Jinbo Wu

List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	Practical observer-based path following control of the guide ship with propeller and rudder in the underway replenishment. Ships and Offshore Structures, 2022, 17, 506-517.	0.9	2
2	Identification of hydrodynamic coefficients of a ship manoeuvring model based on PRBS input. Ocean Engineering, 2022, 246, 110640.	1.9	3
3	Indirect adaptive robust control of nonstrict feedback nonlinear systems by a fuzzy approximation strategy. ISA Transactions, 2021, 108, 10-17.	3.1	12
4	Indirect Adaptive Robust Control Design for Course Tracking of Ships Subject to Unknown Control Coefficient and Disturbances. International Journal of Control, Automation and Systems, 2021, 19, 2059-2067.	1.6	8
5	Online identification method for a system with unknown varying time-delay and parameter. Transactions of the Institute of Measurement and Control, 2021, 43, 3267-3271.	1.1	0
6	Robust Adaptive Identification of Linear Time-Varying Systems Under Relaxed Excitation Conditions. IEEE Access, 2020, 8, 8268-8274.	2.6	11
7	Online identification of timeâ€varying delay systems under relaxed input conditions. Electronics Letters, 2020, 56, 1317-1320.	0.5	0
8	Integrated design of a novel force tracking electro-hydraulic actuator. Mechatronics, 2019, 62, 102247.	2.0	9
9	Nonlocal Means Image Denoising With Minimum MSE-Based Decay Parameter Adaptation. IEEE Access, 2019, 7, 130246-130261.	2.6	8
10	Indirect adaptive robust control of nonlinear systems with timeâ€varying parameters in a strict feedback form. International Journal of Robust and Nonlinear Control, 2018, 28, 3835-3851.	2.1	31
11	Integrated design of an active heave compensation crane with hydrostatic secondary control. , 2018, ,		1
12	PCANet based nonlocal means method for speckle noise removal in ultrasound images. PLoS ONE, 2018, 13, e0205390.	1.1	22
13	Calibration of Binocular Vision Sensors Based on Unknown-Sized Elliptical Stripe Images. Sensors, 2017, 17, 2873.	2.1	5
14	Robust adaptive identification of linear timeâ€varying systems with modified leastâ€squares algorithm. Electronics Letters, 2016, 52, 2038-2040.	0.5	10
15	Robust adaptive control for a nonholonomic mobile robot with unknown parameters. Journal of Control Theory and Applications, 2009, 7, 212-218.	0.8	32