Balakrishnan Ramalingam

List of Publications by Year in descending order

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687220 642610 31 567 13 23 citations g-index h-index papers 31 31 31 386 docs citations citing authors all docs times ranked

#	Article	IF	CITATIONS
1	False Ceiling Deterioration Detection and Mapping Using a Deep Learning Framework and the Teleoperated Reconfigurable †Falcon' Robot. Sensors, 2022, 22, 262.	2.1	4
2	Al-Enabled Predictive Maintenance Framework for Autonomous Mobile Cleaning Robots. Sensors, 2022, 22, 13.	2.1	10
3	Al-Enabled Mosquito Surveillance and Population Mapping Using Dragonfly Robot. Sensors, 2022, 22, 4921.	2.1	3
4	Toward a Comprehensive Domestic Dirt Dataset Curation for Cleaning Auditing Applications. Sensors, 2022, 22, 5201.	2.1	1
5	Social Density Monitoring Toward Selective Cleaning by Human Support Robot With 3D Based Perception System. IEEE Access, 2021, 9, 41407-41416.	2.6	10
6	Locomotion with Pedestrian Aware from Perception Sensor by Pavement Sweeping Reconfigurable Robot. Sensors, 2021, 21, 1745.	2.1	13
7	Deep Learning Based Pavement Inspection Using Self-Reconfigurable Robot. Sensors, 2021, 21, 2595.	2.1	23
8	An Autonomous Robot-Aided Auditing Scheme for Floor Cleaning. Sensors, 2021, 21, 4332.	2.1	14
9	Al Enabled loRT Framework for Rodent Activity Monitoring in a False Ceiling Environment. Sensors, 2021, 21, 5326.	2.1	7
10	sTetro-Deep Learning Powered Staircase Cleaning and Maintenance Reconfigurable Robot. Sensors, 2021, 21, 6279.	2.1	14
11	Drain Structural Defect Detection and Mapping Using Al-Enabled Reconfigurable Robot Raptor and loRT Framework. Sensors, 2021, 21, 7287.	2.1	3
12	Simultaneous Motion-Slosh Control for a Self-Reconfigurable Mobile Robot., 2021,,.		O
13	Remote drain inspection framework using the convolutional neural network and re-configurable robot Raptor. Scientific Reports, 2021, 11 , 22378.	1.6	4
14	A Reinforcement Learning Based Dirt-Exploration for Cleaning-Auditing Robot. Sensors, 2021, 21, 8331.	2.1	5
15	Remote Insects Trap Monitoring System Using Deep Learning Framework and IoT. Sensors, 2020, 20, 5280.	2.1	46
16	A Time Delay Estimation Based Adaptive Sliding Mode Strategy for Hybrid Impedance Control. IEEE Access, 2020, 8, 155352-155361.	2.6	3
17	Wall-Following Behavior for a Disinfection Robot Using Type 1 and Type 2 Fuzzy Logic Systems. Sensors, 2020, 20, 4445.	2.1	22
18	Table Cleaning Task by Human Support Robot Using Deep Learning Technique. Sensors, 2020, 20, 1698.	2.1	43

#	Article	IF	CITATIONS
19	Vision Based Wall Following Framework: A Case Study With HSR Robot for Cleaning Application. Sensors, 2020, 20, 3298.	2.1	16
20	A Path Tracking Strategy for Car Like Robots with Sensor Unpredictability and Measurement Errors. Sensors, 2020, 20, 3077.	2.1	6
21	A Human Support Robot for the Cleaning and Maintenance of Door Handles Using a Deep-Learning Framework. Sensors, 2020, 20, 3543.	2.1	59
22	Complete coverage path planning using reinforcement learning for Tetromino based cleaning and maintenance robot. Automation in Construction, 2020, 112, 103078.	4.8	99
23	Visual Inspection of the Aircraft Surface Using a Teleoperated Reconfigurable Climbing Robot and Enhanced Deep Learning Technique. International Journal of Aerospace Engineering, 2019, 2019, 1-14.	0.5	29
24	Vision-Based Dirt Detection and Adaptive Tiling Scheme for Selective Area Coverage. Journal of Sensors, 2018, 2018, 1-13.	0.6	10
25	Cascaded Machine-Learning Technique for Debris Classification in Floor-Cleaning Robot Application. Applied Sciences (Switzerland), 2018, 8, 2649.	1.3	38
26	Chaos triggered image encryption - a reconfigurable security solution. Multimedia Tools and Applications, 2018, 77, 11669-11692.	2.6	22
27	Hybrid image crypto system for secure image communication– A VLSI approach. Microprocessors and Microsystems, 2017, 50, 1-13.	1.8	22
28	Multiplexed stego path on reconfigurable hardware: A novel random approach. Computers and Electrical Engineering, 2016, 55, 153-163.	3.0	7
29	Stego on FPGA: An IWT Approach. Scientific World Journal, The, 2014, 2014, 1-9.	0.8	15
30	LCC-LSB-FPGA Stego-A Reconfigurable Security. Journal of Applied Sciences, 2014, 14, 2139-2148.	0.1	16
31	A singular perturbation based adaptive strategy for bounded controller design in feedback linearizable systems. International Journal of Adaptive Control and Signal Processing, 0, , .	2.3	3