## Dariu M Gavrila

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/3262420/publications.pdf

Version: 2024-02-01

687363 839539 2,865 31 13 18 citations h-index g-index papers 31 31 31 2009 docs citations times ranked citing authors all docs

#	Article	lF	Citations
1	Monocular Pedestrian Detection: Survey and Experiments. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2009, 31, 2179-2195.	13.9	1,017
2	Human motion trajectory prediction: a survey. International Journal of Robotics Research, 2020, 39, 895-935.	<b>8.</b> 5	381
3	Will the Pedestrian Cross? A Study on Pedestrian Path Prediction. IEEE Transactions on Intelligent Transportation Systems, 2014, 15, 494-506.	8.0	251
4	EuroCity Persons: A Novel Benchmark for Person Detection in Traffic Scenes. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2019, 41, 1844-1861.	13.9	180
5	Active Pedestrian Safety by Automatic Braking and Evasive Steering. IEEE Transactions on Intelligent Transportation Systems, 2011, 12, 1292-1304.	8.0	163
6	Context-Based Pedestrian Path Prediction. Lecture Notes in Computer Science, 2014, , 618-633.	1.3	139
7	CNN Based Road User Detection Using the 3D Radar Cube. IEEE Robotics and Automation Letters, 2020, 5, 1263-1270.	5.1	97
8	Context-Based Path Prediction for Targets with Switching Dynamics. International Journal of Computer Vision, 2019, 127, 239-262.	15.6	96
9	A Unified Framework for Concurrent Pedestrian and Cyclist Detection. IEEE Transactions on Intelligent Transportation Systems, 2017, 18, 269-281.	8.0	75
10	Integrated pedestrian classification and orientation estimation. , 2010, , .		64
11	A Probabilistic Framework for Joint Pedestrian Head and Body Orientation Estimation. IEEE Transactions on Intelligent Transportation Systems, 2015, 16, 1872-1882.	8.0	54
12	An Extrinsic Calibration Tool for Radar, Camera and Lidar. , 2019, , .		52
13	Multi-Class Road User Detection With 3+1D Radar in the View-of-Delft Dataset. IEEE Robotics and Automation Letters, 2022, 7, 4961-4968.	5.1	52
14	Using road topology to improve cyclist path prediction. , 2017, , .		38
15	A Joint Extrinsic Calibration Tool for Radar, Camera and Lidar. IEEE Transactions on Intelligent Vehicles, 2021, 6, 571-582.	12.7	32
16	Analysis of pedestrian dynamics from a vehicle perspective., 2014,,.		26
17	Driver and pedestrian awareness-based collision risk analysis. , 2016, , .		26
18	Context-based cyclist path prediction using Recurrent Neural Networks. , 2019, , .		26

#	Article	IF	CITATIONS
19	Occlusion aware sensor fusion for early crossing pedestrian detection., 2019,,.		18
20	Semantic Scene Completion Using Local Deep Implicit Functions on LiDAR Data. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2022, 44, 7205-7218.	13.9	17
21	Mixture of Switching Linear Dynamics to Discover Behavior Patterns in Object Tracks. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2016, 38, 322-334.	13.9	12
22	Scenario-Based Trajectory Optimization in Uncertain Dynamic Environments. IEEE Robotics and Automation Letters, 2021, 6, 5389-5396.	5.1	12
23	Deep End-to-end 3D Person Detection from Camera and Lidar. , 2019, , .		8
24	Fast and Compact Image Segmentation Using Instance Stixels. IEEE Transactions on Intelligent Vehicles, 2022, 7, 45-56.	12.7	7
25	Crafted vs Learned Representations in Predictive Models—A Case Study on Cyclist Path Prediction. IEEE Transactions on Intelligent Vehicles, 2021, 6, 747-759.	12.7	6
26	General-Sum Multi-Agent Continuous Inverse Optimal Control. IEEE Robotics and Automation Letters, 2021, 6, 3429-3436.	5.1	5
27	Instance Stixels: Segmenting and Grouping Stixels into Objects. , 2019, , .		4
28	Simple Pair Pose - Pairwise Human Pose Estimation in Dense Urban Traffic Scenes. , 2021, , .		4
29	ECP2.5D - Person Localization in Traffic Scenes. , 2020, , .		2
30	Generating 3D Person Trajectories from Sparse Image Annotations in an Intelligent Vehicles Setting. , 2019, , .		1
31	An Experimental Study on 3D Person Localization in Traffic Scenes. , 2020, , .		O