

Minh Hoang Trinh

List of Publications by Year in descending order

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46
papers

589
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933447

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46
all docs

46
docs citations

46
times ranked

262
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Matrix-weighted consensus and its applications. Automatica, 2018, 89, 415-419. | 5.0 | 73 |
| 2 | Finite-Time Bearing-Only Formation Control via Distributed Global Orientation Estimation. IEEE Transactions on Control of Network Systems, 2019, 6, 702-712. | 3.7 | 57 |
| 3 | Bearing-Based Formation Control of A Group of Agents with Leader-First Follower Structure. IEEE Transactions on Automatic Control, 2018, , 1-1. | 5.7 | 42 |
| 4 | Continuous-time opinion dynamics on multiple interdependent topics. Automatica, 2020, 115, 108884. | 5.0 | 35 |
| 5 | Robust tracking control of bearing-constrained leader-follower formation. Automatica, 2021, 131, 109733. | 5.0 | 34 |
| 6 | Distance-Based Formation Control With Bounded Disturbances. , 2021, 5, 451-456. | | 29 |
| 7 | Formations on directed cycles with bearing-only measurements. International Journal of Robust and Nonlinear Control, 2018, 28, 1074-1096. | 3.7 | 27 |
| 8 | Guidance using bearing-only measurements with three beacons in the plane. Control Engineering Practice, 2016, 51, 81-91. | 5.5 | 19 |
| 9 | Opinion Dynamics With Cross-Coupling Topics: Modeling and Analysis. IEEE Transactions on Computational Social Systems, 2020, 7, 632-647. | 4.4 | 17 |
| 10 | Discrete-Time Matrix-Weighted Consensus. IEEE Transactions on Control of Network Systems, 2021, 8, 1568-1578. | 3.7 | 17 |
| 11 | Comments on "Global stabilization of rigid formations in the plane [Automatica 49 (2013) 1436-1441]". Automatica, 2017, 77, 393-396. | 5.0 | 16 |
| 12 | Finite-Time Bearing-Based Maneuver of Acyclic Leader-Follower Formations. , 2022, 6, 1004-1009. | | 16 |
| 13 | Laman graphs are generically bearing rigid in arbitrary dimensions. , 2017, , . | | 15 |
| 14 | Matrix-weighted consensus with leader-following topologies. , 2017, , . | | 13 |
| 15 | Distance-based control of K4 formation with almost global convergence. , 2016, , . | | 12 |
| 16 | Bearing-Only Control of Leader First Follower Formations**This work was supported by the National Research Foundation of Korea under Grant NRF-2015M2A8A4049953.. IFAC-PapersOnLine, 2016, 49, 7-12. | 0.9 | 11 |
| 17 | Pointing Consensus and Bearing-Based Solutions to the Fermat-Weber Location Problem. IEEE Transactions on Automatic Control, 2020, 65, 2339-2354. | 5.7 | 11 |
| 18 | Minimal and Redundant Bearing Rigidity: Conditions and Applications. IEEE Transactions on Automatic Control, 2020, 65, 4186-4200. | 5.7 | 11 |

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 19 | Bearing-only control of directed cycle formations: Almost global convergence and hardware implementation. <i>International Journal of Robust and Nonlinear Control</i> , 2020, 30, 4789-4804. | 3.7 | 11 |
| 20 | The Fermat-Weber location problem in single integrator dynamics using only local bearing angles. <i>Automatica</i> , 2015, 59, 90-96. | 5.0 | 10 |
| 21 | Infinitesimal Weak Rigidity and Stability Analysis on Three-Agent Formations. , 2018, , . | | 10 |
| 22 | Bearing-Based Formation Control and Network Localization via Global Orientation Estimation. , 2018, , . | | 8 |
| 23 | Free-will arbitrary time consensus protocols with diffusive coupling. <i>International Journal of Robust and Nonlinear Control</i> , 2022, 32, 8711-8731. | 3.7 | 8 |
| 24 | Further analysis on graph rigidity. , 2016, , . | | 7 |
| 25 | Distributed formation control of the special Euclidean group SE(2) via global orientation control. <i>IET Control Theory and Applications</i> , 2020, 14, 1393-1399. | 2.1 | 7 |
| 26 | Coordination of multi-agent systems with arbitrary convergence time. <i>IET Control Theory and Applications</i> , 2021, 15, 900-909. | 2.1 | 7 |
| 27 | Finite-time bearing-only formation control. , 2017, , . | | 6 |
| 28 | Consensus under misaligned orientations. , 2017, , . | | 6 |
| 29 | Comments on "Design of controllers with arbitrary convergence time" [<i>Automatica</i> 108710]. <i>Automatica</i> , 2020, 122, 109195. | 5.0 | 6 |
| 30 | Control of a mobile agent using only bearing measurements in triangular region. , 2014, , . | | 5 |
| 31 | Formation control of rigid graphs with flex edges. <i>International Journal of Robust and Nonlinear Control</i> , 2018, 28, 2543-2559. | 3.7 | 5 |
| 32 | Fixed-time network localization based on bearing measurements. , 2020, , . | | 5 |
| 33 | A new bearing-only navigation law. , 2017, , . | | 4 |
| 34 | Surrounding formation of star frameworks using bearing-only measurements. , 2018, , . | | 4 |
| 35 | Pointing consensus for rooted out-branching graphs. , 2018, , . | | 4 |
| 36 | Consensus under biased alignment. <i>Automatica</i> , 2019, 110, 108605. | 5.0 | 4 |

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 37 | Distance-based directed formation control in three-dimensional space. , 2017, , . | | 3 |
| 38 | Finite-time convergence of acyclic generically persistent formations. , 2018, , . | | 3 |
| 39 | Distance-based Formation Tracking with Unknown Bounded Reference Velocity. , 2020, , . | | 3 |
| 40 | Planar Bearing-only Cyclic Pursuit for Target Capture. IFAC-PapersOnLine, 2017, 50, 10136-10141. | 0.9 | 2 |
| 41 | Distributed Nash equilibrium seeking of an aggregative game by a singular perturbed algorithm. , 2017, , . | | 2 |
| 42 | Tracking Control of Directed Acyclic Formation via Target Point Localization. Lecture Notes in Networks and Systems, 2021, , 839-845. | 0.7 | 2 |
| 43 | The bearing-based multi-agent rendezvous problem on a circle. , 2017, , . | | 1 |
| 44 | A finite-time convergence of acyclic generically persistent formation in 3-D using relative position measurements. , 2017, , . | | 1 |
| 45 | Distributed coordination and control in combined AC-MT HVDC power grids. , 2017, , . | | 0 |
| 46 | Decentralized sliding-mode control laws for the bearing-based formation tracking problem. , 2021, , . | | 0 |