MarÃ-a del Carmen RodrÃ-guez LiñÃ;

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/4036460/publications.pdf

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22 papers 81 citations

5 h-index

1874746

9 g-index

22 all docs 22 docs citations

times ranked

22

70 citing authors

#	Article	IF	CITATIONS
1	A Class of Bounded and Partially Bounded Nonlinear Controllers for First and Second Order Dynamical Systems., 2022, 6, 1028-1033.		2
2	Evolved Extended Kalman Filter for first-order dynamical systems with unknown measurements noise covariance. Applied Soft Computing Journal, 2022, 115, 108174.	4.1	5
3	A literature review of sensor heads for humanoid robots. Robotics and Autonomous Systems, 2021, 143, 103834.	3.0	15
4	Position control with dynamic obstacle avoidance in omnidirectional mobile robots., 2021,,.		0
5	Minimum energy nonlinear controllers based on analytic behaviors for velocity tracking on DC motors. , 2021, , .		1
6	Tuning of a SNF tracking controller using genetic algorithms. , 2021, , .		0
7	On the implementation of a SNF velocity controller for DC motors with low resolution encoders. , 2021, , .		O
8	Family of controllers based on sector nonâ€linear functions: an application for firstâ€order dynamical systems. IET Control Theory and Applications, 2020, 14, 1387-1392.	1.2	4
9	Visible and near-infrared spectroscopy for detection of powdery mildew in Cucurbita pepo L. leaves. Journal of Applied Remote Sensing, 2020, 14, .	0.6	1
10	Synthetic-analytic behavior-based control framework: Constraining velocity in tracking for nonholonomic wheeled mobile robots. Information Sciences, 2019, 501, 436-459.	4.0	15
11	Controller structure for plants with combined saturation and stiction. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2019, 233, 945-960.	0.7	O
12	Saturating Stiffness Control of Robot Manipulators with Bounded Inputs. International Journal of Applied Mathematics and Computer Science, 2017, 27, 79-90.	1.5	9
13	Backlash compensation for plants with saturating actuators. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2017, 231, 471-480.	0.7	5
14	Developing a Studentâ€"Focused Undergraduate Laboratory. International Journal of Electrical Engineering and Education, 2013, 50, 268-278.	0.4	4
15	Themed Project Case Study: Quadruple Tanks Control with PLCs. International Journal of Electrical Engineering and Education, 2013, 50, 279-292.	0.4	4
16	Team organization and participation in the Eurobot 2012 contest. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 180-185.	0.4	0
17	Distributed knowledge-based computer-aided control education environment. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 156-161.	0.4	О
18	Student-focused undergraduate laboratory development: position control of a printer head. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 232-237.	0.4	0

#	Article	IF	CITATIONS
19	Controlling a quadruple tanks rig with PLCs as a Masters dissertation project. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 238-243.	0.4	2
20	MPC for Plants Subject to Saturation and Deadzone, Backlash or Stiction. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 418-423.	0.4	10
21	Controller structure for plants with combined saturation and deadzone/backlash., 2012,,.		3
22	Orbital synchronization of homogeneous mechanical systems with one degree of underactuation. International Journal of Robust and Nonlinear Control, 0, , .	2.1	1