

# Xiaojian Li

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/3916330/publications.pdf>

Version: 2024-02-01

19  
papers

526  
citations

1307594

7  
h-index

1125743

13  
g-index

19  
all docs

19  
docs citations

19  
times ranked

712  
citing authors

| #  | ARTICLE  | IF   | CITATIONS |
|----|--|------|-----------|
| 1  | Development of a magnetic microrobot for carrying and delivering targeted cells. <i>Science Robotics</i> , 2018, 3, .  | 17.6 | 290       |
| 2  | Gradient-Enhanced Electromagnetic Actuation System With a New Core Shape Design for Microrobot Manipulation. <i>IEEE Transactions on Industrial Electronics</i> , 2020, 67, 4700-4710.                                 | 7.9  | 47        |
| 3  | <i>In Vivo</i> ; Manipulation of Single Biological Cells With an Optical Tweezers-Based Manipulator and a Disturbance Compensation Controller. <i>IEEE Transactions on Robotics</i> , 2017, 33, 1200-1212.             | 10.3 | 43        |
| 4  | Transportation of Multiple Biological Cells Through Saturation-Controlled Optical Tweezers In Crowded Microenvironments. <i>IEEE/ASME Transactions on Mechatronics</i> , 2016, 21, 888-899.                            | 5.8  | 36        |
| 5  | Unsupervised-Learning-Based Continuous Depth and Motion Estimation With Monocular Endoscopy for Virtual Reality Minimally Invasive Surgery. <i>IEEE Transactions on Industrial Informatics</i> , 2021, 17, 3920-3928.  | 11.3 | 25        |
| 6  | Autonomous Multiple Instruments Tracking for Robot-Assisted Laparoscopic Surgery With Visual Tracking Space Vector Method. <i>IEEE/ASME Transactions on Mechatronics</i> , 2022, 27, 733-743.                          | 5.8  | 24        |
| 7  | Simultaneous Localization and Mapping-Based In Vivo Navigation Control of Microparticles. <i>IEEE Transactions on Industrial Informatics</i> , 2020, 16, 2956-2964.  | 11.3 | 15        |
| 8  | Leveraging Multimodal Semantic Fusion for Gastric Cancer Screening via Hierarchical Attention Mechanism. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2022, 52, 4286-4299.                     | 9.3  | 7         |
| 9  | Automatic Acetowhite Lesion Segmentation via Specular Reflection Removal and Deep Attention Network. <i>IEEE Journal of Biomedical and Health Informatics</i> , 2021, 25, 3529-3540.                                   | 6.3  | 7         |
| 10 | SIRNet: Fine-Grained Surgical Interaction Recognition. <i>IEEE Robotics and Automation Letters</i> , 2022, 7, 4212-4219.   | 5.1  | 7         |
| 11 | Precise Drug Delivery by Using PLGA-Based Microspheres and Optical Manipulators. <i>IEEE Transactions on Nanobioscience</i> , 2020, 19, 192-202.   | 3.3  | 5         |
| 12 | <i>LightGBM</i> : A machine learning model based on hybrid feature selection for classifying <i>ICU</i> patient readmissions. <i>Expert Systems</i> , 2021, 38, e12658.  | 4.5  | 5         |
| 13 | Preparation, Morphology, and Structure of Thermotropic Liquid Crystalline Polyester-imide/Phenol-formaldehyde Resin Blends. <i>Journal of Macromolecular Science - Pure and Applied Chemistry</i> , 2012, 49, 378-384. | 2.2  | 3         |
| 14 | Automated in-vivo transportation of biological cells with a disturbance compensation controller. , 2016, , .   |      | 3         |
| 15 | Design of an automated controller with collision-avoidance capability for in-vivo transportation of biological cells. , 2017, , .  |      | 3         |
| 16 | Stabilization Algorithm Based on Improved Motion Model for Jittery Video in Minimally Invasive Surgery. , 2019, , .  |      | 2         |
| 17 | A Novel Dynamic Filed Tracking Algorithm of Mirror-holding Robot for Minimally Invasive Surgery. , 2019, , .   |      | 2         |
| 18 | Haptic Feedback Based Laparoscope Movement Perception Method for Autonomous Surgical Instruments Tracking in Robot-Assisted Minimally Invasive Surgery. , 2021, , .  |      | 2         |

| #  | ARTICLE  | IF | CITATIONS |
|----|--|----|-----------|
| 19 | Virtual Fixtures Assistance for Safe Polyp Dissection in Minimally Invasive Robotic Surgery. , 2021, , . |    | 0         |