## Nicole Gehring

## List of Publications by Year

 in descending orderSource: https:/|exaly.com/author-pdf/4087626/publications.pdf
Version: 2024-02-01

5.0

54

Output feedback control of general linear heterodirectional hyperbolic PDE-ODE systems with
1.9

27
spatially-varying coefficients. International Journal of Control, 2019, 92, 2274-2290.
2

Output Feedback Control of Coupled Linear Parabolic ODEâ€"PDEâ€"ODE Systems. IEEE Transactions on
5.7

Automatic Control, 2021, 66, 4668-4683.

Backstepping Control of Linear 2 Ã- 2 Hyperbolic Systems with Dynamic Boundary Conditions.
0.9

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IFAC-PapersOnLine, 2017, 50, 4522-4527.

An Algebraic Approach to the Identification of Linear Systems with Fractional Derivatives.
IFAC-PapersOnLine, 2017, 50, 6214-6219.
$0.9 \quad 9$

Controllability and prediction-free control of coupled transport processes viewed as linear systems
6 with distributed delays. IFAC Postprint Volumes IPPV | International Federation of Automatic Control 2013, 46, 13-18.

7 Flatness-Based Output Feedback Tracking Control of a Hyperbolic Distributed-Parameter System. , 2022,
7 6, 992-997.

8 Parameter identification, fault detection and localization for an electrical transmission line. , 2016, , .
Fractional-order model identification for state of health assessment of solid-oxide fuel cells.
IFAC-PapersOnLine, 2018, 51, 849-854. $\quad 0.9$

$$
\begin{aligned}
& 11 \text { Observer design for } 2 \tilde{A}-2 \text { linear hyperbolic PDEs that are bidirectionally coupled with nonlinear ODEs. } \\
& , 2021,, .
\end{aligned}
$$

Prediction-free tracking control for systems with incommensurate lumped and distributed delays:

| 12 Two examples*. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, | 0.4 |
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| $37-42$. |  |

Algebraic identification of heavy rope parameters. IFAC Postprint Volumes IPPV / International
Federation of Automatic Control, 2012, 45, 161-166. $\quad 0.4$

15 An algebraic algorithm for parameter identification in a class of systems described by linear partial
$0.2 \quad 2$
differential equations. Proceedings in Applied Mathematics and Mechanics, 2016, 16, 39-42.

Flatness-based tracking control for a pneumatic system with distributed parameters.
IFAC-PapersOnLine, 2018, 51, 487-492.

Control of Linear Delay Systems: An Approach without Explicit Predictions. Advances in Delays and
Dynamics, 2014, , 17-30.

