

Renquan Lu

List of Publications by Citations

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128
papers

5,770
citations

42
h-index

73
g-index

138
ext. papers

7,265
ext. citations

6.1
avg, IF

6.98
L-index

#	Paper	IF	Citations
128	Passivity-Based Asynchronous Control for Markov Jump Systems. <i>IEEE Transactions on Automatic Control</i> , 2017 , 62, 2020-2025	5.9	321
127	Adaptive finite-time tracking control of full state constrained nonlinear systems with dead-zone. <i>Automatica</i> , 2019 , 100, 99-107	5.7	282
126	Event-Triggered Control for Consensus of Multiagent Systems With Fixed/Switching Topologies. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2018 , 48, 1736-1746	7.3	232
125	Finite-Time Distributed State Estimation Over Sensor Networks With Round-Robin Protocol and Fading Channels. <i>IEEE Transactions on Cybernetics</i> , 2018 , 48, 336-345	10.2	184
124	Asynchronous Dissipative State Estimation for Stochastic Complex Networks With Quantized Jumping Coupling and Uncertain Measurements. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2017 , 28, 268-277	10.3	181
123	Adaptive Neural Network Tracking Control for Robotic Manipulators With Dead Zone. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2019 , 30, 3611-3620	10.3	181
122	Synchronization on complex networks of networks. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2014 , 25, 2110-8	10.3	173
121	Prescribed Performance Observer-Based Adaptive Fuzzy Control for Nonstrict-Feedback Stochastic Nonlinear Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2018 , 48, 1747-1758	7.3	159
120	Consensus in Multi-Agent Systems With Second-Order Dynamics and Sampled Data. <i>IEEE Transactions on Industrial Informatics</i> , 2013 , 9, 2137-2146	11.9	144
119	Networked Control With State Reset and Quantized Measurements: Observer-Based Case. <i>IEEE Transactions on Industrial Electronics</i> , 2013 , 60, 5206-5213	8.9	138
118	Adaptive event-triggered control for a class of nonlinear systems with periodic disturbances. <i>Science China Information Sciences</i> , 2020 , 63, 1	3.4	131
117	Event-Triggered Consensus Control for Multi-Agent Systems Against False Data-Injection Attacks. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 1856-1866	10.2	130
116	Dissipativity-Based Sampled-Data Fuzzy Control Design and its Application to Truck-Trailer System. <i>IEEE Transactions on Fuzzy Systems</i> , 2015 , 23, 1669-1679	8.3	128
115	An input-based triggering approach to leader-following problems. <i>Automatica</i> , 2017 , 75, 221-228	5.7	126
114	Observer-Based Composite Adaptive Fuzzy Control for Nonstrict-Feedback Systems With Actuator Failures. <i>IEEE Transactions on Fuzzy Systems</i> , 2018 , 26, 2336-2347	8.3	124
113	A sliding mode approach to stabilization of nonlinear Markovian jump singularly perturbed systems. <i>Automatica</i> , 2018 , 97, 404-413	5.7	124
112	Fuzzy-Model-Based Nonfragile Guaranteed Cost Control of Nonlinear Markov Jump Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2017 , 47, 2388-2397	7.3	119

