Xiang-Gui Guo

List of Publications by Year in descending order

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331538 360920 1,251 68 21 35 h-index g-index citations papers 69 69 69 783 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Distributed Adaptive Integrated-Sliding-Mode Controller Synthesis for String Stability of Vehicle Platoons. IEEE Transactions on Intelligent Transportation Systems, 2016, 17, 2419-2429.	4.7	164
2	Distributed Adaptive Sliding Mode Control Strategy for Vehicle-Following Systems With Nonlinear Acceleration Uncertainties. IEEE Transactions on Vehicular Technology, 2017, 66, 981-991.	3.9	103
3	CNN-Based Distributed Adaptive Control for Vehicle-Following Platoon With Input Saturation. IEEE Transactions on Intelligent Transportation Systems, 2018, 19, 3121-3132.	4.7	91
4	Event-Triggered Adaptive Fault-Tolerant Pinning Control for Cluster Consensus of Heterogeneous Nonlinear Multi-Agent Systems Under Aperiodic DoS Attacks. IEEE Transactions on Network Science and Engineering, 2021, 8, 1941-1956.	4.1	81
5	Adaptive Event-Triggered Fault Detection for Interval Type-2 Tâ€"S Fuzzy Systems With Sensor Saturation. IEEE Transactions on Fuzzy Systems, 2021, 29, 2310-2321.	6.5	66
6	Adaptive fuzzy faultâ€tolerant control for multiple highâ€speed trains with proportional and integralâ€based sliding mode. IET Control Theory and Applications, 2017, 11, 1234-1244.	1.2	55
7	Distributed neuroadaptive fault-tolerant sliding-mode control for 2-D plane vehicular platoon systems with spacing constraints and unknown direction faults. Automatica, 2021, 129, 109675.	3.0	51
8	Quantized \$H_{infty}\$ Consensus of Multiagent Systems With Quantization Mismatch Under Switching Weighted Topologies. IEEE Transactions on Control of Network Systems, 2017, 4, 202-212.	2.4	47
9	Neuroadaptive quantized PID slidingâ€mode control for heterogeneous vehicular platoon with unknown actuator deadzone. International Journal of Robust and Nonlinear Control, 2019, 29, 188-208.	2.1	41
10	Insensitive <mml:math altimg="si36.gif" display="inline" overflow="scroll" xmlns:mml="http://www.w3.org/1998/Math/MathML"><mml:msub><mml:mrow><mml:mi>H</mml:mi></mml:mrow><mml:mrow><mml:mi>a^zfilter design for continuous-time systems with respect to filter coefficient variations. Automatica, 2010, 46, 1860-1869.</mml:mi></mml:mrow></mml:msub></mml:math>	നി :ങ ひ ന</td <td>ıml37ırow></td>	ım l37 ırow>
11	Quantized insensitive consensus of Lipschitz nonlinear multi-agent systems using the incidence matrix. Journal of the Franklin Institute, 2015, 352, 4845-4863.	1.9	35
12	Event-Triggered Switching-Type Fault Detection and Isolation for Fuzzy Control Systems Under DoS Attacks. IEEE Transactions on Fuzzy Systems, 2021, 29, 3401-3414.	6. 5	35
13	Reliable <i>H</i> _{âî} filter design for a class of discreteâ€time nonlinear systems with timeâ€varying delay. Optimal Control Applications and Methods, 2010, 31, 303-322.	1.3	31
14	Multiple-fault diagnosis for spacecraft attitude control systems using RBFNN-based observers. Aerospace Science and Technology, 2020, 106, 106195.	2.5	29
15	Adaptive Fault-Tolerant Pseudo-PID Sliding-Mode Control for High-Speed Train With Integral Quadratic Constraints and Actuator Saturation. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 7421-7431.	4.7	29
16	Non-fragile Hâ^ž Filter Design for Delta Operator Formulated Systems with Circular Region Pole Constraints: an LMI Optimization Approach. Zidonghua Xuebao/Acta Automatica Sinica, 2009, 35, 1209-1215.	1.5	27
17	Event-Triggered Observer-Based \$mathcal {H}_infty\$ Consensus Control and Fault Detection of Multiagent Systems Under Stochastic False Data Injection Attacks. IEEE Transactions on Network Science and Engineering, 2022, 9, 481-494.	4.1	26
18	Fully Distributed Adaptive Fault-Tolerant Sliding-Mode Control for Nonlinear Leader-Following Multiagent Systems With ANASs and IQCs. IEEE Transactions on Cybernetics, 2022, 52, 2763-2774.	6.2	25

