## Waweru Njeri

## List of Publications by Year in descending order

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2258059 1872680 13 40 3 6 citations h-index g-index papers 13 13 13 28 docs citations times ranked citing authors all docs

#	Article	IF	Citations
1	24-Gaze-Point Calibration Method for Improving the Precision of AC-EOG Gaze Estimation. Sensors, 2019, 19, 3650.	3.8	9
2	Gain Tuning for High-Speed Vibration Control of a Multilink Flexible Manipulator Using Artificial Neural Network. Journal of Vibration and Acoustics, Transactions of the ASME, 2019, 141, .	1.6	9
3	Enhanced vibration control of a multilink flexible manipulator using filtered inverse controller. ROBOMECH Journal, 2018, 5, .	1.6	6
4	Robot control systems using bio-potential signals. AIP Conference Proceedings, 2020, , .	0.4	5
5	Linear-Quadratic Regulator for Control of Multi-Wall Carbon Nanotube/Polydimethylsiloxane Based Conical Dielectric Elastomer Actuators. Actuators, 2020, 9, 18.	2.3	3
6	Two-degree-of-freedom control of a multilink flexible manipulator using filtered inverse feedforward controller and strain feedback controller. , 2018, , .		2
7	Development of neck surface electromyography gaming control interface for application in tetraplegic patients' entertainment. AIP Conference Proceedings, 2020, , .	0.4	2
8	Two-Degree-of-Freedom Control of Flexible Manipulator Using Adaptive Notch Filter and Strain Feedback. , 2019, , .		1
9	Vibration Control of Flexible Manipulator Using Filtered Inverse Controller. , 2017, , .		1
10	Strain feedback gain tuning using neural network for the vibration control in a multilink flexible manipulator. The Proceedings of JSME Annual Conference on Robotics and Mechatronics (Robomec), 2018, 2018, 1P1-I08.	0.0	1
11	Two Degree-of-Freedom Vibration Control of a 3D, 2 Link Flexible Manipulator. Advances in Science, Technology and Engineering Systems, 2018, 3, 412-424.	0.5	1
12	Identification and Discrimination of the Limb Motions using Brain Waves from Motor Imagery. , 2017, , .		0
13	Internal Model Control of a Multilink Flexible Manipulator. , 2017, , .		O