

Hugo Rodrigue

List of Publications by Year in descending order

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51
papers

1,881
citations

257357

24
h-index

265120

42
g-index

51
all docs

51
docs citations

51
times ranked

1591
citing authors

#	ARTICLE	IF	CITATIONS
1	An Overview of Shape Memory Alloy-Coupled Actuators and Robots. <i>Soft Robotics</i> , 2017, 4, 3-15.	4.6	189
2	Locomotion of inchworm-inspired robot made of smart soft composite (SSC). <i>Bioinspiration and Biomimetics</i> , 2014, 9, 046006.	1.5	181
3	Origami-Based Vacuum Pneumatic Artificial Muscles with Large Contraction Ratios. <i>Soft Robotics</i> , 2019, 6, 109-117.	4.6	117
4	Long Shape Memory Alloy Tendon-based Soft Robotic Actuators and Implementation as a Soft Gripper. <i>Scientific Reports</i> , 2019, 9, 11251.	1.6	111
5	Curved shape memory alloy-based soft actuators and application to soft gripper. <i>Composite Structures</i> , 2017, 176, 398-406.	3.1	109
6	35% shape memory alloy actuator with bending-twisting mode. <i>Scientific Reports</i> , 2016, 6, 21118.	1.6	92
7	Soft composite hinge actuator and application to compliant robotic gripper. <i>Composites Part B: Engineering</i> , 2016, 98, 397-405.	5.9	84
8	Turtle mimetic soft robot with two swimming gaits. <i>Bioinspiration and Biomimetics</i> , 2016, 11, 036010.	1.5	71
9	Kirigami/Origami-Based Soft Deployable Reflector for Optical Beam Steering. <i>Advanced Functional Materials</i> , 2017, 27, 1604214.	7.8	71
10	Deployable Soft Composite Structures. <i>Scientific Reports</i> , 2016, 6, 20869.	1.6	63
11	SMA-based smart soft composite structure capable of multiple modes of actuation. <i>Composites Part B: Engineering</i> , 2015, 82, 152-158.	5.9	61
12	Shape memory alloy/glass fiber woven composite for soft morphing winglets of unmanned aerial vehicles. <i>Composite Structures</i> , 2016, 140, 202-212.	3.1	61
13	Fabrication of wrist-like SMA-based actuator by double smart soft composite casting. <i>Smart Materials and Structures</i> , 2015, 24, 125003.	1.8	59
14	A smart soft actuator using a single shape memory alloy for twisting actuation. <i>Smart Materials and Structures</i> , 2015, 24, 125033.	1.8	51
15	Modular assembly of soft deployable structures and robots. <i>Materials Horizons</i> , 2017, 4, 367-376.	6.4	48
16	Cross-shaped twisting structure using SMA-based smart soft composite. <i>International Journal of Precision Engineering and Manufacturing - Green Technology</i> , 2014, 1, 153-156.	2.7	46
17	Effect of twist morphing wing segment on aerodynamic performance of UAV. <i>Journal of Mechanical Science and Technology</i> , 2016, 30, 229-236.	0.7	41
18	Double Helix Twisted and Coiled Soft Actuator from Spandex and Nylon. <i>Advanced Engineering Materials</i> , 2018, 20, 1800536.	1.6	37

