

# Hao Li

## List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Adaptive Cubature Split Covariance Intersection Filter for Multi-Vehicle Cooperative Localization. IEEE Robotics and Automation Letters, 2022, 7, 1158-1165.	5.1	5
2	Inertial Navigation System Based Vehicle Temporal Relative Localization With Split Covariance Intersection Filter. IEEE Robotics and Automation Letters, 2022, 7, 5270-5277.	5.1	5
3	LiDAR SLAM Based Multivehicle Cooperative Localization Using Iterated Split CIF. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 21137-21147.	8.0	15
4	Adversarial Training-Based Hard Example Mining for Pedestrian Detection in Fish-Eye Images. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 7688-7698.	8.0	5
5	SteeringLoss: A Cost-Sensitive Loss Function for the End-to-End Steering Estimation. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 1104-1113.	8.0	2
6	3D Instance Embedding Learning With a Structure-Aware Loss Function for Point Cloud Segmentation. IEEE Robotics and Automation Letters, 2020, 5, 4915-4922.	5.1	26
7	Split Covariance Intersection Filter based Front-Vehicle Track Estimation for Vehicle Platooning without Communication. , 2020, , .		5
8	Cooperative Multi-Vehicle Localization Using Split Covariance Intersection Filter. IEEE Intelligent Transportation Systems Magazine, 2013, 5, 33-44.	3.8	102
9	Split Covariance Intersection Filter: Theory and Its Application to Vehicle Localization. IEEE Transactions on Intelligent Transportation Systems, 2013, 14, 1860-1871.	8.0	59