111	Dissipativity-Based Reliable Control for Fuzzy Markov Jump Systems With Actuator Faults. <i>IEEE Transactions on Cybernetics</i> , 2017 , 47, 2377-2388	10.2	111
110	Adaptive Fuzzy Control for Nonstrict Feedback Systems With Unmodeled Dynamics and Fuzzy Dead Zone via Output Feedback. <i>IEEE Transactions on Cybernetics</i> , 2017 , 47, 2400-2412	10.2	109
109	Adaptive output synchronization of heterogeneous network with an uncertain leader. <i>Automatica</i> , 2017 , 76, 183-192	5.7	108
108	Robust Estimation for Neural Networks With Randomly Occurring Distributed Delays and Markovian Jump Coupling. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2018 , 29, 845-855	10.3	98
107	Event-Triggered Control for Multiagent Systems With Sensor Faults and Input Saturation. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 51, 3855-3866	7.3	97
106	Distributed Sliding-Mode Tracking Control of Second-Order Nonlinear Multiagent Systems: An Event-Triggered Approach. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 3892-3902	10.2	92
105	. <i>IEEE Transactions on Fuzzy Systems</i> , 2017 , 25, 1616-1628	8.3	81
104	A New Design of Model Predictive Tracking Control for Networked Control System Under Random Packet Loss and Uncertainties. <i>IEEE Transactions on Industrial Electronics</i> , 2016 , 63, 6999-7007	8.9	80
103	Fuzzy-Model-Based Quantized Guaranteed Cost Control of Nonlinear Networked Systems. <i>IEEE Transactions on Fuzzy Systems</i> , 2015 , 23, 567-575	8.3	74
102	Finite-Time Consensus Tracking Neural Network FTC of Multi-Agent Systems. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , 32, 653-662	10.3	73
101	Finite-Time State Estimation for Coupled Markovian Neural Networks With Sensor Nonlinearities. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2017 , 28, 630-638	10.3	72
100	Reliable Control of Fuzzy Systems With Quantization and Switched Actuator Failures. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2017 , 47, 2198-2208	7.3	65
99	Human-in-the-loop consensus control for nonlinear multi-agent systems with actuator faults. <i>IEEE/CAA Journal of Automatica Sinica</i> , 2020 , 1-12	7	64
98	Synchronization of General Chaotic Neural Networks With Nonuniform Sampling and Packet Missing: A Switched System Approach. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2018 , 29, 523-533	10.3	59
97	Stability and stabilization of periodic piecewise linear systems: A matrix polynomial approach. <i>Automatica</i> , 2018 , 94, 1-8	5.7	58
96	Synchronization of Network Systems via Aperiodic Sampled-Data Control With Constant Delay and Application to Unmanned Ground Vehicles. <i>IEEE Transactions on Industrial Electronics</i> , 2020 , 67, 4980-4990	8.9	57
95	Sampled-Data Control of Network Systems in Industrial Manufacturing. <i>IEEE Transactions on Industrial Electronics</i> , 2018 , 65, 9016-9024	8.9	56
94	Observer-based adaptive consensus control for nonlinear multi-agent systems with time-delay. <i>Science China Information Sciences</i> , 2020 , 63, 1	3.4	55

93	Event-Based Control for Network Systems via Integral Quadratic Constraints. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2018 , 65, 1386-1394	3-9	55
92	Dissipativity-Based Resilient Filtering of Periodic Markovian Jump Neural Networks With Quantized Measurements. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2018 , 29, 1888-1899	10-3	53
91	Robust H ∞ Filtering for Markov jump systems with mode-dependent quantized output and partly unknown transition probabilities. <i>Signal Processing</i> , 2017 , 137, 328-338	4-4	52
90	Finite-Horizon H State Estimation for Periodic Neural Networks Over Fading Channels. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2020 , 31, 1450-1460	10-3	50
89	Nested adaptive super-twisting sliding mode control design for a vehicle steer-by-wire system. <i>Mechanical Systems and Signal Processing</i> , 2019 , 122, 658-672	7-8	49
88	State Estimation for Periodic Neural Networks With Uncertain Weight Matrices and Markovian Jump Channel States. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2018 , 48, 1841-1850	7-3	42
87	Stability of continuous-time positive switched linear systems: A weak common copositive Lyapunov functions approach. <i>Automatica</i> , 2018 , 97, 278-285	5-7	42
86	Adaptive Fixed-Time Control of Error-Constrained Pure-Feedback Interconnected Nonlinear Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 1-12	7-3	38
85	Optimal Filtered and Smoothed Estimators for Discrete-Time Linear Systems With Multiple Packet Dropouts Under Markovian Communication Constraints. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 4169-4181	10-2	38
84	Event-triggered H ∞ Filter design for Markovian jump systems with quantization. <i>Nonlinear Analysis: Hybrid Systems</i> , 2018 , 28, 23-41	4-5	37
83	Finite-Horizon l-l Synchronization for Time-Varying Markovian Jump Neural Networks Under Mixed-Type Attacks: Observer-Based Case. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2019 , 30, 1695-1704	10-3	35
82	Asynchronous Filtering of Nonlinear Markov Jump Systems With Randomly Occurred Quantization via TB Fuzzy Models. <i>IEEE Transactions on Fuzzy Systems</i> , 2017 , 1-1	8-3	33
81	Analysis and Design of Synchronization for Heterogeneous Network. <i>IEEE Transactions on Cybernetics</i> , 2018 , 48, 1253-1262	10-2	33
80	Disturbance-observer-based event-triggered control for multi-agent systems with input saturation. <i>Scientia Sinica Informationis</i> , 2019 , 49, 1502-1516	2-3	33
79	Stability and \mathcal{L}_2 Synthesis of a Class of Periodic Piecewise Time-Varying Systems. <i>IEEE Transactions on Automatic Control</i> , 2019 , 64, 3378-3384	5-9	31
78	Reliable Control Against Sensor Failures for Markov Jump Systems With Unideal Measurements. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2019 , 49, 308-316	7-3	31
77	Output Synchronization and \mathcal{L}_2 -Gain Analysis for Network Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2018 , 48, 2105-2114	7-3	30
76	Filtering for Fuzzy Systems With Multiplicative Sensor Noises and Multidensity Quantizer. <i>IEEE Transactions on Fuzzy Systems</i> , 2018 , 26, 1011-1022	8-3	30

