

Gao-Wei Zhang

List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Periodic event-triggered sliding mode control for lower limb exoskeleton based on human-robot cooperation. ISA Transactions, 2022, 123, 87-97.	5.7	24
2	Disturbance Observer-Based Terminal Sliding Mode Control of a 5-DOF Upper-Limb Exoskeleton Robot. IEEE Access, 2019, 7, 62833-62839.	4.2	21
3	Command Filter Backstepping Sliding Model Control for Lower-Limb Exoskeleton. Mathematical Problems in Engineering, 2017, 2017, 1-10.	1.1	13
4	Multivariable Finite-Time Control of 5 DOF Upper-Limb Exoskeleton Based on Linear Extended Observer. IEEE Access, 2018, 6, 43213-43221.	4.2	13
5	Integrated Observer-based Fixed-time Control with Backstepping Method for Exoskeleton Robot. International Journal of Automation and Computing, 2020, 17, 71-82.	4.5	10
6	A learning control scheme for upper-limb exoskeleton via adaptive sliding mode technique. Mechatronics, 2022, 86, 102832.	3.3	7
7	Model-Free Based Back-Stepping Sliding Mode Control for Wearable Exoskeletons. , 2019, , .		4
8	Event-triggered sliding mode controller design for lower limb exoskeleton. , 2020, , .		2
9	Sliding Mode Control for Wearable Exoskeleton based on Disturbance Observer. , 2018, , .		0