## Grzegorz Pajak

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/4143102/publications.pdf

Version: 2024-02-01

2682572 2053705 37 8 2 5 citations g-index h-index papers 8 8 8 40 citing authors docs citations times ranked all docs

#	Article	IF	CITATIONS
1	Motion Planning for a Mobile Humanoid Manipulator Working in an Industrial Environment. Applied Sciences (Switzerland), $2021$ , $11$ , $6209$ .	2.5	2
2	Point-to-Point Collision-Free Trajectory Planning for Mobile Manipulators. Journal of Intelligent and Robotic Systems: Theory and Applications, 2017, 85, 523-538.	3.4	14
3	Trajectory planning for mobile manipulators subject to control constraints. , 2017, , .		3
4	Planning of a point to point collision-free trajectory for mobile manipulators. , 2015, , .		5
5	Sub-optimal trajectory planning for mobile manipulators. Robotica, 2015, 33, 1181-1200.	1.9	9
6	Collision-Free Trajectory Planning for Mobile Manipulators Subject to Control Constraints. Archive of Mechanical Engineering, 2014, 61, 35-55.	0.7	2
7	Motion planning for mobile surgery assistant. Acta of Bioengineering and Biomechanics, 2014, 16, 11-20.	0.4	1
8	Trajectory planning for mobile manipulators with vibration reduction. Journal of Vibroengineering, 0, , .	1.0	1