Indrani Kar

List of Publications by Year in descending order

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1307594 1281871 21 284 7 11 citations g-index h-index papers 21 21 21 308 all docs docs citations times ranked citing authors

| # | Article | IF | CITATIONS |
|----|---|--------------|-----------|
| 1 | A priority-driven optimal guidance approach to moving target tracking for safe navigation in a narrow space. International Journal of Systems Science, 2022, 53, 138-153. | 5.5 | 1 |
| 2 | Validating observer based on-line slip estimation for improved navigation by a mobile robot. International Journal of Intelligent Robotics and Applications, 2022, 6, 564-575. | 2.8 | 4 |
| 3 | Nonlinear disturbance observer based geometric control of quadrotors. Asian Journal of Control, 2021, 23, 1936-1951. | 3.0 | 10 |
| 4 | Adaptive geometric control of quadrotors with dynamic offset between center of gravity and geometric center. Asian Journal of Control, 2021, 23, 1923-1935. | 3.0 | 7 |
| 5 | Control of a quadrotor with network induced time delay. ISA Transactions, 2021, 111, 132-143. | 5 . 7 | 12 |
| 6 | Almost global attitude consensus of multi-agent rigid bodies on \$\$mathrm{TSO}(3)^N\$\$ in the presence of disturbances and directed topology. Nonlinear Dynamics, 2021, 104, 3617-3631. | 5.2 | 4 |
| 7 | Finite Time Disturbance Observer Based Geometric Control of Quadrotors. IFAC-PapersOnLine, 2020, 53, 295-300. | 0.9 | 9 |
| 8 | Adaptive Compensation of Actuator Failures using Multiple Models. IFAC-PapersOnLine, 2017, 50, 10350-10356. | 0.9 | 5 |
| 9 | Control of twin-rotor MIMO system using multiple models with second level adaptation. IFAC-PapersOnLine, 2016, 49, 676-681. | 0.9 | 8 |
| 10 | Multiple models and second level adaptation for a class of nonlinear systems with nonlinear parameterization. , 2014, , . | | 8 |
| 11 | A Multi Charging Station for Electric Vehicles and Its Utilization for Load Management and the Grid Support. IEEE Transactions on Smart Grid, 2013, 4, 1026-1037. | 9.0 | 123 |
| 12 | T-S fuzzy model based controller and observer design for a Twin Rotor MIMO System. , 2013, , . | | 13 |
| 13 | Sliding mode controller design for Twin Rotor MIMO system with a nonlinear state observer. , 2013, , . | | 28 |
| 14 | Coordination of Electric Vehicles in charging stations connected at different nodes of a distribution substation., 2012,,. | | 2 |
| 15 | A model of Electric Vehicle charging station compatibles with Vehicle to Grid scenario. , 2012, , . | | 5 |
| 16 | Direct Adaptive Neural Control Scheme for Discrete Time Affine Nonlinear Systems. , 2008, , . | | 1 |
| 17 | Visual motor control of a 6 DOF robot manipulator using a fuzzy learning paradigm., 2008,,. | | 2 |
| 18 | Neural network based direct adaptive control for a class of affine nonlinear systems., 2006,,. | | 3 |

| # | Article | IF | CITATIONS |
|----|--|-----|-----------|
| 19 | A Recurrent Quantum Neural Network Model to Describe Eye Tracking of Moving Targets. Foundations of Physics Letters, 2005, 18, 357-370. | 0.6 | 32 |
| 20 | On Identification and Stabilization of nonlinear plants using Fuzzy Neural Network. , 0, , . | | 1 |
| 21 | Quantum Stochastic Filtering., 0,,. | | 6 |