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List of Publications by Year in descending order

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23
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286
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | Inverse eigenvalue problem for mass-spring-inerter systems. <i>Mechanical Systems and Signal Processing</i> , 2022, 167, 108506. | 8.0 | 1 |
| 2 | Closed-loop identification for a class of nonlinearly parameterized discrete-time systems. <i>Automatica</i> , 2021, 131, 109747. | 5.0 | 1 |
| 3 | On the Convergence of Least Squares Estimator for Nonlinear Autoregressive Models *, 2021, , . | | 0 |
| 4 | Is it Possible to Stabilize Discrete-Time Parameterized Uncertain Systems Growing Exponentially Fast?. <i>SIAM Journal on Control and Optimization</i> , 2019, 57, 1965-1984. | 2.1 | 2 |
| 5 | On instability of LS-based self-tuning systems with bounded disturbances. <i>Systems and Control Letters</i> , 2019, 129, 51-55. | 2.3 | 1 |
| 6 | Robust Adaptive Tracking Control for Quadrotors by Combining PI and Self-Tuning Regulator. <i>IEEE Transactions on Control Systems Technology</i> , 2019, 27, 2663-2671. | 5.2 | 43 |
| 7 | Passive Controller Realization of a Biquadratic Impedance With Double Poles and Zeros as a Seven-Element Series-Parallel Network for Effective Mechanical Control. <i>IEEE Transactions on Automatic Control</i> , 2018, 63, 3010-3015. | 5.7 | 13 |
| 8 | How much information is needed in quantized nonlinear control?. <i>Science China Information Sciences</i> , 2018, 61, 1. | 4.3 | 11 |
| 9 | Further Results on Stabilizability of Discrete-time Nonlinearly Parameterized Systems With Scalar Parameters. <i>IEEE Transactions on Automatic Control</i> , 2018, 63, 2153-2160. | 5.7 | 1 |
| 10 | Stabilisation of non-linear DISS systems with uncertainty via encoded feedback. <i>IET Control Theory and Applications</i> , 2017, 11, 732-739. | 2.1 | 1 |
| 11 | The dual algebraic Riccati equations and the set of all solutions of the discrete-time Riccati equation. <i>International Journal of Control</i> , 2017, 90, 1371-1388. | 1.9 | 3 |
| 12 | Realization of Biquadratic Impedances as Five-Element Bridge Networks. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2017, 64, 1599-1611. | 5.4 | 15 |
| 13 | On-line aerodynamic identification of quadrotor and its application to tracking control. <i>IET Control Theory and Applications</i> , 2017, 11, 3097-3106. | 2.1 | 5 |
| 14 | Consensus networks with switching topology and time-delays over finite fields. <i>Automatica</i> , 2016, 68, 39-43. | 5.0 | 50 |
| 15 | Simultaneous Identification and Stabilization of Nonlinearly Parameterized Discrete-Time Systems by Nonlinear Least Squares Algorithm. <i>IEEE Transactions on Automatic Control</i> , 2016, 61, 1810-1823. | 5.7 | 13 |
| 16 | Synthesis of n -port resistive networks containing $2n$ terminals. <i>International Journal of Circuit Theory and Applications</i> , 2015, 43, 427-437. | 2.0 | 23 |
| 17 | On Stabilizability of Nonlinearly Parameterized Discrete-Time Systems. <i>IEEE Transactions on Automatic Control</i> , 2014, 59, 3014-3019. | 5.7 | 5 |
| 18 | Feedback systems with communications: integrated study of signal estimation, sampling, quantization, and feedback robustness. <i>International Journal of Adaptive Control and Signal Processing</i> , 2014, 28, 496-522. | 4.1 | 7 |

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 19 | Stabilization of Discrete-Time Nonlinear Uncertain Systems by Feedback Based on LS Algorithm. SIAM Journal on Control and Optimization, 2013, 51, 1128-1151. | 2.1 | 20 |
| 20 | Realizations of a Special Class of Admittances With Strictly Lower Complexity Than Canonical Forms. IEEE Transactions on Circuits and Systems I: Regular Papers, 2013, 60, 2465-2473. | 5.4 | 43 |
| 21 | A tighter reachable set bound for linear systems subject to both discrete and distributed delays. , 2012, , . | | 0 |
| 22 | On Exponential Almost Sure Stability of Random Jump Systems. IEEE Transactions on Automatic Control, 2012, 57, 3064-3077. | 5.7 | 48 |
| 23 | On Feedback Capability in a Class of Nonlinearly Parameterized Uncertain Systems. IEEE Transactions on Automatic Control, 2011, 56, 2946-2951. | 5.7 | 15 |