Uzair

List of Publications by Year in descending order

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1125743 933447 27 291 10 13 citations h-index g-index papers 27 27 27 149 docs citations citing authors all docs times ranked

| # | Article | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Three degrees of freedom rotary double inverted pendulum stabilization by using robust generalized dynamic inversion control: Design and experiments. JVC/Journal of Vibration and Control, 2020, 26, 2174-2184. | 2.6 | 13 |
| 2 | Underactuated rotary inverted pendulum control using robust generalized dynamic inversion. JVC/Journal of Vibration and Control, 2020, 26, 2210-2220. | 2.6 | 13 |
| 3 | Highly maneuvering target interception via robust generalized dynamic inversion homing guidance and control. Aerospace Science and Technology, 2020, 99, 105749. | 4.8 | 8 |
| 4 | Adaptive Robust Generalized Dynamic Inversion Quadrotor Control. IFAC-PapersOnLine, 2020, 53, 3841-3846. | 0.9 | 1 |
| 5 | Design and Implementation of Robust Generalized Dynamic Inversion Control for Stabilizing Rotary Inverted Pendulum., 2019,,. | | 0 |
| 6 | Tracking Control of Quadrotor using Generalized Dynamic Inversion with Constant-Proportional Rate Reaching Law. , 2019, , . | | 1 |
| 7 | Development and experimental investigation of a Quadrotor's robust generalized dynamic inversion control system. Nonlinear Dynamics, 2019, 96, 1541-1557. | 5.2 | 20 |
| 8 | Angular Position Control of Twin Rotor MIMO System using Generalized Dynamic Inversion with Switching Surface. , 2019, , . | | 2 |
| 9 | Autonomous Underwater Vehicles Attitude control using Neuro-Adaptive Generalized Dynamic Inversion. IFAC-PapersOnLine, 2019, 52, 103-109. | 0.9 | 6 |
| 10 | Quadrotor Control using Neuro-Adaptive Robust Generalized Dynamic Inverasion., 2019,,. | | 1 |
| 11 | Twin-rotor Attitude Control using Adaptive Generalized Dynamic Inversion with Neural Estimation. , 2019, , . | | O |
| 12 | Nonlinear Robust Generalized Dynamic Inversion based Homing Guidance and Control of Aerial Interceptors. IFAC-PapersOnLine, 2019, 52, 219-226. | 0.9 | 0 |
| 13 | Quadrotor Control Via Robust Generalized Dynamic Inversion and Adaptive Nonâ€Singular Terminal Sliding Mode. Asian Journal of Control, 2019, 21, 1237-1249. | 3.0 | 59 |
| 14 | Control of Twin Rotor MIMO System using Robust Generalized Dynamic Inversion. , 2018, , . | | 0 |
| 15 | Robust Generalized Dynamic Inversion Control for Stabilizing Rotary Double Inverted Pendulum. , 2018, , . | | 1 |
| 16 | Hybrid Direct-Indirect Adaptive Generalized Dynamic Inversion Based Attitude Control of Autonomous Underwater Vehicles., 2018,,. | | 6 |
| 17 | Aircraft Motion Decoupling of Roll and Yaw Dynamics Using Generalized Dynamic Inversion Control. , 2018, , . | | 16 |
| 18 | Adaptive Generalized Dynamic Inversion Based Trajectory Tracking Control of Autonomous Underwater Vehicle. , 2018, , . | | 8 |

| # | Article | IF | CITATION |
|----|---|-----|----------|
| 19 | Quadrotor Motion Control using Adaptive Generalized Dynamic Inversion. , 2018, , . | | 12 |
| 20 | Positional control of rotary servo cart system using generalized dynamic inversion. Journal of Vibroengineering, 2018, 20, 2403-2413. | 1.0 | 10 |
| 21 | Robust Generalized Dynamic Inversion Quadrotor Control. IFAC-PapersOnLine, 2017, 50, 8181-8188. | 0.9 | 22 |
| 22 | Robust launch vehicle's generalized dynamic inversion attitude control. Aircraft Engineering and Aerospace Technology, 2017, 89, 902-910. | 1.2 | 28 |
| 23 | Robust Generalized Dynamic Inversion Control of Autonomous Underwater Vehicles. IFAC-PapersOnLine, 2017, 50, 10658-10665. | 0.9 | 16 |
| 24 | Generalized Dynamic Inversion based Attitude Control of Autonomous Underwater Vehicles. IFAC-PapersOnLine, 2016, 49, 582-589. | 0.9 | 13 |
| 25 | Guidance and robust generalized inversion based attitude control of Satellite Launch Vehicle. , 2016, , | | 9 |
| 26 | Generalized Dynamic Inversion Scheme for Satellite Launch Vehicle Attitude Control. IFAC-PapersOnLine, 2015, 48, 114-119. | 0.9 | 14 |
| 27 | Quadrotor control using generalized dynamic inversion and terminal sliding mode. , 2015, , . | | 12 |