#	ARTICLE	IF	CITATIONS
19	A shape memory alloy-based soft morphing actuator capable of pure twisting motion. <i>Journal of Intelligent Material Systems and Structures</i> , 2015, 26, 1071-1078.	1.4	36
20	Design of Paired Pouch Motors for Robotic Applications. <i>Advanced Materials Technologies</i> , 2019, 4, 1800414.	3.0	33
21	Jumping Tensegrity Robot Based on Torsionally Prestrained SMA Springs. <i>ACS Applied Materials & Interfaces</i> , 2019, 11, 40793-40799.	4.0	31
22	Expanding Pouch Motor Patterns for Programmable Soft Bending Actuation: Enabling Soft Robotic System Adaptations. <i>IEEE Robotics and Automation Magazine</i> , 2020, 27, 65-74.	2.2	28
23	Comparison of mold designs for SMA-based twisting soft actuator. <i>Sensors and Actuators A: Physical</i> , 2016, 237, 96-106.	2.0	26
24	3D soft lithography: A fabrication process for thermocurable polymers. <i>Journal of Materials Processing Technology</i> , 2015, 217, 302-309.	3.1	25
25	Proprioceptive Soft Pneumatic Gripper for Extreme Environments Using Hybrid Optical Fibers. <i>IEEE Robotics and Automation Letters</i> , 2021, 6, 8694-8701.	3.3	25
26	A Novel Soft Bending Actuator Using Combined Positive and Negative Pressures. <i>Frontiers in Bioengineering and Biotechnology</i> , 2020, 8, 472.	2.0	22
27	Shape-Adaptive Universal Soft Parallel Gripper for Delicate Grasping Using a Stiffness-Variable Composite Structure. <i>IEEE Transactions on Industrial Electronics</i> , 2021, 68, 12441-12451.	5.2	22
28	Application of SMA spring tendons for improved grasping performance. <i>Smart Materials and Structures</i> , 2019, 28, 035006.	1.8	17
29	Smart Phone Robot Made of Smart Soft Composite (SSC). <i>Composites Research</i> , 2015, 28, 52-57.	0.1	16
30	Artificial musculoskeletal actuation module driven by twisted and coiled soft actuators. <i>Smart Materials and Structures</i> , 2019, 28, 125010.	1.8	14
31	Efficiency of Origami-Based Vacuum Pneumatic Artificial Muscle for Off-Grid Operation. <i>International Journal of Precision Engineering and Manufacturing - Green Technology</i> , 2019, 6, 789-797.	2.7	12
32	Armor-Based Stable Force Pneumatic Artificial Muscles for Steady Actuation Properties. <i>Soft Robotics</i> , 2022, 9, 413-424.	4.6	12
33	Design and development of bio-mimetic soft robotic hand with shape memory alloy. , 2015, , .		10
34	Pleated Film-Based Soft Twisting Actuator. <i>International Journal of Precision Engineering and Manufacturing</i> , 2019, 20, 1149-1158.	1.1	9
35	Film-based anisotropic balloon inflatable bending actuator. <i>Journal of Mechanical Science and Technology</i> , 2019, 33, 4469-4476.	0.7	8
36	Sliding Filament Joint Mechanism: Biomimetic Artificial Joint Mechanism for Artificial Skeletal Muscles. <i>Journal of Mechanisms and Robotics</i> , 2019, 11, .	1.5	6

#	ARTICLE	IF	CITATIONS
37	A Positive and Negative Pressure Soft Linear Brake for Wearable Applications. IEEE Transactions on Industrial Electronics, 2023, 70, 688-698.	5.2	6
38	Toward the Development of Large-Scale Inflatable Robotic Arms Using Hot Air Welding. Soft Robotics, 2023, 10, 88-96.	4.6	6
39	Biomimetic robotic joint mechanism driven by soft linear actuators. , 2017, , .		5
40	Inflatable L-shaped prisms as soft actuators for soft exogloves. Engineering Research Express, 2019, 1, 025009.	0.8	5
41	Hybrid Robotic Manipulator Using Sensorized Articulated Segment Joints With Soft Inflatable Rubber Bellows. IEEE Transactions on Industrial Electronics, 2022, 69, 10259-10269.	5.2	4
42	High-Precision Roller Supported by Active Magnetic Bearings. Applied Sciences (Switzerland), 2019, 9, 4389.	1.3	3
43	Design and Control of Lightweight Bionic Arm Driven by Soft Twisted and Coiled Artificial Muscles. Soft Robotics, 2023, 10, 17-29.	4.6	2
44	Simultaneous Positive and Negative Pressure Control Using Disturbance Observer Compensating Coupled Disturbance Dynamics. IEEE Robotics and Automation Letters, 2022, 7, 5763-5770.	3.3	2
45	Preface for the Soft and Green Manufacturing and Applications. International Journal of Precision Engineering and Manufacturing - Green Technology, 2021, 8, 743-744.	2.7	1
46	Manufacturing 2DOF Inflatable Joint Actuator by Pneumatic Control. The Journal of Korea Robotics Society, 2018, 13, 92-96.	0.2	1
47	Simple and Scalable Soft Actuation Through Coupled Inflatable Tubes. IEEE Access, 2022, , 1-1.	2.6	1
48	Design of a Novel Sensing Method for a Pneumatic Artificial Muscle Actuator-Driven 2-Degrees of Freedom Parallel Joint. Soft Robotics, 0, , .	4.6	1
49	Reconfigurable constriction-based soft actuation for decorative morphing flowers. Journal of Mechanical Science and Technology, 2021, 35, 3705-3712.	0.7	0
50	Print-and-Spray Electromechanical Metamaterials. Soft Robotics, 2021, , .	4.6	0
51	Towards the Development of Variable Elasticity Devices. IEEE Robotics and Automation Letters, 2022, 7, 2094-2101.	3.3	0