75	Quasi-Synchronization of Time Delay Markovian Jump Neural Networks With Impulsive-Driven Transmission and Fading Channels. <i>IEEE Transactions on Cybernetics</i> , 2020 , 50, 4121-4131	10.2	30
74	. <i>IEEE Transactions on Industrial Informatics</i> , 2021 , 17, 7479-7488	11.9	30
73	Adaptive Attitude Control for Multi-MUAV Systems With Output Dead-Zone and Actuator Fault. <i>IEEE/CAA Journal of Automatica Sinica</i> , 2021 , 8, 1567-1575	7	29
72	. <i>IEEE Transactions on Automatic Control</i> , 2017 , 62, 4564-4579	5.9	28
71	On stability and convergence of optimal estimation for networked control systems with dual packet losses without acknowledgment. <i>Automatica</i> , 2018 , 90, 81-90	5.7	28
70	Distributed Cooperative Compound Tracking Control for a Platoon of Vehicles With Adaptive NN. <i>IEEE Transactions on Cybernetics</i> , 2021 , PP,	10.2	27
69	Performance Recovery of Dynamic Feedback-Linearization Methods for Multivariable Nonlinear Systems. <i>IEEE Transactions on Automatic Control</i> , 2020 , 65, 1365-1380	5.9	25
68	Optimal Estimation for Discrete-Time Linear System with Communication Constraints and Measurement Quantization. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 50, 1932-1942	7.3	24
67	Filtering of T _B Fuzzy Systems With Nonuniform Sampling. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2018 , 48, 2442-2450	7.3	23
66	Remote Estimator Design for Time-Delay Neural Networks Using Communication State Information. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2018 , 29, 5149-5158	10.3	22
65	Robust tracking control of an IPMC actuator using nonsingular terminal sliding mode. <i>Smart Materials and Structures</i> , 2017 , 26, 095042	3.4	20
64	Adaptive sliding mode controller design of Markov jump systems with time-varying actuator faults and partly unknown transition probabilities. <i>Nonlinear Analysis: Hybrid Systems</i> , 2018 , 28, 105-122	4.5	20
63	Sliding mode control for state-delayed Markov jump systems with partly unknown transition probabilities. <i>Nonlinear Dynamics</i> , 2018 , 91, 475-486	5	19
62	A Wide-Deep-Sequence Model-Based Quality Prediction Method in Industrial Process Analysis. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2020 , 31, 3721-3731	10.3	18
61	Distributed Event-Triggered Formation Control of USVs with Prescribed Performance. <i>Journal of Systems Science and Complexity</i> , ¹	1	16
60	Dissipativity-based asynchronous filtering for periodic Markov jump systems. <i>Information Sciences</i> , 2017 , 420, 505-516	7.7	15
59	Observer-Based Impulsive Synchronization for Neural Networks With Uncertain Exchanging Information. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2020 , 31, 3777-3787	10.3	15
58	Quasi-Synchronization for Periodic Neural Networks With Asynchronous Target and Constrained Information. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 51, 4379-4388	7.3	15