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19	Hâ^ž filter design for delta operator formulated systems with low sensitivity to filter coefficient variations. IET Control Theory and Applications, 2011, 5, 1677-1688.	1.2	23
20	Delay-dependent reliable <i>H</i> _{â^ž} filtering for sector-bounded nonlinear continuous-time systems with time-varying state delays and sensor failures. International Journal of Systems Science, 2012, 43, 117-131.	3.7	23
21	Non-fragile H _{â^ž} Filter Design for Delta Operator Formulated Systems with Circular Region Pole Constraints: an LMI Optimization Approach. Zidonghua Xuebao/Acta Automatica Sinica, 2009, 35, 1209-1215.	0.3	23
22	BLF-Based Neuroadaptive Fault-Tolerant Control for Nonlinear Vehicular Platoon With Time-Varying Fault Directions and Distance Restrictions. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 12388-12398.	4.7	20
23	Distributed adaptive control for vehicular platoon with unknown deadâ€zone inputs and velocity/acceleration disturbances. International Journal of Robust and Nonlinear Control, 2017, 27, 2961-2981.	2.1	17
24	Reliable Hâ^ž Filter Design for Discrete-time Systems with Sector-bounded Nonlinearities: an LMI Optimization Approach. Zidonghua Xuebao/Acta Automatica Sinica, 2009, 35, 1347-1351.	0.3	17
25	Reliable Hâ^ž Filter Design for Discrete-time Systems with Sector-bounded Nonlinearities: an LMI Optimization Approach. Zidonghua Xuebao/Acta Automatica Sinica, 2009, 35, 1347-1351.	1.5	16
26	Adaptive quantised observerâ€based output feedback control for nonâ€linear systems with input and output quantisation. IET Control Theory and Applications, 2017, 11, 263-272.	1.2	15
27	Non-fragile quantized Hâ^ž output feedback control for nonlinear systems with quantized inputs and outputs. Journal of the Franklin Institute, 2017, 354, 415-438.	1.9	12
28	Novel auxiliary saturation compensation design for neuroadaptive NTSM tracking control of high speed trains with actuator saturation. Journal of the Franklin Institute, 2020, 357, 1582-1602.	1.9	12
29	Observer-Based Event-Triggered Composite Anti-Disturbance Control for Multi-Agent Systems Under Multiple Disturbances and Stochastic FDIAs. IEEE Transactions on Automation Science and Engineering, 2023, 20, 528-540.	3.4	12
30	Low-sensitivity <i>H</i> _{â^ž} filter design for linear delta operator systems with sampling time jitter. International Journal of Control, 2012, 85, 397-408.	1.2	11
31	Insensitive dynamic output feedback control with mixed-Hâ´ž norm sensitivity minimization. Journal of the Franklin Institute, 2013, 350, 72-91.	1.9	11
32	String stability of heterogeneous leader-following vehicle platoons based on constant spacing policy. , 2016, , .		10
33	Cluster synchronization of heterogeneous nonlinear multi-agent systems with actuator faults and IQCs through adaptive fault-tolerant pinning control. Information Sciences, 2021, 575, 289-305.	4.0	9
34	Synthesis of low $\hat{a} \in \hat{c}$ oefficient sensitivity controllers with respect to multiplicative controller coefficient variations. IET Control Theory and Applications, 2015, 9, 120-128.	1.2	7
35	Adaptive platoon control for nonlinear vehicular systems with asymmetric input deadzone and inter-vehicular spacing constraints. , 2017, , .		7
36	Static group synchronization of second-order multi-agent systems via pinning control. Journal of the Franklin Institute, 2019, 356, 4842-4858.	1.9	7

