear transformation. Automatica, 1998, 34, 111-124.	3.0	16
113	Enhancement of GPS Signals for Automatic Control of a UAV Helicopter System. , 2007, , .		16
114	Comprehensive Nonlinear Modeling of a Miniature Unmanned Helicopter. Journal of the American Helicopter Society, 2012, 57, 1-13.	0.5	16
115	Guidance, navigation and control of an unmanned helicopter for automatic cargo transportation. , 2014, , .		16
116	Special Issue on Development of Autonomous Unmanned Aerial Vehicles. Mechatronics, 2011, 21, 763-764.	2.0	15
117	Hierarchical hybrid modelling and control of an unmanned helicopter. International Journal of Control, 2014, 87, 1779-1793.	1.2	15
118	Solvability conditions for disturbance decoupling problems with static measurement feedback. International Journal of Control, 1997, 68, 51-60.	1.2	14
119	Market turning points forecasting using wavelet analysis. Physica A: Statistical Mechanics and Its Applications, 2015, 437, 184-197.	1.2	14
120	Development of an Unmanned Helicopter for Vertical Replenishment. Unmanned Systems, 2015, 03, 63-87.	2.7	14
121	Toward Autonomy of Micro Aerial Vehicles in Unknown and Global Positioning System Denied Environments. IEEE Transactions on Industrial Electronics, 2021, 68, 7642-7651.	5.2	14
122	A non-iterative method for computing the infimum in Hâˆž -optimization. International Journal of Control, 1992, 56, 1399-1418.	1.2	13
123	Improvement of transient performance in tracking control for discrete-time systems with input saturation and disturbances. IET Control Theory and Applications, 2007, 1, 65-74.	1.2	13
124	A graph-theoretic characterization of structural controllability for multi-agent system with switching topology. , 2009, , .		13
125	Survey on the Development of Aerialâ€“Aquatic Hybrid Vehicles. Unmanned Systems, 2021, 09, 263-282.	2.7	13
126	A microdrive track following controller design using robust and perfect tracking control with nonlinear compensation. Mechatronics, 2005, 15, 933-948.	2.0	12

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127	Improved disturbance rejection with online adaptive pole-zero compensation on a Î¦-shaped PZT active suspension. Microsystem Technologies, 2009, 15, 1499-1508.	1.2	12
128	Multi-layer flight control synthesis and analysis of a small-scale UAV helicopter. , 2010, , .		12
129	Platform design and mathematical modeling of an ultralight quadrotor micro aerial vehicle. , 2013, , .		12
130	Design and Implementation of a Thrust-Vectored Unmanned Tail-Sitter with Reconfigurable Wings. Unmanned Systems, 2015, 03, 143-162.	2.7	12
131	Online schedule for autonomy of multiple unmanned aerial vehicles. Science China Information Sciences, 2017, 60, 1.	2.7	12
132	Safe navigation of quadrotors with jerk limited trajectory. Frontiers of Information Technology and Electronic Engineering, 2019, 20, 107-119.	1.5	12
133	Design of a Morphable Multirotor Aerial-Aquatic Vehicle. , 2019, , .		12
134	Smooth quadrotor trajectory generation for tracking a moving target in cluttered environments. Science China Information Sciences, 2021, 64, 1.	2.7	12
135	On the Trends of Autonomous Unmanned Systems Research. Engineering, 2022, 12, 20-23.	3.2	12
136	On blocking zeros and strong stabilizability of linear multivariable systems. Automatica, 1992, 28, 1051-1055.	3.0	11
137	A simple algorithm for the stable/unstable decomposition of a linear discrete-time system. International Journal of Control, 1995, 61, 255-260.	1.2	11
138	Design for general Hinfinity almost disturbance decoupling problem with measurement feedback and internal stability an eigenstructure assignment approach. International Journal of Control, 1998, 71, 653-685.	1.2	11
139	Attitude Control System Design for Unmanned Aerial Vehicles using H-Infinity and Loop-shaping Methods. , 2007, , .		11
140	Nonrepeatable Run-out Rejection Using Online Iterative Control for High-Density Data Storage. IEEE Transactions on Magnetics, 2007, 43, 2029-2037.	1.2	11
141	Design and implementation of a hardware-in-the-loop simulation system for small-scale UAV helicopters. , 2008, , .		11
142	Bisimilarity enforcing supervisory control for deterministic specifications. Automatica, 2014, 50, 287-290.	3.0	11
143	A lightweight autonomous MAV for indoor search and rescue. Asian Journal of Control, 2019, 21, 1732-1744.	1.9	11
144	Autonomous task planning and acting for micro aerial vehicles. , 2019, , .		11