57	Nonfragile H_2 - H_∞ State estimation for discrete-time neural networks with jumping saturations. <i>Neurocomputing</i> , 2016 , 207, 15-21	5-4	14
56	Mathematical H_2 Performance Analysis and Applications of 2-D Hidden Bernoulli Jump System. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2019 , 49, 2097-2107	7-3	14
55	Approximation-Based Nussbaum Gain Adaptive Control of Nonlinear Systems With Periodic Disturbances. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 1-10	7-3	14
54	Nonfragile Finite-Time Synchronization for Coupled Neural Networks With Impulsive Approach. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2020 , 31, 4980-4989	10-3	13
53	Distributed event triggering control for six-rotor UAV systems with asymmetric time-varying output constraints. <i>Science China Information Sciences</i> , 2021 , 64, 1	3-4	13
52	Adaptive Attitude Control of a Quadrotor Using Fast Non-singular Terminal Sliding Mode. <i>IEEE Transactions on Industrial Electronics</i> , 2021 , 1-1	8-9	13
51	Adaptive Multigradient Recursive Reinforcement Learning Event-Triggered Tracking Control for Multiagent Systems. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , PP,	10-3	13
50	Reset Moving Horizon Estimation for Quantized Discrete Time Systems. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 4199-4205	5-9	13
49	Distributed H_∞ State Estimator Design for Time-Delay Periodic Systems Over Scheduling Sensor Networks. <i>IEEE Transactions on Cybernetics</i> , 2021 , 51, 462-472	10-2	12
48	Synchronization Control for Unreliable Network Systems in Intelligent Robots. <i>IEEE/ASME Transactions on Mechatronics</i> , 2019 , 24, 2641-2651	5-5	11
47	H_∞ Control of periodic piecewise polynomial time-varying systems with polynomial Lyapunov function. <i>Journal of the Franklin Institute</i> , 2019 , 356, 6968-6988	4	11
46	Dissipative non-fragile state estimation for Markovian complex networks with coupling transmission delays. <i>Neurocomputing</i> , 2018 , 275, 1576-1584	5-4	11
45	Synchronization Control for Network Systems With Communication Constraints. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2019 , 30, 3150-3160	10-3	10
44	Adaptive Microtracking Control for an Underwater IPMC Actuator Using New Hyperplane-Based Sliding Mode. <i>IEEE/ASME Transactions on Mechatronics</i> , 2019 , 24, 2108-2117	5-5	9
43	State Estimation for Networked Systems With Markov Driven Transmission and Buffer Constraint. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 1-8	7-3	9
42	Adaptive sliding mode control of switched systems with different input matrix. <i>International Journal of Control, Automation and Systems</i> , 2017 , 15, 2500-2506	2-9	9
41	Multigradient recursive reinforcement learning NN control for affine nonlinear systems with unmodeled dynamics. <i>International Journal of Robust and Nonlinear Control</i> , 2020 , 30, 1643-1663	3-6	9
40	Event-Triggered Guaranteed Cost Leader-Following Consensus Control of Second-Order Nonlinear Multiagent Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 1-10	7-3	9

39	Security Analysis for Dynamic State Estimation of Power Systems With Measurement Delays. <i>IEEE Transactions on Cybernetics</i> , 2021 , PP,	10.2	9
38	Prescribed Performance Consensus Fuzzy Control of Multi-Agent Systems with Nonaffine Nonlinear Faults. <i>IEEE Transactions on Fuzzy Systems</i> , 2020 , 1-1	8.3	8
37	Event-Triggered Output-Feedback Control for Large-Scale Systems With Unknown Hysteresis. <i>IEEE Transactions on Cybernetics</i> , 2021 , 51, 5236-5247	10.2	8
36	Event-triggered guaranteed cost fault-tolerant optimal tracking control for uncertain nonlinear system via adaptive dynamic programming. <i>International Journal of Robust and Nonlinear Control</i> , 2021 , 31, 2572-2592	3.6	8
35	Distributed Finite-Time Containment Control for Nonlinear Multiagent Systems With Mismatched Disturbances. <i>IEEE Transactions on Cybernetics</i> , 2021 , PP,	10.2	8
34	Stability analysis problems of periodic piecewise polynomial systems. <i>Journal of the Franklin Institute</i> , 2019 , 356, 9804-9823	4	7
33	Saturated Threshold Event-Triggered Control for Multiagent Systems Under Sensor Attacks and Its Application to UAVs. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2021 , 1-12	3.9	7
32	Delay Consensus Margin of First-Order Multiagent Systems With Undirected Graphs and PD Protocols. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 4192-4198	5.9	6
31	Adaptive neural control for multiagent systems with asymmetric time-varying state constraints and input saturation. <i>International Journal of Robust and Nonlinear Control</i> , 2020 , 30, 4764-4778	3.6	5
30	Distributed Reinforcement Learning Containment Control for Multiple Nonholonomic Mobile Robots. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2021 , 1-12	3.9	5
29	Robust Distributed H _∞ State Estimation for Stochastic Periodic Systems Over Constraint Sensor Networks. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 50, 4396-4407	7.3	5
28	Hybrid Hierarchical Backtracking Search Optimization Algorithm and Its Application. <i>Arabian Journal for Science and Engineering</i> , 2018 , 43, 993-1014	2.5	5
27	Distributed filtering for a class of periodic non-linear systems with jumping uncertainties and unreliable channels. <i>IET Control Theory and Applications</i> , 2017 , 11, 846-856	2.5	4
26	Output Regulation of Linear Singular Multi-Agent Systems. <i>Circuits, Systems, and Signal Processing</i> , 2017 , 36, 931-946	2.2	4
25	Partial-Nodes-Based State Estimation for Complex Networks With Constrained Bit Rate. <i>IEEE Transactions on Network Science and Engineering</i> , 2021 , 8, 1887-1899	4.9	4
24	Output Regulation of Invertible Nonlinear Systems via Robust Dynamic Feedback-Linearization. <i>IEEE Transactions on Automatic Control</i> , 2021 , 1-1	5.9	4
23	Dynamic Event-Triggered State Estimation for Markov Jump Neural Networks With Partially Unknown Probabilities. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , PP,	10.3	4
22	Quasisynchronization for Neural Networks With Partial Constrained State Information via Intermittent Control Approach. <i>IEEE Transactions on Cybernetics</i> , 2021 , PP,	10.2	4

