

# Quang Dan Le

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/4060164/publications.pdf>

Version: 2024-02-01

6  
papers

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citations

2258059

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2053705

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#	ARTICLE	IF	CITATIONS
1	Implementation of sensorless contact force estimation in collaborative robot based on adaptive third-order sliding mode observer. <i>Systems Science and Control Engineering</i> , 2022, 10, 507-516.	3.1	3
2	An Active Fault-Tolerant Control Based on Synchronous Fast Terminal Sliding Mode for a Robot Manipulator. <i>Actuators</i> , 2022, 11, 195.	2.3	2
3	Finite-Time Fault-Tolerant Control for a Robot Manipulator Based on Synchronous Terminal Sliding Mode Control. <i>Applied Sciences (Switzerland)</i> , 2020, 10, 2998.	2.5	17
4	Implementation of Fault-Tolerant Control for a Robot Manipulator Based on Synchronous Sliding Mode Control. <i>Applied Sciences (Switzerland)</i> , 2020, 10, 2534.	2.5	17
5	A neural network-based synchronized computed torque controller for three degree-of-freedom planar parallel manipulators with uncertainties compensation. <i>International Journal of Advanced Robotic Systems</i> , 2018, 15, 172988141876730.	2.1	15
6	Real Implementation of Fault-Tolerant Sliding Mode Control for a Robot Manipulator. , 2018, , .		0