## Hebah Elgibreen

List of Publications by Year in descending order

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Version: 2024-02-01

1684188 1474206 16 95 5 9 citations g-index h-index papers 16 16 16 44 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Deep Learning and Computer Vision for Estimating Date Fruits Type, Maturity Level, and Weight. IEEE Access, 2020, 8, 206770-206782.	4.2	27
2	A Review of Modern Audio Deepfake Detection Methods: Challenges and Future Directions. Algorithms, 2022, 15, 155.	2.1	21
3	Dynamic task allocation in an uncertain environment with heterogeneous multi-agents. Autonomous Robots, 2019, 43, 1639-1664.	4.8	12
4	RULES-IT: incremental transfer learning with RULES family. Frontiers of Computer Science, 2014, 8, 537-562.	2.4	7
5	Exploring the validity of learning styles as personalization parameters in eLearning environments: An eyetracking study. , 2010, , .		6
6	An Incremental Approach to Corpus Design and Construction: Application to a Large Contemporary Saudi Corpus. IEEE Access, 2021, 9, 88405-88428.	4.2	6
7	Multi Model Transfer Learning with RULES Family. Lecture Notes in Computer Science, 2013, , 42-56.	1.3	5
8	Inductive Learning for Continuous Classes and the Effect of RULES Family. International Journal of Information and Education Technology, 2015, 5, 564-570.	1.2	3
9	Chapter 5: Health Transformation in Saudi Arabia via Connected Health Technologies. , 2020, , 83-99.		2
10	Classifying Continuous Classes with Reinforcement Learning RULES. Lecture Notes in Computer Science, 2015, , 116-127.	1.3	2
11	Tide-Inspired Path Planning Algorithm for Autonomous Vehicles. Remote Sensing, 2021, 13, 4644.	4.0	2
12	Incremental transfer RULES with incomplete data. , 2014, , .		1
13	An Adaptive Epidemiology-Based Approach to Swarm Foraging with Dynamic Deadlines. Applied Sciences (Switzerland), 2021, 11, 4627.	2.5	1
14	Mining Pharmacy Database Using Evolutionary Genetic Algorithm. International Journal of Electronics and Telecommunications, 2010, 56, 427-432.	0.5	0
15	Adopting Relational Reinforcement Learning in Covering Algorithms for Numeric and Noisy Environments. International Journal of Computational Intelligence Systems, 2016, 9, 572-594.	2.7	O
16	Adaptive Self-Localization System for Low-Cost Autonomous Robot., 2021,,.		0