21	Adaptive Neural Sliding Mode Control of Markov Jump Systems Subject to Malicious Attacks. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2020 , 1-12	7.3	3
20	Implementation of the load frequency control by two approaches: variable gain super-twisting algorithm and super-twisting-like algorithm. <i>Nonlinear Dynamics</i> , 2018 , 93, 1073-1086	5	3
19	Observer-based sliding mode control of Markov jump systems with random sensor delays and partly unknown transition rates. <i>International Journal of Systems Science</i> , 2017 , 48, 2985-2996	2.3	3
18	Robust Lidar-Based Localization Scheme for Unmanned Ground Vehicle via Multisensor Fusion. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2021 , 32, 5633-5643	10.3	3
17	. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , 2021 , 68, 2538-2542	3.5	3
16	Barrier Function-Based Adaptive Control for Uncertain Strict-Feedback Systems Within Predefined Neural Network Approximation Sets. <i>IEEE Transactions on Neural Networks and Learning Systems</i> , 2020 , 31, 2942-2954	10.3	3
15	Distributed Kalman Filter for Large-Scale Power Systems With State Inequality Constraints. <i>IEEE Transactions on Industrial Electronics</i> , 2021 , 68, 6238-6247	8.9	3
14	Event-Triggered and Asynchronous Reduced-Order Filtering Codesign for Fuzzy Markov Jump Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , 2021 , 1-10	7.3	3
13	Quantized fuzzy passification for nonlinear systems with Markov-based transmission delays. <i>Journal of the Franklin Institute</i> , 2017 , 354, 1875-1891	4	2
12	Anti-Synchronization of Discrete-Time Fuzzy Memristive Neural Networks via Impulse Sampled-Data Communication.. <i>IEEE Transactions on Cybernetics</i> , 2022 , PP,	10.2	2
11	A Novel Fixed-Time Protocol for First-Order Consensus Tracking with Disturbance Rejection. <i>IEEE Transactions on Automatic Control</i> , 2021 , 1-1	5.9	2
10	Synchronization for Markovian coupled neural networks with partial mode observation: The finite-time case. <i>Journal of the Franklin Institute</i> , 2020 , 357, 12767-12786	4	2
9	2019 ,		2
8	Distributed H _∞ filtering of nonlinear systems with random topology by an event-triggered protocol. <i>Science China Information Sciences</i> , 2021 , 64, 1	3.4	2
7	Containment Control for Networked Fractional-Order Systems With Sampled Position Data. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , 2021 , 68, 3881-3889	3.9	2
6	State estimation for neural networks with jumping interval weight matrices and transmission delays. <i>Neurocomputing</i> , 2018 , 275, 909-915	5.4	1
5	Variable-Parameter-Dependent Saturated Robust Control for Vehicle Lateral Stability. <i>IEEE Transactions on Control Systems Technology</i> , 2021 , 1-12	4.8	1
4	Consensus of Continuous-Time Multiagent Systems via Delayed Output Feedback: Delay Versus Connectivity. <i>IEEE Transactions on Automatic Control</i> , 2021 , 66, 1329-1336	5.9	1

3	Event-Triggered Adaptive Neural Control for Multiagent Systems with Deferred State Constraints. <i>Journal of Systems Science and Complexity</i> ,1	1	1
2	On the Design of Distributed Observers for Nonlinear Systems. <i>IEEE Transactions on Automatic Control</i> , 2021 , 1-1	5.9	1
1	Delay Effect on First-Order Consensus over Directed Graphs: Optimizing PID Protocols for Maximal Robustness. <i>SIAM Journal on Control and Optimization</i> , 2022 , 60, 233-258	1.9	0