

Grzegorz Pajak

List of Publications by Year in descending order

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8
papers

37
citations

2682572

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2053705

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8
all docs

8
docs citations

8
times ranked

40
citing authors

#	ARTICLE	IF	CITATIONS
1	Point-to-Point Collision-Free Trajectory Planning for Mobile Manipulators. Journal of Intelligent and Robotic Systems: Theory and Applications, 2017, 85, 523-538.	3.4	14
2	Sub-optimal trajectory planning for mobile manipulators. Robotica, 2015, 33, 1181-1200.	1.9	9
3	Planning of a point to point collision-free trajectory for mobile manipulators. , 2015, , .		5
4	Trajectory planning for mobile manipulators subject to control constraints. , 2017, , .		3
5	Collision-Free Trajectory Planning for Mobile Manipulators Subject to Control Constraints. Archive of Mechanical Engineering, 2014, 61, 35-55.	0.7	2
6	Motion Planning for a Mobile Humanoid Manipulator Working in an Industrial Environment. Applied Sciences (Switzerland), 2021, 11, 6209.	2.5	2
7	Trajectory planning for mobile manipulators with vibration reduction. Journal of Vibroengineering, 0, , .	1.0	1
8	Motion planning for mobile surgery assistant. Acta of Bioengineering and Biomechanics, 2014, 16, 11-20.	0.4	1