

# Li Ding

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/4125696/publications.pdf>

Version: 2024-02-01

11  
papers

133  
citations

1684188

5  
h-index

1372567

10  
g-index

11  
all docs

11  
docs citations

11  
times ranked

118  
citing authors

#	ARTICLE	IF	CITATIONS
1	Kinematic Reliability Analysis of a 7-DOF Redundant Robot. <i>Journal of Robotics</i> , 2022, 2022, 1-11.	0.9	0
2	Optimal attitude tracking control for an unmanned aerial quadrotor under lumped disturbances. <i>International Journal of Micro Air Vehicles</i> , 2020, 12, 175682932092356.	1.3	4
3	Dynamical Model Identification for a Small-Scale Unmanned Helicopter Using an Integrated Approach. <i>International Journal of Aerospace Engineering</i> , 2019, 2019, 1-11.	0.9	1
4	Dynamical Modelling and Robust Control for an Unmanned Aerial Robot Using Hexarotor with 2-DOF Manipulator. <i>International Journal of Aerospace Engineering</i> , 2019, 2019, 1-12.	0.9	2
5	Dynamic Decoupling Control Optimization for a Small-Scale Unmanned Helicopter. <i>Journal of Robotics</i> , 2018, 2018, 1-12.	0.9	6
6	A Robust Control for an Aerial Robot Quadrotor under Wind Gusts. <i>Journal of Robotics</i> , 2018, 2018, 1-8.	0.9	17
7	Nonlinear Friction and Dynamical Identification for a Robot Manipulator with Improved Cuckoo Search Algorithm. <i>Journal of Robotics</i> , 2018, 2018, 1-10.	0.9	18
8	A hybrid high-performance trajectory tracking controller for unmanned hexrotor with disturbance rejection. <i>Transactions of the Canadian Society for Mechanical Engineering</i> , 2018, 42, 239-251.	0.8	5
9	Yaw control of an unmanned aerial vehicle helicopter using linear active disturbance rejection control. <i>Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering</i> , 2017, 231, 427-435.	1.0	8
10	Dynamic Model Identification for 6-DOF Industrial Robots. <i>Journal of Robotics</i> , 2015, 2015, 1-9.	0.9	39
11	Chaotic Artificial Bee Colony Algorithm for System Identification of a Small-Scale Unmanned Helicopter. <i>International Journal of Aerospace Engineering</i> , 2015, 2015, 1-11.	0.9	33