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145	GTO-MPC-Based Target Chasing Using a Quadrotor in Cluttered Environments. IEEE Transactions on Industrial Electronics, 2022, 69, 6026-6035.	5.2	11
146	Closed-form solutions to a class of Hâˆž-optimization problems. International Journal of Control, 1994, 60, 41-70.	1.2	10
147	Solutions to general Hâˆž almost disturbance decoupling problem with measurement feedback and internal stability for discrete-time systems. Automatica, 2000, 36, 1103-1122.	3.0	10
148	Optimal deployment of mobile sensors for target tracking in 2D and 3D spaces. IEEE/CAA Journal of Automatica Sinica, 2014, 1, 24-30.	8.5	10
149	Monocular vision-based autonomous navigation system on a toy quadcopter in unknown environments. , 2015, , .		10
150	Survey of autopilot for multi-rotor unmanned aerial vehicles. , 2016, , .		10
151	WeakLabel3D-Net: A Complete Framework for Real-Scene LiDAR Point Clouds Weakly Supervised Multi-Tasks Understanding. , 2022, , .		10
152	A MATLAB toolkit for composite nonlinear feedback control â€" improving transient response in tracking control. Journal of Control Theory and Applications, 2010, 8, 271-279.	0.8	9
153	Optimal placement of bearing-only sensors for target localization. , 2012, , .		9
154	A bumpless hybrid supervisory control algorithm for the formation of unmanned helicopters. Mechatronics, 2013, 23, 677-688.	2.0	9
155	Motor-propeller Matching of Aerial Propulsion Systems for Direct Aerial-aquatic Operation. , 2019, , .		9
156	Non-iterative computation of infimum in discrete-time H âˆž-optimization and solvability conditions for the discrete-time disturbance decoupling problem. International Journal of Control, 1996, 65, 433-454.	1.2	8
157	Solvability conditions and solutions to perfect regulation problem under measurement output feedback. Systems and Control Letters, 2000, 40, 269-277.	1.3	8
158	Minimum-time trajectory planning for helicopter UAVs using computational dynamic optimization. , 2012, , .		8
159	Modeling and forecasting of stock markets under a system adaptation framework. Journal of Systems Science and Complexity, 2012, 25, 641-674.	1.6	8
160	Distributed control of angle-constrained circular formations using bearing-only measurements. , 2013, , .		8
161	Development of an unmanned tail-sitter with reconfigurable wings: U-Lion. , 2014, , .		8
162	Flight Control Law Using Composite Nonlinear Feedback Technique for a Mars Airplane. Journal of Guidance, Control, and Dynamics, 2016, 39, 2199-2204.	1.6	8

