

Quang Dan Le

List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Finite-Time Fault-Tolerant Control for a Robot Manipulator Based on Synchronous Terminal Sliding Mode Control. Applied Sciences (Switzerland), 2020, 10, 2998.	2.5	17
2	Implementation of Fault-Tolerant Control for a Robot Manipulator Based on Synchronous Sliding Mode Control. Applied Sciences (Switzerland), 2020, 10, 2534.	2.5	17
3	A neural network-based synchronized computed torque controller for three degree-of-freedom planar parallel manipulators with uncertainties compensation. International Journal of Advanced Robotic Systems, 2018, 15, 172988141876730.	2.1	15
4	Implementation of sensorless contact force estimation in collaborative robot based on adaptive third-order sliding mode observer. Systems Science and Control Engineering, 2022, 10, 507-516.	3.1	3
5	An Active Fault-Tolerant Control Based on Synchronous Fast Terminal Sliding Mode for a Robot Manipulator. Actuators, 2022, 11, 195.	2.3	2
6	Real Implementation of Fault-Tolerant Sliding Mode Control for a Robot Manipulator. , 2018, , .		0