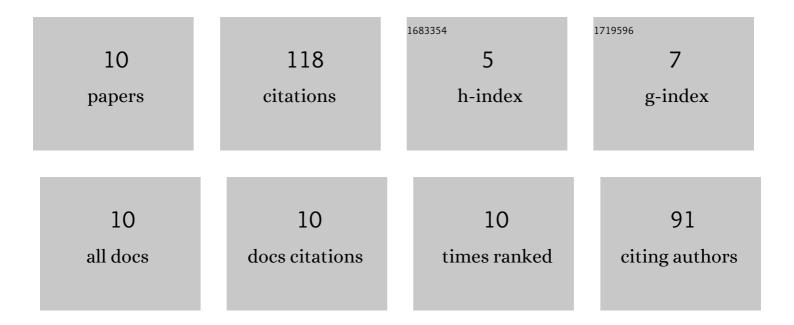
Payam Kheirkhahan

List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	A note on the â€~task-space control of robots using an adaptive Taylor series uncertainty estimator'. International Journal of Control, 2021, 94, 722-723.	1.2	6
2	Observer-based adaptive fractional-order control of flexible-joint robots using the Fourier series expansion: theory and experiment. Journal of the Brazilian Society of Mechanical Sciences and Engineering, 2020, 42, 1.	0.8	21
3	Single-loop versus multi-loop control strategies for electrically driven robots with elastic joint. Journal of the Brazilian Society of Mechanical Sciences and Engineering, 2020, 42, 1.	0.8	3
4	Tracking Control of Electrically Driven Robots Using a Model-free Observer. Robotica, 2019, 37, 729-755.	1.3	19
5	FAT-Based Robust Adaptive Control of Electrically Driven Robots in Interaction with Environment. Robotica, 2019, 37, 779-800.	1.3	22
6	Adaptive fractional-order control of electrical flexible-joint robots: Theory and experiment. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2019, 233, 1136-1145.	0.7	20
7	On the Voltage-based Control of Robot Manipulators Revisited. International Journal of Control, Automation and Systems, 2018, 16, 1887-1894.	1.6	12
8	Nonlinear PID control of electrical flexible joint robots-Theory and experimental verification. , 2018, ,		10
9	FAT-based robust adaptive control of optical micro electro mechanical system. , 2018, , .		0

10 Robust anti-windup control design for PID controllers. , 2017, , .