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37	Insensitive output feedback <i>H</i> _{â^žâ€‰} control of delta operator systems with insensitivity to sampling time jitter. International Journal of Robust and Nonlinear Control, 2014, 24, 725-743.	2.1	6
38	<i>H</i> _{â^ž} output tracking control for delta operator systems with insensitivity to controller coefficient variations. International Journal of Systems Science, 2013, 44, 652-662.	3.7	4
39	Insensitive H <inf>&$\#$x221E;</inf> filter design for discrete-time systems: an LMI optimization approach. , 2009, , .		3
40	Non-fragile H<inf> & amp; $\#x221E$; & lt; /inf> consensus of linear multi-agent systems with interval-bounded variations., 2015,,.		3
41	Reliable H <inf>∞</inf> filter design for a class of continuous-time nonlinear systems with time-varying delay. , 2009, , .		2
42	Non-fragile H <inf>∞</inf> filter design with pole placement constraints for delta operator formulated systems via LMI optimization., 2009,,.		2
43	Insensitive H <inf>∞</inf> filtering for fast-sampled linear systems with respect to sampling time jitter., 2012,,.		1
44	Integral sliding mode output control of delta operator systems with insensitivity to sampling time jitter. , 2014, , .		1
45	A Sequential Linear Programming Matrix Method to Insensitive Hâ^ž Output Feedback for Linear Discrete-Time Systems. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2014, 136, .	0.9	1
46	Robust fault tolerant controller design using indirect adaptive sliding mode control strategy. , 2015, , .		1
47	H2 Control for Discrete-time System with Multiplicative Controller Gain Variations. , 2007, , .		O
48	Reliable nonlinear H <inf>&$\#x221E$;</inf> filter design for continuous-time nonlinear systems with sector-bounded nonlinearities., 2009, , .		0
49	Integral sliding mode fault-tolerant control against actuator nonsymmetric deadzone and unmatched disturbances. , 2014, , .		0
50	Low sensitivity memory control for linear time-delay systems with mixed-H <inf>∞</inf> norm sensitivity minimization., 2014,,.		0
51	Quantized H[infinity] Static Output Control for Linear Systems with Interval-Bounded Additive Controller Coefficient Variations. , 2015, , .		O
52	Robust adaptive fault tolerant control for a steering subsystem of unmanned underwater vehicles., $2015, \dots$		0
53	Adaptive fault-torrent attitude tracking control for hypersonic Unmanned aerial vehicle subject to input constraints. , $2015, , .$		0
54	Asymptotic tracking control for an underactuated quadrotor via immersion and invariance technology. , 2017, , .		0

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55	Non-Fragile Dynamic Output Feedback Control with Norm-Bounded Gain Uncertainty. , 2017, , 37-60.		O
56	Non-Fragile Hâ^ž Filtering wit Interval-Bounded Coefficient Variations. , 2017, , 131-166.		O
57	Robust Non-Fragile Kalman Filtering with Norm-Bounded Gain Uncertainty. , 2017, , 61-83.		O
58	Non-Fragile Dynamic Output Feedback Control with Interval-Bounded Coefficient Variations. , 2017, , 85-129.		0
59	Non-Fragile Quantized Consensus for Multi-Agent Systems Based on Incidence Matrix. , 2019, , 149-170.		O
60	String Stability of Vehicle Platoons with Nonlinear Acceleration Uncertainties. , 2019, , 37-56.		O
61	Neuro-Adaptive Quantized PID-Based SMC of Vehicular Platoon with Deadzone. , 2019, , 113-133.		O
62	Collision Avoidance for Vehicle Platoon with Input Deadzone., 2019,, 99-111.		0
63	CNN-Based Adaptive Control for Vehicle Platoon with Input Saturation., 2019,, 57-78.		O
64	Quantized H â^ž Consensus for Multi-Agent Systems with Quantization Mismatch., 2019, , 183-202.		0
65	Adaptive Fuzzy Fault-Tolerant Control for Multiple High Speed Trains. , 2019, , 79-97.		O
66	Low-Complexity Control of Vehicular Platoon with Asymmetric Saturation., 2019, , 135-147.		0
67	String Stability of Vehicle Platoons with External Disturbances. , 2019, , 17-36.		0
68	Event-triggered Switching Filter Design for Uncertain Nonlinear Networked Systems with Time-varying Delay. , 2020, , .		0