

# Yonghwan Oh

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2926254/publications.pdf>

Version: 2024-02-01

2  
papers

2  
citations

3311381

1  
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3475538

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times ranked

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citing authors

#	ARTICLE	IF	CITATIONS
1	Robust walking stabilization strategy of humanoid robots on uneven terrain via QP-based impedance/admittance control. <i>Robotics and Autonomous Systems</i> , 2022, 154, 104148.	5.1	2
2	Computational Cost Reduction Method for HQP-based Hierarchical Controller for Articulated Robot. <i>The Journal of Korea Robotics Society</i> , 2022, 17, 16-24.	0.4	0