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163	Model-based optimal auto-transition and control synthesis for tail-sitter UAV KH-Lion. , 2017, , .		8
164	Complex system and intelligent control: theories and applications. Frontiers of Information Technology and Electronic Engineering, 2019, 20, 1-3.	1.5	8
165	A Memetic Algorithm for Curvature-Constrained Path Planning of Messenger UAV in Air-Ground Coordination. IEEE Transactions on Automation Science and Engineering, 2022, 19, 3735-3749.	3.4	8
166	GPU-Accelerated Incremental Euclidean Distance Transform for Online Motion Planning of Mobile Robots. IEEE Robotics and Automation Letters, 2022, 7, 6894-6901.	3.3	8
167	The discrete-time H/sub â^ž/ control problem with strictly proper measurement feedback. IEEE Transactions on Automatic Control, 1994, 39, 1936-1939.	3.6	7
168	Structural decomposition of linear singular systems: the single-input and single-output case. Systems and Control Letters, 2002, 47, 327-334.	1.3	7
169	Explicit Constructions of Global Stabilization Control Laws for a Class of Nonminimum Phase Nonlinear Systems. , 2006, , .		7
170	Explicit construction of <mml:math xmlns:mml="http://www.w3.org/1998/Math/MathML" altimg="si1.gif" display="inline" overflow="scroll"><mml:msub><mml:mrow><mml:mi>H</mml:mi></mml:mrow><mml:mrow><mml:mo>â^ž</mml:mo></mml:mrow></ control law for a class of nonminimum phase nonlinear systems. Automatica, 2008, 44, 738-744.	3.0	7
171	Minimum time control of helicopter UAVs using computational dynamic optimization. , 2011, , .		7
172	Null controllability of planar bimodal piecewise linear systems. International Journal of Control, 2011, 84, 766-782.	1.2	7
173	Identification of stock market forces in the system adaptation framework. Information Sciences, 2014, 265, 105-122.	4.0	7
174	Systematic Design Methodology and Construction of Micro Aerial Quadrotor Vehicles. , 2015, , 181-206.		7
175	Robust autonomous flight and mission management for MAVs in GPS-denied environments. , 2017, , .		7
176	Optimal Constrained Trajectory Generation for Quadrotors Through Smoothing Splines. , 2018, , .		7
177	Development of an Autonomous Unmanned Surface Vehicle with Object Detection Using Deep Learning. , 2018, , .		7
178	A modular mission management system for micro aerial vehicles. , 2018, , .		7
179	Decentralized MPC-Based Trajectory Generation for Multiple Quadrotors in Cluttered Environments. Research on World Agricultural Economy, 2021, 01, 2150007.	0.8	7
180	System Integration of a Vision-Guided UAV for Autonomous Tracking on Moving Platform in Low Illumination Condition. , 0, , .		7

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181	Solutions to disturbance decoupling problem with constant measurement feedback for linear systems. Automatica, 2000, 36, 1717-1724.	3.0	6
182	Comprehensive Modeling and Control of the Yaw Dynamics of a UAV Helicopter. , 2006, , .		6
183	Development of a comprehensive software system for implementing cooperative control of multiple unmanned aerial vehicles. , 2009, , .		6
184	Flight control design with hierarchical dynamic inversion. , 2010, , .		6
185	Graphic interpretations of structural controllability for switched linear systems. , 2010, , .		6
186	Wide area surveillance of urban environments using multiple Mini-VTOL UAVs. , 2015, , .		6
187	Vision-aided tracking of a moving ground vehicle with a hybrid UAV. , 2017, , .		6
188	Full envelope dynamics modeling and simulation for tail-sitter hybrid UAVs. , 2017, , .		6
189	A Lightweight Waterproof Casing for an Aquatic UAV using Rapid Prototyping. , 2020, , .		6
190	Closed-Loop Transfer Recovery with Observer-Based Controllers, Part 1: Analysis. Control and Dynamic Systems, 1992, , 247-293.	0.1	5
191	Symbolic realization of asymptotic time-scale and eigenstructure assignment design method in multivariable control. International Journal of Control, 2006, 79, 1471-1484.	1.2	5
192	Midfrequency Runout Compensation in Hard Disk Drives Via a Time-Varying Group Filtering Scheme. IEEE Transactions on Magnetics, 2008, 44, 4769-4779.	1.2	5
193	Autonomous Mini-UAV for indoor flight with embedded on-board vision processing as navigation system. , 2010, , .		5
194	GPS signal enhancement and attitude determination for a mini and low-cost unmanned aerial vehicle. Transactions of the Institute of Measurement and Control, 2011, 33, 665-682.	1.1	5
195	A customized fastslam algorithm using scanning laser range finder in structured indoor environments. , 2013, , .		5
196	Explicit model identification and control of a micro aerial vehicle. , 2014, , .		5
197	Nonlinear Flight Control Design for Maneuvering Flight of Quadrotors in High Speed and Large Acceleration. , 2018, , .		5
198	Systematic Modeling of Rotor-Driving Dynamics for Small Unmanned Aerial Vehicles. Unmanned Systems, 2018, 06, 81-93.	2.7	5

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199	Explicit solvability conditions for the general discrete-time H infinity almost disturbance decoupling problem with internal stability. International Journal of Systems Science, 1999, 30, 105-115.	3.7	4
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